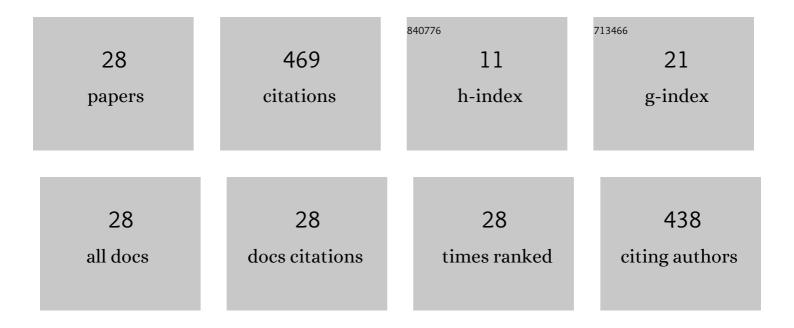
Boujemaa Ait-El-Fquih

List of Publications by Year in descending order

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#	Article	IF	CITATIONS
1	Filtering with One-Step-Ahead Smoothing for Efficient Data Assimilation. , 2022, , 69-96.		2
2	A reduced-order variational Bayesian approach for efficient subsurface imaging. Geophysical Journal International, 2022, 229, 838-852.	2.4	6
3	Enhancing ensemble data assimilation into oneâ€wayâ€coupled models with oneâ€stepâ€ahead smoothing. Quarterly Journal of the Royal Meteorological Society, 2021, 147, 249-272.	2.7	2
4	Bayesian identification of oil spill source parameters from image contours. Marine Pollution Bulletin, 2021, 169, 112514.	5.0	5
5	Ensemble Kalman filtering with coloured observation noise. Quarterly Journal of the Royal Meteorological Society, 2021, 147, 4408-4424.	2.7	2
6	Parametric Bayesian estimation of point-like pollution sources of groundwater layers. Signal Processing, 2020, 168, 107339.	3.7	10
7	A particleâ€filter based adaptive inflation scheme for the ensemble Kalman filter. Quarterly Journal of the Royal Meteorological Society, 2020, 146, 922-937.	2.7	4
8	Calibrating land hydrological models and enhancing their forecasting skills using an ensemble Kalman filter with one-step-ahead smoothing. Journal of Hydrology, 2020, 584, 124708.	5.4	13
9	Enhanced flood forecasting through ensemble data assimilation and joint state-parameter estimation. Journal of Hydrology, 2019, 577, 123924.	5.4	24
10	Combining Hybrid and One-Step-Ahead Smoothing for Efficient Short-Range Storm Surge Forecasting with an Ensemble Kalman Filter. Monthly Weather Review, 2019, 147, 3283-3300.	1.4	6
11	An Efficient State–Parameter Filtering Scheme Combining Ensemble Kalman and Particle Filters. Monthly Weather Review, 2018, 146, 871-887.	1.4	9
12	Ensemble Kalman Filtering with One-Step-Ahead Smoothing. Monthly Weather Review, 2018, 146, 561-581.	1.4	11
13	A Variational Bayesian Estimation Scheme For Parametric Point-Like Pollution Source of Groundwater Layers. , 2018, , .		1
14	Unsupervised ensemble Kalman filtering with an uncertain constraint for land hydrological data assimilation. Journal of Hydrology, 2018, 564, 175-190.	5.4	23
15	Estimating modelâ€error covariances in nonlinear stateâ€space models using Kalman smoothing and the expectation–maximization algorithm. Quarterly Journal of the Royal Meteorological Society, 2017, 143, 1877-1885.	2.7	50
16	A two-update ensemble Kalman filter for land hydrological data assimilation with an uncertain constraint. Journal of Hydrology, 2017, 555, 447-462.	5.4	41
17	A Bayesian consistent dual ensemble Kalman filter for state-parameter estimation in subsurface hydrology. Hydrology and Earth System Sciences, 2016, 20, 3289-3307.	4.9	32
18	A Variational Bayesian Multiple Particle Filtering Scheme for Large-Dimensional Systems. IEEE Transactions on Signal Processing, 2016, 64, 5409-5422.	5.3	34

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#	Article	IF	CITATIONS
19	Efficient Kernel-Based Ensemble Gaussian Mixture Filtering. Monthly Weather Review, 2016, 144, 781-800.	1.4	23
20	An iterative ensemble Kalman filter with one-step-ahead smoothing for state-parameters estimation of contaminant transport models. Journal of Hydrology, 2015, 527, 442-457.	5.4	49
21	An efficient multiple particle filter based on the variational Bayesian approach. , 2015, , .		5
22	Fast Kalman-Like Filtering for Large-Dimensional Linear and Gaussian State-Space Models. IEEE Transactions on Signal Processing, 2015, 63, 5853-5867.	5.3	29
23	Backward hidden Markov chain for outlier-robust filtering and fixed-interval smoothing. , 2013, , .		2
24	Fixed-Interval Kalman Smoothing Algorithms in Singular State–Space Systems. Journal of Signal Processing Systems, 2011, 65, 469-478.	2.1	8
25	Direct, prediction- and smoothing-based Kalman and particle filter algorithms. Signal Processing, 2011, 91, 2064-2077.	3.7	21
26	Variational Bayesian Kalman filtering in dynamical tomography. , 2011, , .		9
27	Kalman Filtering in Triplet Markov Chains. IEEE Transactions on Signal Processing, 2006, 54, 2957-2963.	5.3	31
28	Data Assimilation in Oceanography: Current Status and New Directions. , 0, , .		17