

Boris I Prilutsky

List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/7419774/publications.pdf>

Version: 2024-02-01

77
papers

2,541
citations

172386

29
h-index

206029

48
g-index

79
all docs

79
docs citations

79
times ranked

1901
citing authors

#	ARTICLE	IF	CITATIONS
1	State- and Condition-Dependent Modulation of the Hindlimb Locomotor Pattern in Intact and Spinal Cats Across Speeds. <i>Frontiers in Systems Neuroscience</i> , 2022, 16, 814028.	1.2	7
2	Emergence of Extreme Paw Accelerations During Cat Paw Shaking: Interactions of Spinal Central Pattern Generator, Hindlimb Mechanics and Muscle Length-Depended Feedback. <i>Frontiers in Integrative Neuroscience</i> , 2022, 16, 810139.	1.0	0
3	Control of Forelimb and Hindlimb Movements and Their Coordination during Quadrupedal Locomotion across Speeds in Adult Spinal Cats. <i>Journal of Neurotrauma</i> , 2022, 39, 1113-1131.	1.7	7
4	The Spinal Control of Backward Locomotion. <i>Journal of Neuroscience</i> , 2021, 41, 630-647.	1.7	22
5	Recent Progress in Animal Studies of the Skin- and Bone-integrated Pylon With Deep Porosity for Bone-Anchored Limb Prosthetics With and Without Neural Interface. <i>Military Medicine</i> , 2021, 186, 688-695.	0.4	4
6	How to distinguish between referent configuration and internal models hypotheses of motor control?. <i>Physics of Life Reviews</i> , 2021, 37, 1-2.	1.5	2
7	Design and Preliminary Evaluation of a Tongue-Operated Exoskeleton System for Upper Limb Rehabilitation. <i>International Journal of Environmental Research and Public Health</i> , 2021, 18, 8708.	1.2	4
8	Common and distinct muscle synergies during level and slope locomotion in the cat. <i>Journal of Neurophysiology</i> , 2021, 126, 493-515.	0.9	9
9	Control of Mammalian Locomotion by Somatosensory Feedback. , 2021, 12, 2877-2947.		32
10	Asymmetric and transient properties of reciprocal activity of antagonists during the paw-shake response in the cat. <i>PLoS Computational Biology</i> , 2021, 17, e1009677.	1.5	1
11	Adaptation to slope in locomotor-trained spinal cats with intact and self-reinnervated lateral gastrocnemius and soleus muscles. <i>Journal of Neurophysiology</i> , 2020, 123, 70-89.	0.9	7
12	Frontal plane dynamics of the centre of mass during quadrupedal locomotion on a split-belt treadmill. <i>Journal of the Royal Society Interface</i> , 2020, 17, 20200547.	1.5	6
13	Cutaneous sensory feedback from paw pads affects lateral balance control during split-belt locomotion in the cat. <i>Journal of Experimental Biology</i> , 2019, 222, .	0.8	14
14	Effects of bilateral swing-away grab bars on the biomechanics of stand-to-sit and sit-to-stand toilet transfers. <i>Disability and Rehabilitation: Assistive Technology</i> , 2019, 14, 292-300.	1.3	5
15	Time course of functional recovery during the first 3 mo after surgical transection and repair of nerves to the feline soleus and lateral gastrocnemius muscles. <i>Journal of Neurophysiology</i> , 2018, 119, 1166-1185.	0.9	9
16	Control of transitions between locomotor-like and paw shake-like rhythms in a model of a multistable central pattern generator. <i>Journal of Neurophysiology</i> , 2018, 120, 1074-1089.	0.9	16
17	Kinetics of individual limbs during level and slope walking with a unilateral transtibial bone-anchored prosthesis in the cat. <i>Journal of Biomechanics</i> , 2018, 76, 74-83.	0.9	12
18	A Prototype of a Neural, Powered, Transtibial Prosthesis for the Cat: Benchtop Characterization. <i>Frontiers in Neuroscience</i> , 2018, 12, 471.	1.4	7

#	ARTICLE	IF	CITATIONS
19	Self-reinnervated muscles lose autogenic length feedback, but intermuscular feedback can recover functional connectivity. <i>Journal of Neurophysiology</i> , 2016, 116, 1055-1067.	0.9	19
20	A real-time closed-loop control system for modulating gait characteristics via electrical stimulation of peripheral nerves. , 2016, , .		11
21	Increased intensity and reduced frequency of EMG signals from feline self-reinnervated ankle extensors during walking do not normalize excessive lengthening. <i>Journal of Neurophysiology</i> , 2016, 115, 2406-2420.	0.9	11
22	Computing Motion Dependent Afferent Activity During Cat Locomotion Using a Forward Dynamics Musculoskeletal Model. <i>Springer Series in Computational Neuroscience</i> , 2016, , 273-307.	0.3	7
23	A Neuromechanical Model of Spinal Control of Locomotion. <i>Springer Series in Computational Neuroscience</i> , 2016, , 21-65.	0.3	35
24	Modeling the Organization of Spinal Cord Neural Circuits Controlling Two-Joint Muscles. <i>Springer Series in Computational Neuroscience</i> , 2016, , 121-162.	0.3	8
25	Control of Cat Walking and Paw-Shake by a Multifunctional Central Pattern Generator. <i>Springer Series in Computational Neuroscience</i> , 2016, , 333-359.	0.3	7
26	Accurate stepping on a narrow path: mechanics, EMG, and motor cortex activity in the cat. <i>Journal of Neurophysiology</i> , 2015, 114, 2682-2702.	0.9	20
27	Unexpected Fascicle Length Changes In Denervated Feline Soleus Muscle During Stance Phase Of Walking. <i>Scientific Reports</i> , 2015, 5, 17619.	1.6	3
28	Task-dependent inhibition of slow-twitch soleus and excitation of fast-twitch gastrocnemius do not require high movement speed and velocity-dependent sensory feedback. <i>Frontiers in Physiology</i> , 2014, 5, 410.	1.3	10
29	Effects of pore size, implantation time, and nano-surface properties on rat skin ingrowth into percutaneous porous titanium implants. <i>Journal of Biomedical Materials Research - Part A</i> , 2014, 102, 1305-1315.	2.1	34
30	Stabilization of cat paw trajectory during locomotion. <i>Journal of Neurophysiology</i> , 2014, 112, 1376-1391.	0.9	21
31	Motor adaptation to prosthetic cycling in people with trans-tibial amputation. <i>Journal of Biomechanics</i> , 2014, 47, 2306-2313.	0.9	16
32	Body stability and muscle and motor cortex activity during walking with wide stance. <i>Journal of Neurophysiology</i> , 2014, 112, 504-524.	0.9	38
33	Multifunctional central pattern generator controlling walking and paw shaking. <i>BMC Neuroscience</i> , 2014, 15, P181.	0.8	1
34	An animal model to evaluate skin-implant-bone integration and gait with a prosthesis directly attached to the residual limb. <i>Clinical Biomechanics</i> , 2014, 29, 336-349.	0.5	20
35	Does ankle joint power reflect type of muscle action of soleus and gastrocnemius during walking in cats and humans?. <i>Journal of Biomechanics</i> , 2013, 46, 1383-1386.	0.9	26
36	The effect of force feedback on transfer of learning between the arms during bimanual reaching. , 2013, 2013, 6885-8.		0

#	ARTICLE	IF	CITATIONS
37	The effect of the direction of force-fields on transfer of learning between the arms during bimanual reaching. , 2013, 2013, 6889-92.		1
38	Task dependent activity of motor unit populations in feline ankle extensor muscles. Journal of Experimental Biology, 2012, 215, 3711-22.	0.8	11
39	Motoneuronal and muscle synergies involved in cat hindlimb control during fictive and real locomotion: a comparison study. Journal of Neurophysiology, 2012, 107, 2057-2071.	0.9	63
40	Stance and swing phase detection during level and slope walking in the cat: Effects of slope, injury, subject and kinematic detection method. Journal of Biomechanics, 2012, 45, 1529-1533.	0.9	23
41	Transfer of learning between the arms during bimanual reaching. , 2012, 2012, 6785-8.		5
42	A dynamical systems analysis of afferent control in a neuromechanical model of locomotion: I. Rhythm generation. Journal of Neural Engineering, 2011, 8, 065003.	1.8	41
43	A dynamical systems analysis of afferent control in a neuromechanical model of locomotion: II. Phase asymmetry. Journal of Neural Engineering, 2011, 8, 065004.	1.8	31
44	Short-Term Motor Compensations to Denervation of Feline Soleus and Lateral Gastrocnemius Result in Preservation of Ankle Mechanical Output during Locomotion. Cells Tissues Organs, 2011, 193, 310-324.	1.3	36
45	Electrical stimulation of the sural cutaneous afferent nerve controls the amplitude and onset of the swing phase of locomotion in the spinal cat. Journal of Neurophysiology, 2011, 105, 2297-2308.	0.9	18
46	Motor Control and Motor Redundancy in the Upper Extremity: Implications for Neurorehabilitation. Topics in Spinal Cord Injury Rehabilitation, 2011, 17, 7-15.	0.8	6
47	Modeling the CPG-based Control of Cat Hindlimb Movement During Locomotion. FASEB Journal, 2011, 25, 1046.1.	0.2	0
48	Comments on Point:Counterpoint: Afferent feedback from fatigued locomotor muscles is/is not an important determinant of endurance exercise performance. Journal of Applied Physiology, 2010, 108, 458-468.	1.2	26
49	Locomotor changes in length and EMG activity of feline medial gastrocnemius muscle following paralysis of two synergists. Experimental Brain Research, 2010, 203, 681-692.	0.7	29
50	Differences in Movement Mechanics, Electromyographic, and Motor Cortex Activity Between Accurate and Nonaccurate Stepping. Journal of Neurophysiology, 2010, 103, 2285-2300.	0.9	60
51	Afferent control of locomotor CPG: insights from a simple neuromechanical model. Annals of the New York Academy of Sciences, 2010, 1198, 21-34.	1.8	93
52	Control of Locomotion. , 2010, , 197-218.		0
53	Gains in Upper Extremity Function After Stroke via Recovery or Compensation: Potential Differential Effects on Amount of Real-World Limb Use. Topics in Stroke Rehabilitation, 2009, 16, 237-253.	1.0	135
54	Distinct muscle fascicle length changes in feline medial gastrocnemius and soleus muscles during slope walking. Journal of Applied Physiology, 2009, 106, 1169-1180.	1.2	38

#	ARTICLE	IF	CITATIONS
55	Mathematical modeling and mechanical and histopathological testing of porous prosthetic pylon for direct skeletal attachment. <i>Journal of Rehabilitation Research and Development</i> , 2009, 46, 315.	1.6	19
56	The effects of self-reinnervation of cat medial and lateral gastrocnemius muscles on hindlimb kinematics in slope walking. <i>Experimental Brain Research</i> , 2007, 181, 377-393.	0.7	65
57	Mechanics of Slope Walking in the Cat: Quantification of Muscle Load, Length Change, and Ankle Extensor EMG Patterns. <i>Journal of Neurophysiology</i> , 2006, 95, 1397-1409.	0.9	102
58	A numerical procedure for inferring from experimental data the optimization cost functions using a multibody model of the neuro-musculoskeletal system. <i>Multibody System Dynamics</i> , 2006, 16, 123-154.	1.7	54
59	A Method for Inferring the Optimization Cost Function of Experimentally Observed Motor Strategies. , 2005, , 367.		1
60	Quantification of Motor Cortex Activity and Full-Body Biomechanics During Unconstrained Locomotion. <i>Journal of Neurophysiology</i> , 2005, 94, 2959-2969.	0.9	64
61	Optimization-Based Models of Muscle Coordination. <i>Exercise and Sport Sciences Reviews</i> , 2002, 30, 32-38.	1.6	188
62	Authors'™ response <i>Journal of Biomechanics - Volume 35, Issue 10</i> . <i>Journal of Biomechanics</i> , 2002, 35, 1437-1438.	0.9	1
63	Hindlimb Kinetics and Neural Control during Slope Walking in the Cat: Unexpected Findings. <i>Journal of Applied Biomechanics</i> , 2001, 17, 277-286.	0.3	17
64	Sensitivity of predicted muscle forces to parameters of the optimization-based human leg model revealed by analytical and numerical analyses. <i>Journal of Biomechanics</i> , 2001, 34, 1243-1255.	0.9	124
65	Swing- and support-related muscle actions differentially trigger human walk"run and run"walk transitions. <i>Journal of Experimental Biology</i> , 2001, 204, 2277-2287.	0.8	137
66	Muscle Coordination: The Discussion Continues. <i>Motor Control</i> , 2000, 4, 97-116.	0.3	52
67	Analysis of muscle coordination strategies in cycling. <i>IEEE Transactions on Rehabilitation Engineering: A Publication of the IEEE Engineering in Medicine and Biology Society</i> , 2000, 8, 362-370.	1.4	77
68	Is coordination of two-joint leg muscles during load lifting consistent with the strategy of minimum fatigue?. <i>Journal of Biomechanics</i> , 1998, 31, 1025-1034.	0.9	42
69	Coordination of two-joint rectus femoris and hamstrings during the swing phase of human walking and running. <i>Experimental Brain Research</i> , 1998, 120, 479-486.	0.7	71
70	Strategy of Coordination of Two- and One-Joint Leg Muscles in Controlling an External Force. <i>Motor Control</i> , 1997, 1, 92-116.	0.3	31
71	Forces of individual cat ankle extensor muscles during locomotion predicted using static optimization. <i>Journal of Biomechanics</i> , 1997, 30, 1025-1033.	0.9	43
72	Transfer of mechanical energy between ankle and knee joints by gastrocnemius and plantaris muscles during cat locomotion. <i>Journal of Biomechanics</i> , 1996, 29, 391-403.	0.9	45

#	ARTICLE	IF	CITATIONS
73	Comparison of mechanical energy expenditure of joint moments and muscle forces during human locomotion. <i>Journal of Biomechanics</i> , 1996, 29, 405-415.	0.9	60
74	Role of the muscle belly and tendon of soleus, gastrocnemius, and plantaris in mechanical energy absorption and generation during cat locomotion. <i>Journal of Biomechanics</i> , 1996, 29, 417-434.	0.9	31
75	Comments on the relationship between ankle muscle and joint kinetics during the stance phase of locomotion in the cat. <i>Journal of Biomechanics</i> , 1995, 28, 643-644.	0.9	0
76	Tendon action of two-joint muscles: Transfer of mechanical energy between joints during jumping, landing, and running. <i>Journal of Biomechanics</i> , 1994, 27, 25-34.	0.9	209
77	Force-sharing between cat soleus and gastrocnemius muscles during walking: Explanations based on electrical activity, properties, and kinematics. <i>Journal of Biomechanics</i> , 1994, 27, 1223-1235.	0.9	30