

Peng Han

List of Publications by Year in descending order

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2682572

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citing authors

#	ARTICLE	IF	CITATIONS
1	Quantitative Ground Risk Assessment for Urban Logistical Unmanned Aerial Vehicle (UAV) Based on Bayesian Network. Sustainability, 2022, 14, 5733.	3.2	8
2	Path Planning and Trajectory Tracking Strategy of Autonomous Vehicles. Mathematical Problems in Engineering, 2021, 2021, 1-11.	1.1	4
3	Trajectory tracking method based on the circulation of feasible path planning. PLoS ONE, 2021, 16, e0252542.	2.5	1