## Zhen Liu

## List of Publications by Year in descending order

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623734 642732 29 530 14 23 citations h-index g-index papers 29 29 29 476 docs citations citing authors all docs times ranked

#	Article	IF	CITATIONS
1	Simple and fast rail wear measurement method based on structured light. Optics and Lasers in Engineering, 2011, 49, 1343-1351.	3.8	83
2	Calibration method for line-structured light vision sensor based on a single ball target. Optics and Lasers in Engineering, 2015, 69, 20-28.	3.8	66
3	High-accuracy calibration of low-cost camera using image disturbance factor. Optics Express, 2016, 24, 24321.	3.4	40
4	On-site calibration of line-structured light vision sensor in complex light environments. Optics Express, 2015, 23, 29896.	3.4	31
5	A Novel Stereo Vision Measurement System Using Both Line Scan Camera and Frame Camera. IEEE Transactions on Instrumentation and Measurement, 2019, 68, 3563-3575.	4.7	27
6	Automatic Fault Detection of Multiple Targets in Railway Maintenance Based on Time-Scale Normalization. IEEE Transactions on Instrumentation and Measurement, 2018, 67, 849-865.	4.7	26
7	Accurate camera calibration with distortion models using sphere images. Optics and Laser Technology, 2015, 65, 83-87.	4.6	24
8	Robust object tracking via multi-cue fusion. Signal Processing, 2017, 139, 86-95.	3.7	23
9	High-accuracy calibration of line-structured light vision sensor by correction of image deviation. Optics Express, 2019, 27, 4364.	3.4	20
10	Dynamic tread wear measurement method for train wheels against vibrations. Applied Optics, 2015, 54, 5270.	2.1	19
11	On-Site Reliable Wheel Size Measurement Based on Multisensor Data Fusion. IEEE Transactions on Instrumentation and Measurement, 2019, 68, 4575-4589.	4.7	17
12	Novel Multistate Fault Diagnosis and Location Method for Key Components of High-Speed Trains. IEEE Transactions on Industrial Electronics, 2021, 68, 3537-3547.	7.9	17
13	PAC Interaction Inspection Using Real-Time Contact Point Tracking. IEEE Transactions on Instrumentation and Measurement, 2019, 68, 4051-4064.	4.7	16
14	Robust Method for Measuring the Position and Orientation of Drogue Based on Stereo Vision. IEEE Transactions on Industrial Electronics, 2021, 68, 4298-4308.	7.9	16
15	Automatic Wear Measurement of Pantograph Slider Based on Multiview Analysis. IEEE Transactions on Industrial Informatics, 2021, 17, 3111-3121.	11.3	15
16	Flexible method of refraction correction in vision measurement systems with multiple glass ports. Optics Express, 2017, 25, 831.	3.4	11
17	Line Structured-Light Vision Sensor Calibration Based on Multi-Tooth Free-Moving Target and Its Application in Railway Fields. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 5762-5771.	8.0	11
18	Automatic visual inspection of a missing split pin in the China railway high-speed. Applied Optics, 2016, 55, 8395.	2.1	11

#	Article	IF	Citations
19	Fast and Flexible Movable Vision Measurement for the Surface of a Large-Sized Object. Sensors, 2015, 15, 4643-4657.	3.8	10
20	A Robust 3-D Abrasion Diagnosis Method of Pantograph Slipper Based on Stereo Vision. IEEE Transactions on Instrumentation and Measurement, 2020, 69, 9072-9086.	4.7	8
21	A Novel Subpixel Edge Detection Method of Pantograph Slide in Complicated Surroundings. IEEE Transactions on Industrial Electronics, 2022, 69, 3172-3182.	7.9	7
22	Reliable and Accurate Wheel Size Measurement under Highly Reflective Conditions. Sensors, 2018, 18, 4296.	3.8	6
23	Tracking and Position of Drogue for Autonomous Aerial Refueling. , 2018, , .		6
24	Target Tracking Based on Multiparameter Adaptive Adjustment for Autonomous Aerial Refueling. IEEE Transactions on Instrumentation and Measurement, 2021, 70, 1-13.	4.7	6
25	A Pantograph Horn Detection Method Based on Deep Learning Network. , 2018, , .		5
26	On-line Detection of Pantograph Offset Based on Deep Learning. , 2018, , .		4
27	Barcode detection and decoding method based on deep learning. , 2019, , .		4
28	Vision Sensor for Measuring Aerial Refueling Drogue Using Robust Method. IEEE Sensors Journal, 2021, 21, 28037-28049.	4.7	1
29	Pose Measurement for Unmanned Aerial Vehicle Based on Rigid Skeleton. Applied Sciences (Switzerland), 2021, 11, 1373.	2.5	O