

Zhiqiang Sui

List of Publications by Year in descending order

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7
papers

105
citations

2682572

2
h-index

2917675

2
g-index

7
all docs

7
docs citations

7
times ranked

70
citing authors

#	ARTICLE	IF	CITATIONS
1	GeoFusion: Geometric Consistency Informed Scene Estimation in Dense Clutter. IEEE Robotics and Automation Letters, 2020, 5, 5913-5920.	5.1	9
2	GRIP: Generative Robust Inference and Perception for Semantic Robot Manipulation in Adversarial Environments. , 2019, , .		17
3	Plenoptic Monte Carlo Object Localization for Robot Grasping Under Layered Translucency. , 2018, , .		11
4	Semantic Robot Programming for Goal-Directed Manipulation in Cluttered Scenes. , 2018, , .		19
5	Goal-directed robot manipulation through axiomatic scene estimation. International Journal of Robotics Research, 2017, 36, 86-104.	8.5	20
6	SUM: Sequential scene understanding and manipulation. , 2017, , .		20
7	Physically plausible scene estimation for manipulation in clutter. , 2016, , .		9