

Luca Fiorio

List of Publications by Year in descending order

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Version: 2024-02-01

15
papers

194
citations

1937685

4
h-index

2053705

5
g-index

15
all docs

15
docs citations

15
times ranked

218
citing authors

#	ARTICLE	IF	CITATIONS
1	Momentum-Based Extended Kalman Filter for Thrust Estimation on Flying Multibody Robots. IEEE Robotics and Automation Letters, 2022, 7, 526-533.	5.1	10
2	Modeling and Control of Morphing Covers for the Adaptive Morphology of Humanoid Robots. IEEE Transactions on Robotics, 2022, 38, 3300-3313.	10.3	1
3	A Novel Sensorised Insole for Sensing Feet Pressure Distributions. Sensors, 2020, 20, 747.	3.8	23
4	Modeling, Identification and Control of Model Jet Engines for Jet Powered Robotics. IEEE Robotics and Automation Letters, 2020, 5, 2070-2077.	5.1	12
5	Design and Control of a Passive Noise Rejecting Variable Stiffness Actuator. Springer Tracts in Advanced Robotics, 2019, , 235-262.	0.4	0
6	Position and Attitude Control of an Underactuated Flying Humanoid Robot. , 2018, , .		15
7	The design and validation of the R1 personal humanoid. , 2017, , .		33
8	A parallel kinematic mechanism for the torso of a humanoid robot: Design, construction and validation. , 2017, , .		6
9	A parallel kinematic wrist for the R1 humanoid robot. , 2017, , .		7
10	Walking on partial footholds including line contacts with the humanoid robot atlas. , 2016, , .		62
11	Control of a two-DoF manipulator equipped with a pnr-variable stiffness actuator. , 2014, , .		2
12	Exploiting global force torque measurements for local compliance estimation in tactile arrays. , 2014, , .		8
13	On the effects of internal stiction in pnrVIA actuators. , 2013, , .		2
14	Control of a single Degree of Freedom Noise Rejecting - Variable Impedance Actuator. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 473-478.	0.4	6
15	pnrVSA: human-like actuator with non-linear springs in agonist-antagonist configuration. , 2012, , .		7