

Ting Zhang

List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/7893174/publications.pdf>

Version: 2024-02-01

10
papers

57
citations

1478505

6
h-index

1588992

8
g-index

10
all docs

10
docs citations

10
times ranked

54
citing authors

#	ARTICLE	IF	CITATIONS
1	Dynamic characteristics and stability criterion of rotary galloping gait with an articulated passive spine joint. <i>Advanced Robotics</i> , 2017, 31, 168-183.	1.8	11
2	Intelligent Machine Fault Diagnosis Using Convolutional Neural Networks and Transfer Learning. <i>IEEE Access</i> , 2022, 10, 50959-50973.	4.2	10
3	Sparse Reconstruction Based on the ADMM and Lasso-LSQR for Bearings Vibration Signals. <i>IEEE Access</i> , 2017, 5, 20083-20088.	4.2	9
4	Adaptive modal vibration control for smart flexible beam with two piezoelectric actuators by multivariable self-tuning control. <i>JVC/Journal of Vibration and Control</i> , 2020, 26, 490-504.	2.6	8
5	Dynamic Imbalance Analysis and Stability Control of Galloping Gait for a Passive Quadruped Robot. <i>Applied Bionics and Biomechanics</i> , 2015, 2015, 1-17.	1.1	6
6	Hysteresis characteristics influence on the super-harmonic vibration of a bi-stable piezoelectric energy harvester. <i>Journal of Low Frequency Noise Vibration and Active Control</i> , 2018, 37, 1003-1014.	2.9	6
7	Time delay stability analysis for vibration suppression of a smart cantilever beam with hysteresis property. <i>Journal of Low Frequency Noise Vibration and Active Control</i> , 2021, 40, 898-915.	2.9	4
8	Dynamical Model for an Interharmonic Property of a Piezoelectric Bimorph Cantilever Beam with Self-Sensing Function. <i>Shock and Vibration</i> , 2016, 2016, 1-9.	0.6	1
9	Influence of Hysteresis on the Vibration Control of a Smart Beam with a Piezoelectric Actuator by the Bouc-Wen Model. <i>Shock and Vibration</i> , 2020, 2020, 1-11.	0.6	1
10	Adaptive vibration control for a cantilevered beam using actuating and sensing functions of a piezoelectric bimorph. <i>Vibroengineering PROCEDIA</i> , 2018, 20, 87-90.	0.5	1