## Soura Dasgupta

List of Publications by Year in descending order

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Version: 2024-02-01

567281 1,581 92 15 citations h-index papers

g-index 93 93 93 1164 docs citations times ranked citing authors all docs

434195

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#	Article	IF	CITATIONS
1	Stability and Resilience of Distributed Information Spreading in Aggregate Computing. IEEE Transactions on Automatic Control, 2023, 68, 454-461.	<b>5.7</b>	1
2	A Lyapunov Analysis of a Most Probable Path Finding Algorithm. , 2022, 6, 1052-1057.		0
3	Heartbeat Measurement with Millimeter Wave Radar in the Driving Environment. , 2021, , .		7
4	Effect of Monotonic Filtering on Graph Collection Dynamics. , 2021, , .		1
5	Improved small gain conditions for input-to-state stability with respect to measurement functions: Discrete time networked system. , 2021, , .		1
6	Linear predictive coding distinguishes spectral EEG features of Parkinson's disease. Parkinsonism and Related Disorders, 2020, 79, 79-85.	2.2	65
7	Improving Collection Dynamics by Monotonic Filtering. , 2020, , .		3
8	Linear Predictive Approaches Separate Field Potentials in Animal Model of Parkinson's Disease. Frontiers in Neuroscience, 2020, 14, 394.	2.8	6
9	A Resilient Leader Election Algorithm Using Aggregate Computing Blocks. IFAC-PapersOnLine, 2020, 53, 3336-3341.	0.9	7
10	A Framework for Self-Adaptive Dispersal of Computing Services. , 2019, , .		6
10	A Framework for Self-Adaptive Dispersal of Computing Services., 2019,,.  Control of Formations with Nonlinear Non-Passive Actuation., 2019,,.		6
		5.7	
11	Control of Formations with Nonlinear Non-Passive Actuation. , 2019, , .  Robustness of the Adaptive Bellman –Ford Algorithm: Global Stability and Ultimate Bounds. IEEE	5.7	0
11 12	Control of Formations with Nonlinear Non-Passive Actuation. , 2019, , .  Robustness of the Adaptive Bellman –Ford Algorithm: Global Stability and Ultimate Bounds. IEEE Transactions on Automatic Control, 2019, 64, 4121-4136.	5.7	20
11 12 13	Control of Formations with Nonlinear Non-Passive Actuation. , 2019, , .  Robustness of the Adaptive Bellman –Ford Algorithm: Global Stability and Ultimate Bounds. IEEE Transactions on Automatic Control, 2019, 64, 4121-4136.  Global Uniform Asymptotic Stability of a Generalized Adaptive Bellman-Ford Algorithm. , 2019, , .	5.7	0 20 1
11 12 13	Control of Formations with Nonlinear Non-Passive Actuation. , 2019, , .  Robustness of the Adaptive Bellman –Ford Algorithm: Global Stability and Ultimate Bounds. IEEE Transactions on Automatic Control, 2019, 64, 4121-4136.  Global Uniform Asymptotic Stability of a Generalized Adaptive Bellman-Ford Algorithm. , 2019, , .  Robust Stability of Spreading Blocks in Aggregate Computing. , 2018, , .	9.2	0 20 1 3
11 12 13 14	Control of Formations with Nonlinear Non-Passive Actuation., 2019,,.  Robustness of the Adaptive Bellman –Ford Algorithm: Global Stability and Ultimate Bounds. IEEE Transactions on Automatic Control, 2019, 64, 4121-4136.  Global Uniform Asymptotic Stability of a Generalized Adaptive Bellman-Ford Algorithm., 2019,,.  Robust Stability of Spreading Blocks in Aggregate Computing., 2018,,.  An Aggregate Computing Approach to Self-Stabilizing Leader Election., 2018,,  Optimal Precoder Design for Distributed Transmit Beamforming Over Frequency-Selective Channels.		0 20 1 3

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19	Subspace Aware Recovery of Low Rank and Jointly Sparse Signals. IEEE Transactions on Computational Imaging, 2017, 3, 22-35.	4.4	3
20	Experimental demonstration of nullforming from a fully wireless distributed array., 2017,,.		1
21	Distributed MIMO Multicast With Protected Receivers: A Scalable Algorithm for Joint Beamforming and Nullforming. IEEE Transactions on Wireless Communications, 2017, 16, 512-525.	9.2	8
22	Adaptive Source Localization Based Station Keeping of Autonomous Vehicles. IEEE Transactions on Automatic Control, 2017, 62, 3122-3135.	5.7	29
23	Error in Self-Stabilizing Spanning-Tree Estimation of Collective State. , 2017, , .		7
24	A class of scalable feedback algorithms for beam and null-forming from distributed arrays. , 2016, , .		4
25	Maximizing wireless power transfer using distributed beamforming. , 2016, , .		4
26	A Lyapunov analysis for the robust stability of an adaptive Bellman-Ford algorithm. , 2016, , .		11
27	Rigid formation control with nonlinear passive actuation. , 2016, , .		2
28	Experimental demonstration of retrodirective beamforming from a fully wireless distributed array. , 2016, , .		16
29	Capacity maximization for distributed broadband beamforming. , 2016, , .		3
30	Experimental demonstration of a distributed antenna array pre-synchronized for retrodirective transmission. , 2016, , .		13
31	A bayesian approach to multiple target localization. , 2015, , .		1
32	Maximum Likelihood Localization of Radioactive Sources Against a Highly Fluctuating Background. IEEE Transactions on Nuclear Science, 2015, 62, 3274-3282.	2.0	22
33	An approach to Kalman filtering for oscillator tracking. , 2015, , .		1
34	Spark under 2-D fourier sampling. , 2015, , .		1
35	Channel State Tracking for Large-Scale Distributed MIMO Communication Systems. IEEE Transactions on Signal Processing, 2015, 63, 2559-2571.	<b>5.</b> 3	3
36	A Scalable Feedback Mechanism for Distributed Nullforming With Phase-Only Adaptation. IEEE Transactions on Signal and Information Processing Over Networks, 2015, 1, 58-70.	2.8	14

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37	A New Measure of Wireless Network Connectivity. IEEE Transactions on Mobile Computing, 2015, 14, 1765-1779.	5.8	11
38	Toward Predicting Distributed Systems Dynamics., 2015,,.		6
39	The maximum likelihood estimate for radiation source localization: Initializing an iterative search. , 2014, , .		9
40	A distributed control law for optimum sensor placement for source localization. , 2014, , .		1
41	Coprime conditions for Fourier sampling for sparse recovery. , 2014, , .		6
42	On Forward Channel Estimation for MIMO Precoding in Cooperative Relay Wireless Transmission Systems. IEEE Transactions on Signal Processing, 2014, 62, 1265-1278.	5.3	12
43	An empirical study of the statistics of phase drift of off-the-shelf oscillators for distributed MIMO applications. , 2014, , .		2
44	Multiple Source Localization in Wireless Sensor Networks Based on Time of Arrival Measurement. IEEE Transactions on Signal Processing, 2014, 62, 1938-1949.	5.3	118
45	Asymptotic oscillator tracking performance analysis for distributed massive MIMO systems. , 2014, , .		2
46	On the Gradient Descent Localization of Radioactive Sources. IEEE Signal Processing Letters, 2013, 20, 1046-1049.	3.6	19
47	Adaptive rangeâ€measurementâ€based target pursuit. International Journal of Adaptive Control and Signal Processing, 2013, 27, 66-81.	4.1	49
48	Certifying non-existence of undesired locally stable equilibria in formation shape control problems. , 2013, , .		3
49	Identifiability and excitation of polynomial systems. , 2013, , .		9
50	On the quality of wireless network connectivity. , 2012, , .		4
51	Urban source localization based on time of arrival measurement and street information. , 2012, , .		0
52	Optimum sensor placement for localization in three dimensional under log normal shadowing. , 2012, , .		8
53	Adaptive docking using range measurements. , 2012, , .		O
54	Receiver-coordinated distributed transmit nullforming with channel state uncertainty. , 2012, , .		30

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55	Tensor scale: An analytic approach with efficient computation and applications. Computer Vision and Image Understanding, 2012, 116, 1060-1075.	4.7	10
56	Poster abstract: Cybermussels: A biological sensor network using freshwater mussels. , 2012, , .		0
57	Circumnavigation Using Distance Measurements Under Slow Drift. IEEE Transactions on Automatic Control, 2012, 57, 889-903.	5.7	177
58	Source Localization in Wireless Sensor Networks From Signal Time-of-Arrival Measurements. IEEE Transactions on Signal Processing, 2011, 59, 2887-2897.	5.3	217
59	Control of Minimally Persistent Leader-Remote-Follower and Coleader Formations in the Plane. IEEE Transactions on Automatic Control, 2011, 56, 2778-2792.	5.7	120
60	Reduced Complexity Semidefinite Relaxation Algorithms for Source Localization Based on Time Difference of Arrival. IEEE Transactions on Mobile Computing, 2011, 10, 1276-1282.	5.8	44
61	Stability of adaptive delta modulators with forgetting factor and constant inputs. International Journal of Adaptive Control and Signal Processing, 2011, 25, 723-739.	4.1	2
62	Coordinated fault tolerant optimal control of autonomous agents: geometry and communication architecture. Communications in Information and Systems, 2011, 11, 173-196.	0.5	5
63	Wireless source localization based on time of arrival measurement. , 2010, , .		8
64	Robust and Low Complexity Source Localization in Wireless Sensor Networks Using Time Difference of Arrival Measurement., 2010,,.		6
65	Optimum sensor placement for localization under log-normal shadowing. , 2010, , .		5
66	An exponentially convergent adaptive algorithm for time-varying IIR filters. , 2010, , .		0
67	Source Localization from Received Signal Strength Under Log-Normal Shadowing: Bias and Variance. , 2009, , .		4
68	An exponentially convergent adaptive algorithm for time-varying IIR filters. , 2009, , .		0
69	Distance Estimation From Received Signal Strength Under Log-Normal Shadowing: Bias and Variance. IEEE Signal Processing Letters, 2009, 16, 216-218.	3.6	80
70	Optimum sensor placement for source monitoring under log-normal shadowing in three dimensions. , 2009, , .		8
71	Circumnavigation using distance measurements. , 2009, , .		6
72	Distance estimation from received signal strength under log-normal shadowing: Bias and variance. , 2008, , .		8

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73	Performance Analysis of a Forward Link Channel Estimation Method for Wireless Multicarrier Systems. IEEE Transactions on Wireless Communications, 2008, 7, 3026-3035.	9.2	1
74	Achieving formations under medium access, relative position and velocity constraints., 2008,,.		1
75	The relation between redundancy and convergence rate in distributed multi-agent formation control. , 2008, , .		5
76	A Semidefinite Programming Approach to Source Localization in Wireless Sensor Networks. IEEE Signal Processing Letters, 2008, 15, 253-256.	3.6	72
77	Control of directed formations with a leader-first follower structure. , 2007, , .		22
78	Fault Tolerant Scalable Coordinated Control of Agent Formations with Arbitrary Trajectories. , 2007, , .		2
79	Optimumisi-free DMT systems withconcave SNR tobit rate relations: when does othonornmality suffice?., 2007,,.		2
80	Distributed multiagent formation control with enhanced scalability., 2007,,.		2
81	NONLINEAR OPTIMAL CONTROL. , 2007, , 569-586.		3
82	Toward a Theory of Multirate Nonlinear Systems. , 2006, , .		0
83	Adaptive Source Localization by Mobile Agents. , 2006, , .		28
84	Integral quadratic constraint approach vs. multiplier approach. Automatica, 2005, 41, 281-287.	5.0	28
85	Optimum compaction filters for cyclostationary signals. , 2002, , .		0
86	5. Parametric Lyapunov Functions for Uncertain Systems: The Multiplier Approach., 2000,, 95-108.		29
87	Robust control design of sampled systems. International Journal of Systems Science, 1990, 21, 985-992.	5 <b>.</b> 5	2
88	Uncertainties in Sampled Data Systems. , 1989, , .		1
89	Convergence of an Adaptive Filter with Signed Error Filtering. , 1988, , .		3
90	A Kharitonov like theorem for systems under nonlinear passive feedback. , 1987, , .		53

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#	Article	IF	CITATIONS
91	Tuning leakage for robust adaptive control. , 1987, , .		8
92	Output-error identification methods for partially known systems. International Journal of Control, 1986, 43, 177-191.	1.9	47