

Hamed Farivarnejad

List of Publications by Year in descending order

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papers

100
citations

2258059

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2550090

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7
docs citations

7
times ranked

71
citing authors

#	ARTICLE	IF	CITATIONS
1	Kinematic Modeling and Trajectory Tracking Control of an Octopus-Inspired Hyper-Redundant Robot. IEEE Robotics and Automation Letters, 2020, 5, 3460-3467.	5.1	30
2	Decentralized sliding mode control for autonomous collective transport by multi-robot systems. , 2016, , .		27
3	Adaptation of Gradient-Based Navigation Control for Holonomic Robots to Nonholonomic Robots. IEEE Robotics and Automation Letters, 2021, 6, 191-198.	5.1	15
4	Stability and Convergence Analysis of a Decentralized Proportional-Integral Control Strategy for Collective Transport. , 2018, , .		11
5	Decentralized Collective Transport along Manifolds Compatible with Holonomic Constraints by Robots with Minimal Global Information. , 2020, , .		7
6	Multirobot Control Strategies for Collective Transport. Annual Review of Control, Robotics, and Autonomous Systems, 2022, 5, 205-219.	11.8	7
7	A Consensus Strategy for Decentralized Kinematic Control of Multi-Segment Soft Continuum Robots. , 2020, , .		3