Laura Justham

List of Publications by Year in descending order

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840776 642732 38 596 11 23 citations h-index g-index papers 40 40 40 561 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Soft pneumatic grippers embedded with stretchable electroadhesion. Smart Materials and Structures, 2018, 27, 055006.	3.5	108
2	Optimization and experimental verification of coplanar interdigital electroadhesives. Journal Physics D: Applied Physics, 2016, 49, 415304.	2.8	64
3	Embedded programming and real-time signal processing of swimming strokes. Sports Engineering, 2011, 14, 1-14.	1.1	54
4	Investigation of relationship between interfacial electroadhesive force and surface texture. Journal Physics D: Applied Physics, 2016, 49, 035303.	2.8	42
5	Toward Adaptive and Intelligent Electroadhesives for Robotic Material Handling. IEEE Robotics and Automation Letters, 2017, 2, 538-545.	5.1	33
6	Visualization methods for understanding the dynamic electroadhesion phenomenon. Journal Physics D: Applied Physics, 2017, 50, 205304.	2.8	27
7	Development of a real time system for monitoring of swimming performance. Procedia Engineering, 2010, 2, 2707-2712.	1.2	23
8	A Concept Selection Method for Designing Climbing Robots. Key Engineering Materials, 0, 649, 22-29.	0.4	23
9	Experimental study of relationship between interfacial electroadhesive force and applied voltage for different substrate materials. Applied Physics Letters, 2017, 110, .	3.3	21
10	Feature extraction and tracking of a weld joint for adaptive robotic welding. , 2014, , .		20
10	Feature extraction and tracking of a weld joint for adaptive robotic welding., 2014, , . Geometric Optimisation of Electroadhesive Actuators Based on 3D Electrostatic Simulation and its Experimental Verification. IFAC-PapersOnLine, 2016, 49, 309-315.	0.9	20
	Geometric Optimisation of Electroadhesive Actuators Based on 3D Electrostatic Simulation and its	0.9 3.6	
11	Geometric Optimisation of Electroadhesive Actuators Based on 3D Electrostatic Simulation and its Experimental Verification. IFAC-PapersOnLine, 2016, 49, 309-315. Autonomous metrology for robot mounted 3D vision systems. CIRP Annals - Manufacturing		20
11 12	Geometric Optimisation of Electroadhesive Actuators Based on 3D Electrostatic Simulation and its Experimental Verification. IFAC-PapersOnLine, 2016, 49, 309-315. Autonomous metrology for robot mounted 3D vision systems. CIRP Annals - Manufacturing Technology, 2017, 66, 483-486.	3.6	18
11 12 13	Geometric Optimisation of Electroadhesive Actuators Based on 3D Electrostatic Simulation and its Experimental Verification. IFAC-PapersOnLine, 2016, 49, 309-315. Autonomous metrology for robot mounted 3D vision systems. CIRP Annals - Manufacturing Technology, 2017, 66, 483-486. Dynamic signature for tumble turn performance in swimming. Procedia Engineering, 2010, 2, 3391-3396. New lifecycle monitoring system for electronic manufacturing with embedded wireless components.	3.6	20 18 15
11 12 13 14	Geometric Optimisation of Electroadhesive Actuators Based on 3D Electrostatic Simulation and its Experimental Verification. IFAC-PapersOnLine, 2016, 49, 309-315. Autonomous metrology for robot mounted 3D vision systems. CIRP Annals - Manufacturing Technology, 2017, 66, 483-486. Dynamic signature for tumble turn performance in swimming. Procedia Engineering, 2010, 2, 3391-3396. New lifecycle monitoring system for electronic manufacturing with embedded wireless components. Circuit World, 2010, 36, 33-39.	3.6 1.2 0.9	20 18 15
11 12 13 14	Geometric Optimisation of Electroadhesive Actuators Based on 3D Electrostatic Simulation and its Experimental Verification. IFAC-PapersOnLine, 2016, 49, 309-315. Autonomous metrology for robot mounted 3D vision systems. CIRP Annals - Manufacturing Technology, 2017, 66, 483-486. Dynamic signature for tumble turn performance in swimming. Procedia Engineering, 2010, 2, 3391-3396. New lifecycle monitoring system for electronic manufacturing with embedded wireless components. Circuit World, 2010, 36, 33-39. The development of an inexpensive passive marker system for the analysis of starts and turns in swimming. Procedia Engineering, 2010, 2, 2727-2733. Three-dimensional vision analysis to measure the release characteristics of elite bowlers in cricket. Proceedings of the Institution of Mechanical Engineers, Part P: Journal of Sports Engineering and	3.6 1.2 0.9	20 18 15 12

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19	Novel metrics and methodology for the characterisation of 3D imaging systems. Optics and Lasers in Engineering, 2017, 91, 169-177.	3.8	9
20	Quantification of the Cricket Bowling Delivery; a Study of Elite Players to Gauge Variability and Controllability., 2006,, 205-210.		9
21	Human skill capture: A Hidden Markov Model of force and torque data in peg-in-a-hole assembly process. , 2016, , .		7
22	Virtual Reality Study of Human Adaptability in Industrial Human-Robot Collaboration. , 2020, , .		7
23	From Light to Displacement: A Design Framework for Optimising Spectral-Domain Low-Coherence Interferometric Sensors for In Situ Measurement. Applied Sciences (Switzerland), 2020, 10, 8590.	2.5	6
24	A Multi-sensor System for Monitoring the Performance of Elite Swimmers. Communications in Computer and Information Science, 2012, , 350-362.	0.5	6
25	Symmetrical electroadhesives independent of different interfacial surface conditions. Applied Physics Letters, 2017, 111, .	3.3	5
26	Batter's behaviour during training when facing a bowling machine and when facing a bowler. Proceedings of the Institution of Mechanical Engineers, Part P: Journal of Sports Engineering and Technology, 2010, 224, 201-208.	0.7	4
27	A Comparison of the Manufacturing Resilience between Fixed Automation Systems and Mobile Robots in Large Structure Assembly. Procedia CIRP, 2016, 57, 235-240.	1.9	4
28	Design and development of a novel, integrated bowling machine for cricket. Proceedings of the Institution of Mechanical Engineers, Part P: Journal of Sports Engineering and Technology, 2009, 223, 125-137.	0.7	3
29	Characterizing the influence of surface roughness and inclination on 3D vision sensor performance. , 2015, , .		3
30	Pragmatic Micrometre to Millimetre Calibration Using Multiple Methods for Low-Coherence Interferometer in Embedded Metrology Applications. Sensors, 2021, 21, 5101.	3.8	3
31	A Self-organisation Model for Mobile Robots in Large Structure Assembly Using Multi-agent Systems. Studies in Computational Intelligence, 2017, , 83-91.	0.9	3
32	Performance evaluation of a three dimensional laser scanner for industrial applications. , 2014, , .		2
33	Dynamic vs dedicated automation systems - a study in large structure assembly. Production and Manufacturing Research, 2020, 8, 35-58.	1.5	1
34	Use of the quality function deployment methodology in the development of a novel training system for cricket. Proceedings of the Institution of Mechanical Engineers, Part P: Journal of Sports Engineering and Technology, 2008, 222, 103-112.	0.7	0
35	The development of a novel cricket bowling system: recreating spin and swing bowling deliveries at the elite level. Journal of Physics: Conference Series, 2008, 105, 012003.	0.4	0
36	Development of an Optimised Dataset for Training a Deep Neural Network. Advances in Transdisciplinary Engineering, 2021, , .	0.1	0

#	Article	lF	CITATIONS
37	Engineering a Device which Imparts Spin onto a Cricket Ball. , 2007, , .		O
38	Investigating the optimisation of real-world and synthetic object detection training datasets through the consideration of environmental and simulation factors. Intelligent Systems With Applications, 2022, , 200079.	3.0	O