## Maopeng Ran

List of Publications by Year in descending order

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MAODENC RAN

#	Article	IF	CITATIONS
1	Stabilization of a class of nonlinear systems with actuator saturation via active disturbance rejection control. Automatica, 2016, 63, 302-310.	5.0	142
2	Active Disturbance Rejection Control for Uncertain Nonaffine-in-Control Nonlinear Systems. IEEE Transactions on Automatic Control, 2017, 62, 5830-5836.	5.7	87
3	Active disturbance rejection control for uncertain time-delay nonlinear systems. Automatica, 2020, 112, 108692.	5.0	70
4	Backstepping design of missile guidance and control based on adaptive fuzzy sliding mode control. Chinese Journal of Aeronautics, 2014, 27, 634-642.	5.3	59
5	A new extended state observer for uncertain nonlinear systems. Automatica, 2021, 131, 109772.	5.0	48
6	Anti-windup design for uncertain nonlinear systems subject to actuator saturation and external disturbance. International Journal of Robust and Nonlinear Control, 2016, 26, 3421-3438.	3.7	40
7	Efficient Trajectory Planning for Multiple Non-Holonomic Mobile Robots via Prioritized Trajectory Optimization. IEEE Robotics and Automation Letters, 2021, 6, 405-412.	5.1	35
8	Robust partial integrated guidance and control for missiles via extended state observer. ISA Transactions, 2016, 65, 27-36.	5.7	31
9	Fully distributed time-varying formation tracking control for multiple quadrotor vehicles via finite-time convergent extended state observer. Chinese Journal of Aeronautics, 2020, 33, 2907-2920.	5.3	29
10	Backstepping active disturbance rejection control: a delayed activation approach. IET Control Theory and Applications, 2017, 11, 2336-2342.	2.1	22
11	On Finiteâ€īime Stabilization of Active Disturbance Rejection Control for Uncertain Nonlinear Systems. Asian Journal of Control, 2018, 20, 415-424.	3.0	22
12	MPC-based Unified Trajectory Planning and Tracking Control Approach for Automated Guided Vehicles. , 2019, , .		20
13	Reinforcement-Learning-Based Disturbance Rejection Control for Uncertain Nonlinear Systems. IEEE Transactions on Cybernetics, 2022, 52, 9621-9633.	9.5	16
14	Time-varying formation control for unmanned aerial vehicles with external disturbances. Transactions of the Institute of Measurement and Control, 2019, 41, 3777-3786.	1.7	15
15	An analysis and design method for a class of nonlinear systems with nested saturations. International Journal of Control, 2016, 89, 1711-1724.	1.9	14
16	A Behavior-Based Mobile Robot Navigation Method with Deep Reinforcement Learning. Unmanned Systems, 2021, 09, 201-209.	3.6	12
17	Multistage anti-windup design for linear systems with saturation nonlinearity: enlargement of the domain of attraction. Nonlinear Dynamics, 2015, 80, 1543-1555.	5.2	11
18	Practical output consensus of nonlinear heterogeneous multi-agent systems with limited data rate. Automatica, 2021, 129, 109624.	5.0	10

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MAOPENG RAN

#	Article	IF	CITATIONS
19	Improved particle swarm optimization approach to path planning of amphibious mouse robot. , 2011, , .		8
20	Stabilization of a class of switched uncertain systems by active disturbance rejection control. Transactions of the Institute of Measurement and Control, 2018, 40, 4421-4431.	1.7	6
21	Distributed output-feedback consensus control of multi-agent systems with dynamically changing directed interaction topologies. ISA Transactions, 2019, 85, 71-75.	5.7	6
22	Data rate for output feedback consensus of uncertain nonlinear multiagent systems. International Journal of Robust and Nonlinear Control, 2020, 30, 5430-5445.	3.7	6
23	Extended State Observer Based Reinforcement Learning and Disturbance Rejection for Uncertain Nonlinear Systems. , 2020, , .		6
24	Adaptive Observation-Based Efficient Reinforcement Learning for Uncertain Systems. IEEE Transactions on Neural Networks and Learning Systems, 2022, 33, 5492-5503.	11.3	5
25	Design and Experimental Evaluation of a Hierarchical Controller for an Autonomous Ground Vehicle With Large Uncertainties. IEEE Transactions on Control Systems Technology, 2022, 30, 1215-1227.	5.2	5
26	Simultaneous anti-windup synthesis for linear systems subject to actuator saturation. Journal of Systems Engineering and Electronics, 2015, 26, 119-126.	2.2	4
27	Distributed Output Feedback Consensus of Uncertain Nonlinear Multi-Agent Systems With Limited Data Rate. , 2019, , .		4
28	Active Disturbance Rejection Time-Varying Formation Tracking for Unmanned Aerial Vehicles. , 2020, , .		4
29	Active disturbance rejection consensus control of uncertain high-order nonlinear multi-agent systems. Transactions of the Institute of Measurement and Control, 2020, 42, 604-617.	1.7	3
30	Integrated design of missile guidance and control: Active disturbance rejection control method. , 2014, , .		2
31	Fast Loop Closure Detection via Binary Content. , 2019, , .		2
32	Output tracking for nonlinear systems subject to unmodeled sluggish actuator dynamics via model-based extended state observer. ISA Transactions, 2022, 125, 198-211.	5.7	2
33	An Improved Antiwindup Design Using an Anticipatory Loop and an Immediate Loop. Mathematical Problems in Engineering, 2014, 2014, 1-9.	1.1	0
34	Simultaneous multi-stage anti-windup synthesis for open-loop stable plants. Transactions of the Institute of Measurement and Control, 2015, 37, 560-568.	1.7	0
35	Reply to "Comments on â€~Stabilization of a class of nonlinear systems with actuator saturation via active disturbance rejection control' [Automatica 63 (2016) 302–310]― Automatica, 2017, 83, 399. 	5.0	0
36	Recognition and simulation of parachute action based on continuous hidden Markov model. , 2017, , .		0

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#	Article	IF	CITATIONS
37	Observer-based Sliding Mode Fault-Tolerant Control for Spacecraft Attitude System with Actuator Faults. , 2019, , .		Ο

Predictive ESO design for Manned Mars Landing. , 2020, , .