

Suiyang Khoo

List of Publications by Year in descending order

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68
papers

3,231
citations

257450

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214800

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docs citations

68
times ranked

2832
citing authors

#	ARTICLE	IF	CITATIONS
1	A Probabilistic Model for Minimization of Solar Energy Operation Costs as Well as CO2 Emissions in a Multi-Carrier Microgrid (MCMG). <i>Energies</i> , 2022, 15, 3088.	3.1	2
2	A Linear Time-Varying Model Predictive Control-Based Motion Cueing Algorithm for Hexapod Simulation-Based Motion Platform. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021, 51, 6096-6110.	9.3	36
3	New Lyapunov conditions of stochastic finite-time stability and instability of nonlinear time-varying SDEs. <i>International Journal of Control</i> , 2021, 94, 1674-1681.	1.9	14
4	Energy trading among electric vehicles based on Stackelberg approaches: A review. <i>Sustainable Cities and Society</i> , 2021, 75, 103199.	10.4	18
5	Adaptive Neural Network Based Sliding Mode Control of Continuum Robots with Mismatched Uncertainties. , 2021, , .		2
6	Domain recurrence and probabilistic analysis of residence time of stochastic systems and domain aiming control. <i>International Journal of Robust and Nonlinear Control</i> , 2020, 30, 6585-6605.	3.7	3
7	The Performance of the DES Sensor for Estimating Soil Bulk Density under the Effect of Different Agronomic Practices. <i>Geosciences (Switzerland)</i> , 2020, 10, 117.	2.2	4
8	Multi-surface sliding mode control of continuum robots with mismatched uncertainties. <i>Meccanica</i> , 2019, 54, 2307-2316.	2.0	17
9	Generalized Lyapunov criteria on finite-time stability of stochastic nonlinear systems. <i>Automatica</i> , 2019, 107, 183-189.	5.0	78
10	Probability distribution of decay rate: a statistical time-domain damping parameter for structural damage identification. <i>Structural Health Monitoring</i> , 2019, 18, 66-86.	7.5	20
11	Robust control of continuum robots using Cosserat rod theory. <i>Mechanism and Machine Theory</i> , 2019, 131, 48-61.	4.5	62
12	Pattern-driven 4D printing. <i>Sensors and Actuators A: Physical</i> , 2018, 274, 231-243.	4.1	81
13	Intelligent control strategy in the islanded network of a solar PV microgrid. <i>Electric Power Systems Research</i> , 2018, 155, 93-103.	3.6	44
14	Robust H ∞ cost guaranteed integral sliding mode control for the synchronization problem of nonlinear tele-operation system with variable time-delay. <i>ISA Transactions</i> , 2018, 72, 25-36.	5.7	20
15	Soil Bulk Density Estimation Methods: A Review. <i>Pedosphere</i> , 2018, 28, 581-596.	4.0	193
16	Robust Control of Tendon Driven Continuum Robots. , 2018, , .		5
17	Modified DSC Propulsion Systems for Efficient Direct Recovery of Regeneration in 25-kV AC Traction Power Supply. <i>IEEE Transactions on Transportation Electrification</i> , 2017, 3, 632-645.	7.8	8
18	Finite-time stability theorems of homogeneous stochastic nonlinear systems. <i>Systems and Control Letters</i> , 2017, 100, 6-13.	2.3	52

#	ARTICLE	IF	CITATIONS
19	Finite-time stability of stochastic nonlinear systems with Markovian switching. , 2017, , .		1
20	Development and analysis of a 3D printed hydrogel soft actuator. Sensors and Actuators A: Physical, 2017, 265, 94-101.	4.1	62
21	Robust control of novel thrust vectored 3D printed multicopter. , 2017, , .		5
22	Evolution of 3D printed soft actuators. Sensors and Actuators A: Physical, 2016, 250, 258-272.	4.1	232
23	Robust finite-time tracking control of nonholonomic mobile robots without velocity measurements. International Journal of Control, 2016, 89, 411-423.	1.9	41
24	Continuous finite-time state feedback stabilizers for some nonlinear stochastic systems. International Journal of Robust and Nonlinear Control, 2015, 25, 1581-1600.	3.7	84
25	Stochastic Systems 2014. Mathematical Problems in Engineering, 2015, 2015, 1-3.	1.1	0
26	Multi-surface sliding control of MIMO autonomous flight systems. , 2015, , .		0
27	Modelling and simulation of regeneration in AC traction propulsion system of electrified railway. IET Electrical Systems in Transportation, 2015, 5, 145-155.	2.4	6
28	Some properties of finite-time stable stochastic nonlinear systems. Applied Mathematics and Computation, 2015, 259, 686-697.	2.2	20
29	Adaptive fuzzy multi-surface sliding control of multiple-input and multiple-output autonomous flight systems. IET Control Theory and Applications, 2015, 9, 587-597.	2.1	17
30	Global finite-time stabilisation for a class of stochastic nonlinear systems by output feedback. International Journal of Control, 2015, 88, 494-506.	1.9	66
31	Frequency-domain beamformers using conjugate gradient techniques for speech enhancement. Journal of the Acoustical Society of America, 2014, 136, 1160-1175.	1.1	4
32	Multi-surface sliding control of MIMO autonomous flight systems. , 2014, , .		0
33	Adaptive cruise control of a HEV using sliding mode control. Expert Systems With Applications, 2014, 41, 607-615.	7.6	80
34	New Variable Step-Sizes Minimizing Mean-Square Deviation for the LMS-Type Algorithms. Circuits, Systems, and Signal Processing, 2014, 33, 2251-2265.	2.0	11
35	Statistical modeling of gear vibration signals and its application to detecting and diagnosing gear faults. Information Sciences, 2014, 259, 295-303.	6.9	28
36	Multi-surface sliding control for fast finite-time leader-follower consensus with high order SISO uncertain nonlinear agents. International Journal of Robust and Nonlinear Control, 2014, 24, 2388-2404.	3.7	133

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37	DSP-Based Sliding-Mode Control for Electromagnetic-Levitation Precise-Position System. IEEE Transactions on Industrial Informatics, 2013, 9, 817-827.	11.3	57
38	An optimal weight learning machine for handwritten digit image recognition. Signal Processing, 2013, 93, 1624-1638.	3.7	31
39	Modeling and analysis of gear tooth crack growth under variable-amplitude loading. Mechanical Systems and Signal Processing, 2013, 40, 105-113.	8.0	12
40	Exact-estimator-based terminal sliding mode control system design. , 2013, , .		0
41	The oscillation behaviors in Euler discretized terminal sliding mode control systems. , 2013, , .		0
42	Finite-time stabilization of stochastic nonlinear systems in strict-feedback form. Automatica, 2013, 49, 1403-1410.	5.0	259
43	Stochastic Systems 2013. Mathematical Problems in Engineering, 2013, 2013, 1-2.	1.1	1
44	Backstepping-based current and voltage control strategy for maglev position device. , 2013, , .		0
45	A variable step-size transform-domain LMS algorithm based on minimum mean-square deviation for autoregressive process. , 2013, , .		0
46	FEM Calibrated ARMAX Model Updating Method for Time Domain Damage Identification. Advances in Structural Engineering, 2013, 16, 51-60.	2.4	12
47	Sliding mode-like learning control for SISO complex systems with T-S fuzzy models. International Journal of Modelling, Identification and Control, 2012, 16, 317.	0.2	15
48	Robust Single-Hidden Layer Feedforward Network-Based Pattern Classifier. IEEE Transactions on Neural Networks and Learning Systems, 2012, 23, 1974-1986.	11.3	39
49	Terminal sliding mode control strategy design for second-order nonlinear system. , 2012, , .		1
50	Adaptive fast finite-time multiple-surface sliding control for a class of uncertain non-linear systems. International Journal of Modelling, Identification and Control, 2012, 16, 392.	0.2	2
51	Optimal sinusoidal modelling of gear mesh vibration signals for gear diagnosis and prognosis. Mechanical Systems and Signal Processing, 2012, 33, 256-274.	8.0	27
52	Adaptive finite-time stabilization of a class of stochastic nonlinear systems. , 2012, , .		2
53	Finite-time stability and instability of stochastic nonlinear systems. Automatica, 2011, 47, 2671-2677.	5.0	394
54	Comments on "Finite-time stability theorem of stochastic nonlinear systems" [Automatica 46 (2010) 2105-2108]. Automatica, 2011, 47, 1542-1543.	5.0	20

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55	A finite-time stability theorem of stochastic nonlinear systems and stabilization designs. , 2011, , .		6
56	A new sliding mode-based learning control scheme. , 2011, , .		11
57	Adaptive data based neural network leader-follower control of multi-agent networks. , 2011, , .		1
58	A New Design of Sliding Mode Control Systems. Lecture Notes in Control and Information Sciences, 2011, , 151-167.	1.0	5
59	Leader-follower consensus control of a class of nonholonomic systems. , 2010, , .		5
60	Fast finite-time consensus of a class of high-order uncertain nonlinear systems. , 2010, , .		14
61	A class of modified variable step-size NLMS algorithms for system identification. , 2009, , .		1
62	Observer-based robust finite-time cooperative consensus control for multi-agent networks. , 2009, , .		9
63	Variable step-size LMS algorithm with a quotient form. Signal Processing, 2009, 89, 67-76.	3.7	53
64	A generalized data windowing scheme for adaptive conjugate gradient algorithms. Signal Processing, 2009, 89, 894-900.	3.7	7
65	Stability and Convergence Analysis of Transform-Domain LMS Adaptive Filters With Second-Order Autoregressive Process. IEEE Transactions on Signal Processing, 2009, 57, 119-130.	5.3	29
66	Robust Finite-Time Consensus Tracking Algorithm for Multirobot Systems. IEEE/ASME Transactions on Mechatronics, 2009, 14, 219-228.	5.8	735
67	Comments on "Adaptive multiple-surface sliding control for non-autonomous systems with mismatched uncertainties"; Automatica, 2008, 44, 2995-2998.	5.0	21
68	Finite-time consensus algorithm of multi-agent networks. , 2008, , .		13