

Luo Xinbin

List of Publications by Year in descending order

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Version: 2024-02-01

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papers

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citations

1684188

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17
docs citations

17
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59
citing authors

#	ARTICLE	IF	CITATIONS
1	Learning efficient single stage pedestrian detection by squeeze-and-excitation network. Neural Computing and Applications, 2021, 33, 16697-16712.	5.6	6
2	Multi-task non-negative matrix factorization for visual object tracking. Pattern Analysis and Applications, 2020, 23, 493-507.	4.6	1
3	UAV tracking based on saliency detection. Soft Computing, 2020, 24, 12149-12162.	3.6	2
4	Robust visual tracking via part-based model. Multimedia Systems, 2020, 26, 607-620.	4.7	2
5	Robust visual tracking via a hybrid correlation filter. Multimedia Tools and Applications, 2019, 78, 31633-31648.	3.9	9
6	Robust visual tracking based on response stability. Engineering Applications of Artificial Intelligence, 2019, 85, 137-149.	8.1	4
7	Multi-scale predictions fusion for robust hand detection and classification. Multimedia Tools and Applications, 2019, 78, 35633-35650.	3.9	3
8	Adaptive sampling for UAV tracking. Neural Computing and Applications, 2019, 31, 5029-5043.	5.6	6
9	Object tracking via dense SIFT features and low-rank representation. Soft Computing, 2019, 23, 10173-10186.	3.6	5
10	Collaborative model based UAV tracking via local kernel feature. Applied Soft Computing Journal, 2018, 72, 90-107.	7.2	5
11	Multi-task based object tracking via a collaborative model. Journal of Visual Communication and Image Representation, 2018, 55, 698-710.	2.8	0
12	Visual tracking via robust multi-task multi-feature joint sparse representation. Multimedia Tools and Applications, 2018, 77, 31447-31467.	3.9	9
13	Visual tracking via robust multi-task multi-feature joint sparse representation. , 2018, 77, 31447.		1
14	Robust object tracking via multi-task based collaborative model. , 2017, , .		1
15	Context multi-task visual object tracking via guided filter. , 2017, , .		1
16	Visual tracking via multi-task non-negative matrix factorization. , 2016, , .		2
17	Visual tracking via robust multi-task multi-feature joint sparse representation. , 2016, , .		1