List of Publications by Year in descending order

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#	Article	IF	CITATIONS
1	Integration of Action and Language Knowledge: A Roadmap for Developmental Robotics. IEEE Transactions on Autonomous Mental Development, 2010, 2, 167-195.	1.6	126
2	COGNITIVE MODELING OF SPATIAL REFERENCE FOR HUMAN-ROBOT INTERACTION. International Journal on Artificial Intelligence Tools, 2001, 10, 589-611.	1.0	68
3	Interpersonal variation in understanding robots as social actors. , 2011, , .		53
4	From Cognitive Semantics to Lexical Pragmatics. , 2000, , .		51
5	Grounding action words in the sensorimotor interaction with the world: experiments with a simulated iCub humanoid robot. Frontiers in Neurorobotics, 2010, 4, .	2.8	50
6	Levels of embodiment. , 2012, , .		48
7	People modify their tutoring behavior in robot-directed interaction for action learning. , 2009, , .		45
8	Experiences developing socially acceptable interactions for a robotic trash barrel. , 2015, , .		44
9	Beyond the sentence. Constructions and Frames, 2010, 2, 185-207.	0.3	42
10	Mindful tutors. Interaction Studies, 2011, 12, 134-161.	0.6	40
11	Zur diskursiven und modalen Funktion der Partikeln aber, auch, doch und ja in instruktionsdialogen. Linguistica (Slovenia), 1998, 38, 75-99.	0.2	40
12	Tutor Spotter: Proposing a Feature Set and Evaluating It in a Robotic System. International Journal of Social Robotics, 2012, 4, 131-146.	4.6	38
13	How People Talk with Robots: Designing Dialogue to Reduce User Uncertainty. Al Magazine, 2011, 32, 31-38.	1.6	33
14	Conversation, Construction Grammar, and cognition. Language and Cognition, 2015, 7, 563-588.	0.6	29
15	Comparing visualization techniques for learning second language prosody. International Journal of Learner Corpus Research, 2017, 3, 250-277.	0.5	26
16	The impact of the contingency of robot feedback on HRI. , 2013, , .		25
17	Teleoperation for learning by demonstration: Data glove versus object manipulation for intuitive robot control. , 2014, , .		25
18	Increasing trust in human–robot medical interactions: effects of transparency and adaptability. Paladyn, 2018, 9, 95-109.	2.7	22

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19	Emotion Expression in HRI â $\in$ When and Why. , 2019, , .		21
20	Experimental Contrastive Pragmatics Using Robots. Contrastive Pragmatics, 2020, 1, 82-107.	0.6	21
21	The Effects of Social Gaze in Human-Robot Collaborative Assembly. Lecture Notes in Computer Science, 2015, , 204-213.	1.3	20
22	SMOOTH Robot: Design for a Novel Modular Welfare Robot. Journal of Intelligent and Robotic Systems: Theory and Applications, 2020, 98, 19-37.	3.4	19
23	Speech Melody Matters—How Robots Profit from Using Charismatic Speech. ACM Transactions on Human-Robot Interaction, 2020, 9, 1-21.	4.1	19
24	Social robots as depictions of social agents. Behavioral and Brain Sciences, 2023, 46, 1-33.	0.7	19
25	Technologies for the Fast Set-Up of Automated Assembly Processes. KI - Kunstliche Intelligenz, 2014, 28, 305-313.	3.2	17
26	The ITALK Project: A Developmental Robotics Approach to the Study of Individual, Social, and Linguistic Learning. Topics in Cognitive Science, 2014, 6, 534-544.	1.9	17
27	Between legibility and contact: The role of gaze in robot approach. , 2016, , .		15
28	Why Collaborative Robots Must Be Social (and even Emotional) Actors. Techné Research in Philosophy and Technology, 2019, 23, 270-289.	0.2	15
29	Integrative Social Robotics Hands-on. Interaction Studies, 2020, 21, 145-185.	0.6	14
30	Contingency allows the robot to spot the tutor and to learn from interaction. , 2011, , .		13
31	Situation in grammar or in frames?. Constructions and Frames, 2015, 7, 258-288.	0.3	13
32	Methods for the description of discourse particles: contrastive analysis. Language Sciences, 1996, 18, 853-861.	1.0	12
33	Do not Hesitate! — Unless You Do it Shortly or Nasally: How the Phonetics of Filled Pauses Determine Their Subjective Frequency and Perceived Speaker Performance. , 0, , .		12
34	Social interaction with robots and agents: Where do we stand, where do we go?. , 2009, , .		11
35	Tracking Anthropomorphizing Behavior in Human-Robot Interaction. ACM Transactions on Human-Robot Interaction, 2022, 11, 1-28.	4.1	11
36	To Beep or Not to Beep Is Not the Whole Question. Lecture Notes in Computer Science, 2014, , 156-165.	1.3	10

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37	On the interaction of constructions with register and genre. Constructions and Frames, 2015, 7, 137-147.	0.3	10
38	Embodied Language Learning and Cognitive Bootstrapping: Methods and Design Principles. International Journal of Advanced Robotic Systems, 2016, 13, 105.	2.1	8
39	The Challenges of Working on Social Robots that Collaborate with People. , 2019, , .		8
40	Gaze-Speech Coordination Influences the Persuasiveness of Human-Robot Dialog in the Wild. Lecture Notes in Computer Science, 2020, , 157-169.	1.3	8
41	A Drink-Serving Mobile Social Robot Selects who to Interact with Using Gaze. , 2020, , .		8
42	Shaping Naive Users' Models of Robots' Situation Awareness. , 2007, , .		7
43	Is talking to a simulated robot like talking to a child?. , 2011, , .		7
44	Studying Drink-Serving Service Robots in the Real World. , 2020, , .		7
45	Effect Confirmed, Patient Dead. ACM Transactions on Human-Robot Interaction, 2021, 10, 1-4.	4.1	7
46	Using discourse segmentation to account for the polyfunctionality of discourse markers: The case of well. Journal of Pragmatics, 2021, 173, 101-118.	1.5	7
47	Modal particles and sentence type restrictions: A construction grammar perspective. Glossa, 2018, 3, .	0.5	7
48	Human embodiment creates problems for robot learning by demonstration using a control panel. , 2014, , .		6
49	Negotiating Instruction Strategies during Robot Action Demonstration. , 2015, , .		6
50	It Gets Worse Before it Gets Better. , 2017, , .		6
51	Timing of multimodal robot behaviors during human-robot collaboration. , 2017, , .		6
52	The SMOOTH-Robot: A Modular, Interactive Service Robot. Frontiers in Robotics and AI, 2021, 8, 645639.	3.2	6
53	Inferential Processes in English and the Question whether English has Modal Particles. Open Linguistics, 2018, 4, 509-535.	0.5	5
54	Trust in Medical Human-Robot Interactions based on Kinesthetic guidance. , 2018, , .		5

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55	Effects of Different Kinds of Robot Feedback. Lecture Notes in Computer Science, 2013, , 260-269.	1.3	5
56	Reasons for singularity in robot teleoperation. , 2014, , .		4
57	The Role of Emotional Expression in Behavior Change Coaching by a Social Robot. Lecture Notes in Computer Science, 2021, , 193-199.	1.3	4
58	Speed and Speech Impact on the Usage of a Hand Sanitizer Robot. , 2021, , .		4
59	Studying Language Attitudes Using Robots. , 2020, , .		4
60	Cognitive Linguistics and Pragmatics. , 0, , 330-346.		3
61	Robot use cases for real needs: A large-scale ethnographic case study. Paladyn, 2019, 10, 193-206.	2.7	3
62	Initiating Human-Robot Interactions Using Incremental Speech Adaptation. , 2021, , .		3
63	Effects of Gaze and Speech in Human-Robot Medical Interactions. , 2021, , .		3
64	Robots for Foreign Language Learning: Speaking Style Influences Student Performance. Frontiers in Robotics and Al, 2021, 8, 680509.	3.2	3
65	Error Feedback for Robust Learning from Demonstration. , 2015, , .		3
66	In the same boat. Interaction Studies, 2021, 22, 488-515.	0.6	3
67	Intuitive error resolution strategies during robot demonstration. , 2014, , .		2
68	People do not interact with robots like they do with dogs. Interaction Studies, 2014, 15, 201-204.	0.6	2
69	Human Smile Distinguishes between Collaborative and Solitary Tasks in Human-Robot Interaction. , 2015, , .		2
70	Eliciting extra prominence in read-speech tasks: The effects of different text-highlighting methods on acoustic cues to perceived prominence. , 0, , .		2
71	Alignment or collaboration? How implicit views of communication influence robot design. , 2014, , .		1
72	A novel tele-operation device allowing for dynamic switching between control points during learning from demonstration. , 2015, , .		1

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73	The Role of a Social Robot in Behavior Change Coaching. , 2021, , .		1
74	Geräsche, Stimmen und natürliche Sprache. , 2021, , 279-292.		1
75	Using Robots to Study the Perception of Feedback Cross-culturally. , 2020, , .		1
76	Review of Itakura (2001): Conversational Dominance and Gender. A Study of Japanese Speakers in First and Second Language Contexts. Studies in Language, 2007, 31, 717-720.	0.5	0
77	Human tutors intuitively reduce complexity in socially guided embodied grammar learning. , 2012, , .		0
78	The Situatedness of Pragmatic Acts: Explaining a Lamp to a Robot. Perspectives in Pragmatics, Philosophy and Psychology, 2016, , 901-910.	0.2	0
79	Understanding the Perception of Incremental Robot Response in Human-Robot Interaction. , 2020, , .		0
80	Relationships between construction grammar(s) and genre: Evidence from an analysis of Instagram posts. Journal of Pragmatics, 2021, 183, 87-104.	1.5	0
81	Multimodal Feedback in Human-Robot Interaction. Advances in Human and Social Aspects of Technology Book Series, 2016, , 135-161.	0.3	0
82	Session details: Session 2: Human-Robot Dialog. , 2017, , .		0
83	Using robots to study speech $\hat{a} \in \hat{~}$ interactional processes and speech functions. , 0, , .		0
84	Multimodal Feedback in Human-Robot Interaction. , 2020, , 990-1017.		0
85	User Expectations and Preferences to How Social Robots Render Text Messages with Emojis. , 2020, , .		0
86	What influences influence?. Interaction Studies, 2021, 22, 291-302.	0.6	0