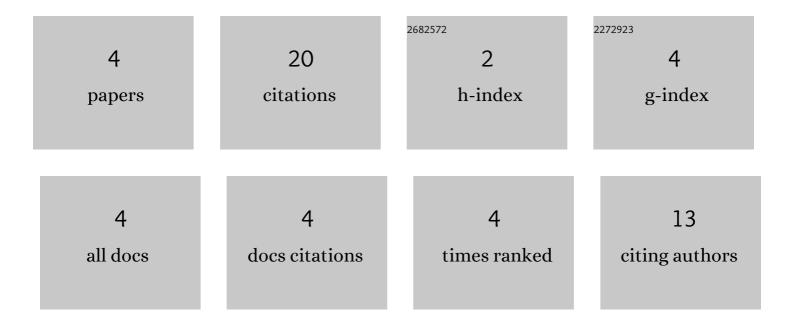
## **Phillipe Cardoso**

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/7840812/publications.pdf Version: 2024-02-01



| # | Article  | IF  | CITATIONS |
|---|--|-----|-----------|
| 1 | Two-Layers Workspace: A New Approach to Cooperative Object Transportation With Obstacle<br>Avoidance for Multi-Robot System. IEEE Access, 2022, 10, 6929-6939. | 4.2 | 2         |
| 2 | FABRIK-R: An Extension Developed Based on FABRIK for Robotics Manipulators. IEEE Access, 2021, 9, 53423-53435.   | 4.2 | 4         |
| 3 | MB-RRT: An Inverse Kinematics Solver of Reduced Dimension. IEEE Access, 2021, 9, 148558-148573.  | 4.2 | 1         |
| 4 | M-FABRIK: A New Inverse Kinematics Approach to Mobile Manipulator Robots Based on FABRIK. IEEE<br>Access, 2020, 8, 208836-208849.                              | 4.2 | 13        |