## Jinglai Shen

## List of Publications by Year in Descending Order

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

50 661 14 g-index

60 791 3.2 4.16 ext. papers ext. citations avg, IF L-index

#	Paper	IF	Citations
50	Nonconvex, Fully Distributed Optimization Based CAV Platooning Control Under Nonlinear Vehicle Dynamics. <i>IEEE Transactions on Intelligent Transportation Systems</i> , <b>2022</b> , 1-16	6.1	O
49	Hybrid MPC System for Platoon based Cooperative Lane change Control Using Machine Learning Aided Distributed Optimization. <i>Transportation Research Part B: Methodological</i> , <b>2021</b> ,	7.2	2
48	. IEEE Transactions on Signal and Information Processing Over Networks, <b>2021</b> , 7, 375-391	2.8	
47	Solution uniqueness of convex piecewise affine functions based optimization with applications to constrained II minimization. <i>ESAIM - Control, Optimisation and Calculus of Variations</i> , <b>2019</b> , 25, 56	1	2
46	Stabilization of Switched Linear Systems Using Continuous Control Input against Known Adversarial Switching <b>2018</b> ,		1
45	Least Sparsity of \$p\$-Norm Based Optimization Problems with \$p>1\$. <i>SIAM Journal on Optimization</i> , <b>2018</b> , 28, 2721-2751	2	8
44	Resilient Stabilization of Switched Linear Control Systems Against Adversarial Switching. <i>IEEE Transactions on Automatic Control</i> , <b>2017</b> , 62, 3820-3834	5.9	11
43	. IEEE Transactions on Automatic Control, 2017, 62, 3482-3487	5.9	0
42	Constrained optimization and distributed computation based car following control of a connected and autonomous vehicle platoon. <i>Transportation Research Part B: Methodological</i> , <b>2016</b> , 94, 314-334	7.2	100
41	Generalized Input-to-State \$ell_2\$-Gains of Discrete-Time Switched Linear Control Systems. <i>SIAM Journal on Control and Optimization</i> , <b>2016</b> , 54, 1475-1503	1.9	3
40	Shape restricted smoothing splines via constrained optimal control and nonsmooth Newton methods. <i>Automatica</i> , <b>2015</b> , 53, 216-224	5.7	6
39	Quadratic stability and stabilization of bimodal piecewise linear systems. Automatica, 2014, 50, 1444-14	15507	7
38	Semistability of switched linear systems with application to PageRank algorithms. <i>European Journal of Control</i> , <b>2014</b> , 20, 132-140	2.5	4
37	Robust Non-Zenoness of Piecewise Affine Systems with Applications to Linear Complementarity Systems. <i>SIAM Journal on Optimization</i> , <b>2014</b> , 24, 2023-2056	2	6
36	Uniform Convergence and Rate Adaptive Estimation of Convex Functions via Constrained Optimization. <i>SIAM Journal on Control and Optimization</i> , <b>2013</b> , 51, 2753-2787	1.9	5
35	Addendum to Cenerating Functions of Switched Linear Systems: Analysis, Computation, and Stability Applications [May 11 1059-1074]. IEEE Transactions on Automatic Control, 2013, 58, 1887-1887	5.9	
34	Stability of Discrete-Time Switched Homogeneous Systems on Cones and Conewise Homogeneous Inclusions. <i>SIAM Journal on Control and Optimization</i> , <b>2012</b> , 50, 2216-2253	1.9	16

## (2006-2012)

33	Positive Invariance of Constrained Affine Dynamics and Its Applications to Hybrid Systems and Safety Verification. <i>IEEE Transactions on Automatic Control</i> , <b>2012</b> , 57, 3-18	5.9	6
32	Generating Functions of Switched Linear Systems: Analysis, Computation, and Stability Applications. <i>IEEE Transactions on Automatic Control</i> , <b>2011</b> , 56, 1059-1074	5.9	25
31	Estimation of Monotone Functions via P-Splines: A Constrained Dynamical Optimization Approach. <i>SIAM Journal on Control and Optimization</i> , <b>2011</b> , 49, 646-671	1.9	10
30	On the asymptotics of penalized spline smoothing. <i>Electronic Journal of Statistics</i> , <b>2011</b> , 5,	1.2	23
29	Integral tau methods for stiff stochastic chemical systems. Journal of Chemical Physics, 2011, 134, 0441	1 <b>29</b> .9	5
28	Semistability of switched linear systems with applications to distributed sensor networks: A generating function approach <b>2011</b> ,		5
27	A study of the generalized input-to-state L2-gain of discrete-time switched linear systems <b>2011</b> ,		2
26	A constrained optimal control approach to smoothing splines <b>2011</b> ,		2
25	A class of grouped Brunk estimators and penalized spline estimators for monotone regression. <i>Biometrika</i> , <b>2010</b> , 97, 585-601	2	8
24	Stability of switched linear systems on cones: A generating function approach <b>2010</b> ,		4
23	Switching and stability properties of conewise linear systems. <i>ESAIM - Control, Optimisation and Calculus of Variations</i> , <b>2010</b> , 16, 764-793	1	14
22	Observability analysis of conewise linear systems via directional derivative and positive invariance techniques. <i>Automatica</i> , <b>2010</b> , 46, 843-851	5.7	8
21	Controllability and motion planning of a multibody Chaplygin's sphere and Chaplygin's top. <i>International Journal of Robust and Nonlinear Control</i> , <b>2008</b> , 18, 905-945	3.6	37
20	Semicopositive linear complementarity systems. <i>International Journal of Robust and Nonlinear Control</i> , <b>2007</b> , 17, 1367-1386	3.6	19
19	Linear Complementarity Systems with Singleton Properties: Non-Zenoness. <i>Proceedings of the American Control Conference</i> , <b>2007</b> ,	1.2	11
18	Lyapunov Stability of Complementarity and Extended Systems. <i>SIAM Journal on Optimization</i> , <b>2007</b> , 17, 1056-1101	2	50
17	. IEEE Transactions on Automatic Control, <b>2007</b> , 52, 242-255	5.9	41
16	Conewise Linear Systems: Non-Zenoness and Observability. <i>SIAM Journal on Control and Optimization</i> , <b>2006</b> , 45, 1769-1800	1.9	51

Linear Complementarity Systems: Zeno States. SIAM Journal on Control and Optimization, 2005, 44, 1040<sub>1</sub>1966 64

	Stability and Stabilization of Relative Equilibria of Dumbbell Bodies in Central Gravity. <i>Journal of</i>		
14	Guidance, Control, and Dynamics, <b>2005</b> , 28, 833-842	2.1	23
13	Local equilibrium controllability of multibody systems controlled via shape change. <i>IEEE Transactions on Automatic Control</i> , <b>2004</b> , 49, 506-520	5.9	13
12	Dynamics and control of a 3D pendulum <b>2004</b> ,		8
11	Mathematical Models for the Triaxial Attitude Control Testbed. <i>Mathematical and Computer Modelling of Dynamical Systems</i> , <b>2003</b> , 9, 165-192	1	15
10	Shape change actuation for precision attitude control. <i>IEEE Control Systems</i> , <b>2003</b> , 23, 44-56	2.9	7
9	Translational and Rotational Maneuvers of an Underactuated Space Robot using Prismatic Actuators. <i>International Journal of Robotics Research</i> , <b>2002</b> , 21, 607-618	5.7	14
8	Attitude control of a tilted air spindle testbed using proof mass actuators 2002,		3
7	2001,		3
7	2001,  Controllability and motion planning of multibody systems with nonholonomic constraints		3
6			1
6	Controllability and motion planning of multibody systems with nonholonomic constraints  Globally convergent adaptive tracking of spacecraft angular velocity with inertia identification and		1
5	Controllability and motion planning of multibody systems with nonholonomic constraints  Globally convergent adaptive tracking of spacecraft angular velocity with inertia identification and		1 4