

# Rafael Arrais

## List of Publications by Citations

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

10  
papers

30  
citations

3  
h-index

5  
g-index

12  
ext. papers

53  
ext. citations

2.2  
avg, IF

1.57  
L-index

#	Paper	IF	Citations
10	Mining the usage patterns of ROS primitives <b>2017</b> ,		9
9	A mobile robot based sensing approach for assessing spatial inconsistencies of a logistic system. <i>Journal of Manufacturing Systems</i> , <b>2017</b> , 43, 129-138	9.1	7
8	Application of the Open Scalable Production System to Machine Tending of Additive Manufacturing Operations by a Mobile Manipulator. <i>Lecture Notes in Computer Science</i> , <b>2019</b> , 345-356	0.9	5
7	Enhancement of Industrial Logistic Systems with Semantic 3D Representations for Mobile Manipulators. <i>Advances in Intelligent Systems and Computing</i> , <b>2018</b> , 617-628	0.4	3
6	On the development of a collaborative robotic system for industrial coating cells. <i>International Journal of Advanced Manufacturing Technology</i> , <b>2020</b> , 115, 853	3.2	2
5	ROBIN: An open-source middleware for plug-and-produce of Cyber-Physical Systems. <i>International Journal of Advanced Robotic Systems</i> , <b>2020</b> , 17, 172988142091031	1.4	2
4	Autonomous Scene Exploration for Robotics: A Conditional Random View-Sampling and Evaluation Using a Voxel-Sorting Mechanism for Efficient Ray Casting. <i>Sensors</i> , <b>2020</b> , 20,	3.8	1
3	FASTEN: EU-Brazil cooperation in IoT for manufacturing. The Embraer use. <i>MATEC Web of Conferences</i> , <b>2019</b> , 304, 04007	0.3	1
2	A Predictive Simulation and Optimization Architecture based on a Knowledge Engineering User Interface to Support Operator 4.0. <i>IFAC-PapersOnLine</i> , <b>2021</b> , 54, 331-336	0.7	
1	A Hybrid Top-Down Bottom-Up Approach for the Detection of Cuboid Shaped Objects. <i>Lecture Notes in Computer Science</i> , <b>2016</b> , 512-520	0.9	