## Yuan Fan

## List of Publications by Year in Descending Order

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

47 papers 1,147 13 33 g-index

88 1,576 3.6 4.81 ext. papers ext. citations avg, IF L-index

#	Paper	IF	Citations
47	New convergence analysis of coverage control on a circle subject to unknown but bounded measurement errors. <i>Automatica</i> , <b>2022</b> , 110216	5.7	
46	Dynamic Event-triggered Approximate Optimal Control Strategy for Nonlinear Systems. <i>International Journal of Control, Automation and Systems</i> , <b>2022</b> , 20, 1418-1427	2.9	0
45	Distributed solving Sylvester equations with fractional order dynamics. <i>Control Theory and Technology</i> , <b>2021</b> , 19, 249-259	1	1
44	Finite-Time Coverage Control for Multiagent Systems With Unidirectional Motion on a Closed Curve. <i>IEEE Transactions on Cybernetics</i> , <b>2021</b> , 51, 3071-3078	10.2	1
43	Dynamic Control Approach for Network Systems under Event-triggered Communication with Dual Triggers. <i>International Journal of Control, Automation and Systems</i> , <b>2021</b> , 19, 3666	2.9	O
42	Coverage control for heterogeneous mobile sensor networks with bounded position measurement errors. <i>Automatica</i> , <b>2020</b> , 120, 109118	5.7	5
41	Sampling-based Event-triggered and Self-triggered Control for Linear Systems. <i>International Journal of Control, Automation and Systems</i> , <b>2020</b> , 18, 672-681	2.9	4
40	Event-triggered Coordination Control for Multi-agent Systems with Connectivity Preservation. <i>International Journal of Control, Automation and Systems</i> , <b>2020</b> , 18, 966-979	2.9	7
39	Coverage control for mobile sensor networks with time-varying communication delays on a closed curve. <i>Journal of the Franklin Institute</i> , <b>2020</b> , 357, 12109-12124	4	5
38	Observer-Based Event-Triggered Optimal Control for Linear Systems <b>2019</b> ,		1
37	Optimized Event-Triggered and Self-Triggered Control for Linear Systems <b>2019</b> ,		1
36	Optimized Control for Exoskeleton for Lower Limb Rehabilitation with Uncertainty 2019,		1
35	Event-Triggered and Self-Triggered Control for Linear System Based on New Event Condition 2019,		2
34	Coverage control for mobile sensor networks with limited communication ranges on a circle. <i>Automatica</i> , <b>2018</b> , 92, 155-161	5.7	21
33	Authors Peply to comments on Distributed event-triggered control of multi-agent systems with combinational measurements [Automatica, 2018, 92, 266]	5.7	
32	Centralized dynamic event-triggered control for multi-agent systems 2018,		1
31	Quantized feedback control based on event-triggered observer 2018,		1

30	Consensus of multi-agent systems by distributed self-triggered control 2018,	1
29	Observer-based Output-feedback Control for Uncertain Linear Systems with Event-triggered 2018,	1
28	Multi-Agent Tracking Control with Dynamic Leader Based on Event-Triggered Control 2018,	2
27	Sampling-based self-triggered coordination control for multi-agent systems with application to distributed generators. <i>International Journal of Systems Science</i> , <b>2018</b> , 49, 3048-3062	13
26	Distributed Reactive Power Sharing Control for Microgrids With Event-Triggered Communication. <i>IEEE Transactions on Control Systems Technology</i> , <b>2017</b> , 25, 118-128	111
25	Sampling-based event-triggered control for distributed generators <b>2017</b> ,	2
24	Distributed event-triggered control with dynamic triggering mechanisms for multi-agent systems <b>2017</b> ,	3
23	Multi-agent rendezvous control based on event-triggered mechanism 2017,	1
22	Dynamical Event-Triggered Consensus Control for Second-Order Multi-Agent Systems 2017,	2
21	Subspace-based continuous-time identification of fractional order systems from non-uniformly sampled data. <i>International Journal of Systems Science</i> , <b>2016</b> , 47, 122-134	22
20	Graph-balancing algorithms for average consensus over directed networks. <i>International Journal of Systems Science</i> , <b>2016</b> , 47, 135-148	3
19	Hybrid triggering control for average consensus of multi-agent systems 2016,	1
18	Sampling-based event-triggered consensus for multi-agent systems. <i>Neurocomputing</i> , <b>2016</b> , 191, 141-14 <del>7</del> .4	45
17	Average consensus of multi-agent systems with self-triggered controllers. <i>Neurocomputing</i> , <b>2016</b> , 177, 33-39	17
16	Control of Networked Systems with Engineering Applications. <i>Mathematical Problems in Engineering</i> , <b>2016</b> , 2016, 1-2	
15	Self-Triggered Consensus for Multi-Agent Systems With Zeno-Free Triggers. <i>IEEE Transactions on Automatic Control</i> , <b>2015</b> , 60, 2779-2784	190
14	Centralized event-triggered control of multi-agent systems with dynamic triggering mechanisms <b>2015</b> ,	7
13	Connectivity-preserving rendezvous of multi-agent systems with event-triggered controllers 2015,	2

12	Suboptimal Event-Triggered Consensus of Multiagent Systems. <i>Abstract and Applied Analysis</i> , <b>2014</b> , 2014, 1-8	0.7	1
11	On event-triggered algorithm design for distributed coordination of multi-agent systems <b>2014</b> ,		1
10	Distributed event-triggered control of multi-agent systems with combinational measurements. <i>Automatica</i> , <b>2013</b> , 49, 671-675	5.7	501
9	Persistent awareness coverage with maximum coverage frequency for mobile sensor networks <b>2013</b> ,		3
8	Event-triggered control of multi-agent systems with suboptimal triggering 2013,		1
7	Virtual neighbor based connectivity preserving of multi-agent systems with bounded control inputs in the presence of unreliable communication links. <i>Automatica</i> , <b>2013</b> , 49, 1261-1267	5.7	33
6	Rendezvous of mobile agents with constrained energy and intermittent communication. <i>IET Control Theory and Applications</i> , <b>2012</b> , 6, 1557-1563	2.5	13
5	Bounded control for preserving connectivity of multi-agent systems using the constraint function approach. <i>IET Control Theory and Applications</i> , <b>2012</b> , 6, 1752	2.5	10
4	A novel approach to coordination of multiple robots with communication failures via proximity graph. <i>Automatica</i> , <b>2011</b> , 47, 1800-1805	5.7	33
3	Decentralized adaptive awareness coverage control for multi-agent networks. <i>Automatica</i> , <b>2011</b> , 47, 2749-2756	5.7	50
2	Combination framework of rendezvous algorithm for multi-agent systems with limited sensing ranges. <i>Asian Journal of Control</i> , <b>2011</b> , 13, 283-294	1.7	21
1	Weight balance for directed networks: Conditions and algorithms <b>2010</b> ,		2