

Young Sam Lee

List of Publications by Year in descending order

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17

papers

1,906

citations

1040056

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940533

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docs citations

17

times ranked

965

citing authors

#	ARTICLE	IF	CITATIONS
1	Adaptive Model-Free Control With Nonsingular Terminal Sliding-Mode for Application to Robot Manipulators. <i>IEEE Access</i> , 2020, 8, 169897-169907.	4.2	13
2	A Low-Cost Surge Current Detection Sensor with Predictive Lifetime Display Function for Maintenance of Surge Protective Devices. <i>Sensors</i> , 2020, 20, 2310.	3.8	7
3	Implementation of Mass-Independent Impedance Control for RFSEA Using a Linkage Arm. <i>IEEE Access</i> , 2019, 7, 104823-104832.	4.2	1
4	A New Submersion Detection Sensor Using Two Resistance Temperature Detectors Operating on the Thermal Equilibrium Principle. <i>Sensors</i> , 2019, 19, 4310.	3.8	4
5	Embedded Model Predictive Control for Enhancing Tracking Performance of a Ball-and-Plate System. <i>IEEE Access</i> , 2019, 7, 39652-39659.	4.2	17
6	Implementation of a Ball and Plate Control System Using Sliding Mode Control. <i>IEEE Access</i> , 2018, 6, 32401-32408.	4.2	36
7	A Light-Weight Rapid Control Prototyping System Based on Open Source Hardware. <i>IEEE Access</i> , 2017, 5, 11118-11130.	4.2	9
8	Path planning using flexible region sampling for arbitrarily-shaped obstacles. , 2017, ..		0
9	An Improved Receding Horizon Control for Time-Delay Systems. <i>Journal of Optimization Theory and Applications</i> , 2015, 165, 627-638.	1.5	9
10	Explicit input and output feedback control for discrete-time systems. <i>International Journal of Control, Automation and Systems</i> , 2013, 11, 482-488.	2.7	1
11	Receding Horizon $\langle \text{mml:math} \text{ xmlns:mml="http://www.w3.org/1998/Math/MathML" id="M1"} \rangle \langle \text{mml:mrow} \rangle \langle \text{mml:msub} \rangle \langle \text{mml:mi} \rangle H \langle / \text{mml:mi} \rangle \langle \text{mml:mi} \rangle \hat{x} \langle / \text{mml:mi} \rangle \langle / \text{mml:msub} \rangle \langle / \text{mml:mrow} \rangle \langle / \text{mml:math} \rangle$ Control for Input-Delayed Systems. <i>Mathematical Problems in Engineering</i> , 2012, 2012, 1-15.		
12	Constrained receding horizon controls for nonlinear time-delay systems. <i>Nonlinear Dynamics</i> , 2012, 69, 149-158.	5.2	8
13	Swing-up control for an inverted pendulum with restricted cart rail length. <i>International Journal of Control, Automation and Systems</i> , 2009, 7, 674-680.	2.7	32
14	RECEDING HORIZON $H\hat{x}$ CONTROL FOR SYSTEMS WITH A STATE-DELAY. <i>Asian Journal of Control</i> , 2008, 8, 63-71.	3.0	16
15	Maximum allowable delay bounds of networked control systems. <i>Control Engineering Practice</i> , 2003, 11, 1301-1313.	5.5	332
16	A simple receding horizon control for state delayed systems and its stability criterion. <i>Journal of Process Control</i> , 2003, 13, 539-551.	3.3	50
17	Delay-dependent robust stabilization of uncertain state-delayed systems. <i>International Journal of Control</i> , 2001, 74, 1447-1455.	1.9	1,370