

# Ella M Atkins

## List of Publications by Citations

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

109  
papers

3,865  
citations

17  
h-index

61  
g-index

119  
ext. papers

4,906  
ext. citations

2.8  
avg, IF

5.9  
L-index

#	Paper	IF	Citations
109	Information consensus in multivehicle cooperative control. <i>IEEE Control Systems</i> , <b>2007</b> , 27, 71-82	2.9	1925
108	Distributed multi-vehicle coordinated control via local information exchange. <i>International Journal of Robust and Nonlinear Control</i> , <b>2007</b> , 17, 1002-1033	3.6	934
107	Emergency Flight Planning Applied to Total Loss of Thrust. <i>Journal of Aircraft</i> , <b>2006</b> , 43, 1205-1216	1.6	67
106	Optimization and Control of Cyber-Physical Vehicle Systems. <i>Sensors</i> , <b>2015</b> , 15, 23020-49	3.8	56
105	X-HALE: A Very Flexible Unmanned Aerial Vehicle for Nonlinear Aeroelastic Tests. <i>AIAA Journal</i> , <b>2012</b> , 50, 2820-2833	2.1	50
104	Enhanced Smoothing Technique for Indirect Optimization of Minimum-Fuel Low-Thrust Trajectories. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2016</b> , 39, 2500-2511	2.1	50
103	Unsupervised Traffic Accident Detection in First-Person Videos <b>2019</b> ,		38
102	Cloud aided semi-active suspension control <b>2014</b> ,		27
101	Roof Shape Classification from LiDAR and Satellite Image Data Fusion Using Supervised Learning. <i>Sensors</i> , <b>2018</b> , 18,	3.8	27
100	Coupled CyberPhysical System Modeling and Coregulation of a CubeSat. <i>IEEE Transactions on Robotics</i> , <b>2015</b> , 31, 443-456	6.5	24
99	Damaged Airplane Trajectory Planning Based on Flight Envelope and Motion Primitives. <i>Journal of Aircraft</i> , <b>2014</b> , 51, 1740-1757	1.6	24
98	Shaping low-thrust trajectories with thrust-handling feature. <i>Advances in Space Research</i> , <b>2018</b> , 61, 879-890	2.4	23
97	Human Intent Prediction Using Markov Decision Processes. <i>Journal of Aerospace Information Systems</i> , <b>2015</b> , 12, 393-397	1	21
96	A New Clustering Algorithm for Processing GPS-Based Road Anomaly Reports With a Mahalanobis Distance. <i>IEEE Transactions on Intelligent Transportation Systems</i> , <b>2017</b> , 18, 1980-1988	6.1	21
95	Egocentric Vision-based Future Vehicle Localization for Intelligent Driving Assistance Systems <b>2019</b> ,		20
94	Emergency Flight Planning for an Energy-Constrained Multicopter. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , <b>2017</b> , 85, 145-165	2.9	18
93	Evaluating Risk to People and Property for Aircraft Emergency Landing Planning. <i>Journal of Aerospace Information Systems</i> , <b>2017</b> , 14, 259-278	1	17

92	Toward Continuous StateSpace Regulation of Coupled CyberPhysical Systems. <i>Proceedings of the IEEE</i> , <b>2012</b> , 100, 60-74	14.3	17
91	Characterizing Energy Usage of a Commercially Available Ground Robot: Method and Results. <i>Journal of Field Robotics</i> , <b>2014</b> , 31, 441-454	6.7	17
90	Optimal coverage trajectories for a UGV with tradeoffs for energy and time. <i>Autonomous Robots</i> , <b>2014</b> , 36, 257-271	3	17
89	Cloud aided safety-based route planning <b>2014</b> ,		15
88	Optimization of a Tetrahedral Satellite Formation. <i>Journal of Spacecraft and Rockets</i> , <b>2005</b> , 42, 699-710	1.5	15
87	Multi-Mode Guidance for an Independent Multicopter Geofencing System <b>2016</b> ,		14
86	Cyber-Physical Challenges for Space Systems <b>2012</b> ,		14
85	Noise-Minimum Runway-Independent Aircraft Approach Design for Baltimore-Washington International Airport. <i>Journal of Aircraft</i> , <b>2006</b> , 43, 39-51	1.6	14
84	BiTraP: Bi-Directional Pedestrian Trajectory Prediction With Multi-Modal Goal Estimation. <i>IEEE Robotics and Automation Letters</i> , <b>2021</b> , 6, 1463-1470	4.2	14
83	HIFiltering for Cloud-Aided Semi-active Suspension with Delayed Road Information. <i>IFAC-PapersOnLine</i> , <b>2015</b> , 48, 275-280	0.7	13
82	Planning and Resource Allocation for Hard Real-time, Fault-Tolerant Plan Execution. <i>Autonomous Agents and Multi-Agent Systems</i> , <b>2001</b> , 4, 57-78	2	13
81	Cooperative aerial lift and manipulation (CALM). <i>Aerospace Science and Technology</i> , <b>2018</b> , 82-83, 105-118	4.9	13
80	Road anomaly estimation: Model based pothole detection <b>2015</b> ,		12
79	Noise-Sensitive Final Approach Trajectory Optimization for Runway-Independent Aircraft. <i>Journal of Aerospace Computing, Information, and Communication</i> , <b>2004</b> , 1, 269-287		12
78	Multi-Objective Weight Optimization for Trajectory Planning of an Airplane with Structural Damage. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , <b>2018</b> , 91, 667-690	2.9	11
77	Geofencing in Immediate Reaches Airspace for Unmanned Aircraft System Traffic Management <b>2018</b> ,		10
76	Unmanned Aircraft System Navigation in the Urban Environment: A Systems Analysis. <i>Journal of Aerospace Information Systems</i> , <b>2016</b> , 13, 143-160	1	10
75	Envelopes for Flight Through Stochastic Gusts. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2013</b> , 36, 1464-1476	1.0	10

74	Qualitative Failure Analysis for a Small Quadrotor Unmanned Aircraft System <b>2013</b> ,		10
73	Game-Theoretic Modeling of Multi-Vehicle Interactions at Uncontrolled Intersections. <i>IEEE Transactions on Intelligent Transportation Systems</i> , <b>2020</b> , 1-15	6.1	10
72	Simultaneous road profile estimation and anomaly detection with an input observer and a jump diffusion process estimator <b>2016</b> ,		9
71	CyberPhysical Optimization for Unmanned Aircraft Systems. <i>Journal of Aerospace Information Systems</i> , <b>2014</b> , 11, 48-60	1	9
70	Incorporating Resource Safety Verification to Executable Model-based Development for Embedded Systems <b>2008</b> ,		9
69	Geofence Boundary Violation Detection in 3D Using Triangle Weight Characterization with Adjacency. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , <b>2019</b> , 95, 239-250	2.9	9
68	Continuum Deformation of Multi-Agent Systems Under Directed Communication Topologies. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , <b>2017</b> , 139,	1.6	8
67	Envelope-Aware Flight Management for Loss of Control Prevention Given Rudder Jam. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2017</b> , 40, 1027-1041	2.1	8
66	Fail-Safe Navigation for Autonomous Urban Multicopter Flight <b>2017</b> ,		7
65	Risk identification and management for safe UAS operation <b>2010</b> ,		7
64	Robust Science-Optimal Spacecraft Control for Circular Orbit Missions. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2020</b> , 50, 923-934	7.3	7
63	Asymptotic Tracking and Robustness of MAS Transitions Under a New Communication Topology. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2018</b> , 15, 16-32	4.9	6
62	Optimal State Estimation for Systems Driven by JumpDiffusion Process With Application to Road Anomaly Detection. <i>IEEE Transactions on Control Systems Technology</i> , <b>2017</b> , 25, 1634-1643	4.8	6
61	Flight Safety Assessment and Management for Takeoff Using Deterministic Moore Machines. <i>Journal of Aerospace Information Systems</i> , <b>2015</b> , 12, 599-615	1	6
60	Trim State Discovery with Physical Constraints. <i>Journal of Aircraft</i> , <b>2015</b> , 52, 90-106	1.6	6
59	Airspace Geofencing and Flight Planning for Low-Altitude, Urban, Small Unmanned Aircraft Systems. <i>Applied Sciences (Switzerland)</i> , <b>2022</b> , 12, 576	2.6	6
58	Verification Guided Refinement of Flight Safety Assessment and Management System for Takeoff. <i>Journal of Aerospace Information Systems</i> , <b>2016</b> , 13, 357-369	1	6
57	Layered Geofences in Complex Airspace Environments <b>2018</b> ,		6

56	Safe multi-cluster UAV continuum deformation coordination. <i>Aerospace Science and Technology</i> , <b>2019</b> , 91, 640-655	4.9	5
55	Fixed-Wing Unmanned Aircraft In-Flight Pitch and Yaw Control Moment Sensing. <i>Journal of Aircraft</i> , <b>2015</b> , 52, 403-420	1.6	5
54	Exploring Non-Aviation Information Sources for Aircraft Emergency Landing Planning <b>2016</b> ,		5
53	Experimental Investigation of Tractor and Pusher Hexacopter Performance. <i>Journal of Aircraft</i> , <b>2019</b> , 56, 1920-1934	1.6	5
52	Design and Development Methodology for Resilient Cyber-Physical Systems <b>2008</b> ,		5
51	The Smart Black Box: A Value-Driven High-Bandwidth Automotive Event Data Recorder. <i>IEEE Transactions on Intelligent Transportation Systems</i> , <b>2021</b> , 22, 1484-1496	6.1	5
50	Comprehensive Risk-based Planning for Small Unmanned Aircraft System Rooftop Landing <b>2018</b> ,		5
49	Scaling of Airplane Dynamic Response to Stochastic Gusts. <i>Journal of Aircraft</i> , <b>2014</b> , 51, 1554-1566	1.6	4
48	Human Productivity in a Workspace Shared with a Safe Robotic Manipulator. <i>Journal of Aerospace Information Systems</i> , <b>2014</b> , 11, 1-18	1	4
47	Experimental Characterization of Lift on a Rigid Flapping Wing. <i>Journal of Aircraft</i> , <b>2013</b> , 50, 1806-1821	1.6	4
46	Robust H <sub>∞</sub> control for a class of networked uncertain systems with multiple channels subject to Markovian switching <b>2015</b> ,		4
45	Supervisory traction control for a slipping UGV <b>2013</b> ,		4
44	Aerospace Avionics Systems <b>2010</b> ,		4
43	Visual Positioning System for an Underwater Space Simulation Environment. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2006</b> , 29, 858-869	2.1	4
42	Multi-Objective Spacecraft Trajectory Optimization with Synthetic Agent Oversight. <i>Journal of Aerospace Computing, Information, and Communication</i> , <b>2005</b> , 2, 4-24		4
41	Development, implementation, and experimental outdoor evaluation of quadcopter controllers for computationally limited embedded systems. <i>Annual Reviews in Control</i> , <b>2021</b> , 52, 372-372	10.3	4
40	Paths to Autonomous Vehicle Operations for Urban Air Mobility <b>2019</b> ,		4
39	Safe Multiquadcopter System Continuum Deformation Over Moving Frames. <i>IEEE Transactions on Control of Network Systems</i> , <b>2019</b> , 6, 737-749	4	3

38	Markov Decision Process Framework for Flight Safety Assessment and Management. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2017</b> , 40, 817-830	2.1	3
37	Continuum Deformation of a Multi-Quadcopter System in a Payload Delivery Mission. <i>IFAC-PapersOnLine</i> , <b>2017</b> , 50, 3455-3462	0.7	3
36	Education in the Crosscutting Sciences of Aerospace and Computing. <i>Journal of Aerospace Information Systems</i> , <b>2014</b> , 11, 726-737	1	3
35	Safe landing planning for an energy-constrained multicopter <b>2014</b> ,		3
34	Automated Curb Recognition and Negotiation for Robotic Wheelchairs. <i>Sensors</i> , <b>2021</b> , 21,	3.8	3
33	Polylidar - Polygons From Triangular Meshes. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 4634-4641	4.2	3
32	<b>2019</b> ,		3
31	The Smart Black Box: A Value-Driven Automotive Event Data Recorder <b>2018</b> ,		3
30	Generating Airspace Geofence Boundary Layers in Wind. <i>Journal of Aerospace Information Systems</i> , <b>2020</b> , 17, 113-124	1	2
29	Optimizing Steady Turns for Gliding Trajectories. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2016</b> , 39, 2627-2637	2.1	2
28	Low-Altitude Rural to Urban Unmanned Aircraft System Operations <b>2016</b> , 1-13		2
27	Automatic Classification of Roof Shapes for Multicopter Emergency Landing Site Selection <b>2018</b> ,		2
26	Cooperative Aerial Payload Transport Guided by an In Situ Human Supervisor. <i>IEEE Transactions on Control Systems Technology</i> , <b>2019</b> , 27, 1452-1467	4.8	2
25	Safety Margins for Flight Through Stochastic Gusts. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2014</b> , 37, 2026-2030	2.1	2
24	A Modal Operations Paradigm for Robust Vision-based Astronaut Following. <i>Journal of Aerospace Computing, Information, and Communication</i> , <b>2006</b> , 3, 603-618		2
23	Satellite Formation Mission Optimization with a Multi-Impulse Design. <i>Journal of Spacecraft and Rockets</i> , <b>2007</b> , 44, 425-433	1.5	2
22	An Autonomous Software Safety System for a Dexterous Space Robot. <i>Journal of Aerospace Computing, Information, and Communication</i> , <b>2004</b> , 1, 564-579		2
21	Keeping Ground Robots on the Move Through Battery & Mission Management. <i>Mechanical Engineering</i> , <b>2014</b> , 136, S1-S6	0.9	2

20	Physics-Based Freely Scalable Continuum Deformation for UAS Traffic Coordination. <i>IEEE Transactions on Control of Network Systems</i> , <b>2020</b> , 7, 532-544	4	2
19	Nonlinear control of semi-active suspension systems: A Quasi-Linear Control approach <b>2016</b> ,		2
18	Continuum Deformation of a Multiple Quadcopter Payload Delivery Team without Inter-Agent Communication <b>2018</b> ,		2
17	Geofence Definition and Deconfliction for UAS Traffic Management. <i>IEEE Transactions on Intelligent Transportation Systems</i> , <b>2021</b> , 22, 5880-5889	6.1	2
16	Improving Attitude Estimation Using Gaussian-Process-Regression-Based Magnetic Field Maps. <i>Sensors</i> , <b>2021</b> , 21,	3.8	2
15	Energy-Aware Multiflight Planning for an Unattended Seaplane: Flying Fish. <i>Journal of Aerospace Information Systems</i> , <b>2017</b> , 14, 73-91	1	1
14	Mission-Based Fault Reconfiguration for Spacecraft Applications. <i>Journal of Aerospace Information Systems</i> , <b>2013</b> , 10, 513-516	1	1
13	Preference-Based Trajectory Generation. <i>Journal of Aerospace Computing, Information, and Communication</i> , <b>2009</b> , 6, 142-170		1
12	Introduction: Achieving Intelligence in Aerospace Systems. <i>Journal of Aerospace Computing, Information, and Communication</i> , <b>2007</b> , 4, 751-752		1
11	H-infinity Filtering for Cloud-Aided Semi-active Suspension with Delayed Information. <i>Advances in Delays and Dynamics</i> , <b>2017</b> , 283-297	0.3	1
10	Polylidar3D-Fast Polygon Extraction from 3D Data. <i>Sensors</i> , <b>2020</b> , 20,	3.8	1
9	Formal Specification of Continuum Deformation Coordination <b>2019</b> ,		1
8	Scalable Vehicle Team Continuum Deformation Coordination with Eigen Decomposition. <i>IEEE Transactions on Automatic Control</i> , <b>2021</b> , 1-1	5.9	1
7	Smart Black Box 2.0: Efficient High-Bandwidth Driving Data Collection Based on Video Anomalies. <i>Algorithms</i> , <b>2021</b> , 14, 57	1.8	1
6	A Data-Driven Approach for Autonomous Motion Planning and Control in Off-Road Driving Scenarios <b>2018</b> ,		1
5	A Mass-Conservation Model for Stability Analysis and Finite-Time Estimation of Spread of COVID-19. <i>IEEE Transactions on Computational Social Systems</i> , <b>2021</b> , 8, 930-937	4.5	1
4	Statistical Properties and Airspace Capacity for Unmanned Aerial Vehicle Networks Subject to Sense-and-Avoid Safety Protocols. <i>IEEE Transactions on Intelligent Transportation Systems</i> , <b>2021</b> , 22, 5890-5903 <sup>1</sup>	6.1	1
3	Urban Metric Maps for Small Unmanned Aircraft Systems Motion Planning. <i>Journal of Aerospace Information Systems</i> , 1-16	1	1

- 2 A graph-theoretic-based method for analyzing conduction problems. *Journal of Engineering Mathematics*, **2017**, 106, 169-201 1.2
- 1 Multi-Unmanned-Aerial-Vehicle Wildfire Boundary Estimation Using a Semantic Segmentation Neural Network. *Journal of Aerospace Information Systems*, **2021**, 18, 231-249 1