## Xiaoyan Yu

## List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/7349065/publications.pdf

Version: 2024-02-01

1937685 1720034 79 9 4 7 citations h-index g-index papers 9 9 9 32 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Observer-based two-time scale robust control of free-flying flexible-joint space manipulators with external disturbances. Robotica, 2017, 35, 2201-2217.	1.9	25
2	Robust fuzzy sliding mode control and vibration suppression of free-floating flexible-link and flexible-joints space manipulator with external interference and uncertain parameter. Robotica, 2022, 40, 997-1019.	1.9	15
3	Hybrid-Trajectory Based Terminal Sliding Mode Control of a Flexible Space Manipulator with an Elastic Base. Robotica, 2020, 38, 550-563.	1.9	13
4	Buffer Compliance Control of Space Robots Capturing a Non-Cooperative Spacecraft Based on Reinforcement Learning. Applied Sciences (Switzerland), 2021, 11, 5783.	2.5	13
5	Dynamic modeling and control of a free-flying space robot with flexible-link and flexible-joints. , 2014, , .		7
6	Time delay estimation-based reactionless augmented adaptive sliding mode control of a space manipulator's pregrasping a target. Robotica, 2022, 40, 3136-3156.	1.9	3
7	Observer Based Robust Control and Vibration Control for a Free-floating flexible Space Manipulator. Jixie Gongcheng Xuebao/Chinese Journal of Mechanical Engineering, 2016, 52, 28.	0.5	2
8	Terminal Sliding Mode Adaptive Fuzzy Controller of a Free-Floating Space Manipulator Based on Time Delay Estimation. Mechanisms and Machine Science, 2020, , 440-449.	0.5	1
9	T-S Fuzzy Compensation Based Sliding Mode Control for a Free-Floating Space Manipulator. Mechanisms and Machine Science, 2020, , 419-429.	0.5	O