

# Juho-Pekka Virtanen

## List of Publications by Year in Descending Order

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

37  
papers

512  
citations

12  
h-index

21  
g-index

40  
ext. papers

692  
ext. citations

3.9  
avg, IF

3.77  
L-index

#	Paper	IF	Citations
37	3D Point Cloud Data in Conveying Information for Local Green Factor Assessment. <i>ISPRS International Journal of Geo-Information</i> , <b>2021</b> , 10, 762	2.9	0
36	Near Real-Time Semantic View Analysis of 3D City Models in Web Browser. <i>ISPRS International Journal of Geo-Information</i> , <b>2021</b> , 10, 138	2.9	3
35	Sense of presence and sense of place in perceiving a 3D geovisualization for communication in urban planning [Differences introduced by prior familiarity with the place. <i>Landscape and Urban Planning</i> , <b>2021</b> , 207, 103996	7.7	7
34	The Combined Use of SLAM Laser Scanning and TLS for the 3D Indoor Mapping. <i>Buildings</i> , <b>2021</b> , 11, 386	3.2	2
33	Humans use Optokinetic Eye Movements to Track Waypoints for Steering. <i>Scientific Reports</i> , <b>2020</b> , 10, 4175	4.9	7
32	A Simple Semantic-Based Data Storage Layout for Querying Point Clouds. <i>ISPRS International Journal of Geo-Information</i> , <b>2020</b> , 9, 72	2.9	2
31	Accurate derivation of stem curve and volume using backpack mobile laser scanning. <i>ISPRS Journal of Photogrammetry and Remote Sensing</i> , <b>2020</b> , 161, 246-262	11.8	33
30	A Comparison of Low-Cost Sensor Systems in Automatic Cloud-Based Indoor 3D Modeling. <i>Remote Sensing</i> , <b>2020</b> , 12, 2624	5	7
29	Evaluating the Quality of TLS Point Cloud Colorization. <i>Remote Sensing</i> , <b>2020</b> , 12, 2748	5	4
28	Nighttime Mobile Laser Scanning and 3D Luminance Measurement: Verifying the Outcome of Roadside Tree Pruning with Mobile Measurement of the Road Environment. <i>ISPRS International Journal of Geo-Information</i> , <b>2020</b> , 9, 455	2.9	1
27	Interactive dense point clouds in a game engine. <i>ISPRS Journal of Photogrammetry and Remote Sensing</i> , <b>2020</b> , 163, 375-389	11.8	8
26	Under-canopy UAV laser scanning for accurate forest field measurements. <i>ISPRS Journal of Photogrammetry and Remote Sensing</i> , <b>2020</b> , 164, 41-60	11.8	42
25	Automated Multi-Sensor 3D Reconstruction for the Web. <i>ISPRS International Journal of Geo-Information</i> , <b>2019</b> , 8, 221	2.9	13
24	Forest in situ observations using unmanned aerial vehicle as an alternative of terrestrial measurements. <i>Forest Ecosystems</i> , <b>2019</b> , 6,	3.8	53
23	Multisource Point Clouds, Point Simplification and Surface Reconstruction. <i>Remote Sensing</i> , <b>2019</b> , 11, 2659	5	8
22	The feasibility of using a low-cost depth camera for 3D scanning in mass customization. <i>Open Engineering</i> , <b>2019</b> , 9, 450-458	1.7	4
21	Depth camera indoor mapping for 3D virtual radio play. <i>Photogrammetric Record</i> , <b>2018</b> , 33, 171-195	1.7	9

20	Characterizing 3D City Modeling Projects: Towards a Harmonized Interoperable System. <i>ISPRS International Journal of Geo-Information</i> , <b>2018</b> , 7, 55	2.9	23
19	Feasibility of Google Tango and Kinect for Crowdsourcing Forestry Information. <i>Forests</i> , <b>2018</b> , 9, 6	2.8	34
18	Mobile mapping of night-time road environment lighting conditions <b>2018</b> , 26, 1-17		5
17	Browser based 3D for the built environment <b>2018</b> , 13, 54-76		4
16	Tutorial: Road Lighting for Efficient and Safe Traffic Environments. <i>LEUKOS - Journal of Illuminating Engineering Society of North America</i> , <b>2017</b> , 13, 223-241	3.5	12
15	Modern empirical and modelling study approaches in fluvial geomorphology to elucidate sub-bend-scale meander dynamics. <i>Progress in Physical Geography</i> , <b>2017</b> , 41, 533-569	3.5	27
14	Nationwide Point Cloud The Future Topographic Core Data. <i>ISPRS International Journal of Geo-Information</i> , <b>2017</b> , 6, 243	2.9	8
13	Comparison of the Selected State-Of-The-Art 3D Indoor Scanning and Point Cloud Generation Methods. <i>Remote Sensing</i> , <b>2017</b> , 9, 796	5	84
12	Camera preparation and performance for 3D luminance mapping of road environments <b>2017</b> , 25, 1-23		6
11	Localization of a mobile laser scanner via dimensional reduction. <i>ISPRS Journal of Photogrammetry and Remote Sensing</i> , <b>2016</b> , 121, 48-59	11.8	12
10	Localization of mobile laser scanner using classical mechanics. <i>ISPRS Journal of Photogrammetry and Remote Sensing</i> , <b>2015</b> , 99, 25-29	11.8	14
9	Intelligent Open Data 3D Maps in a Collaborative Virtual World. <i>ISPRS International Journal of Geo-Information</i> , <b>2015</b> , 4, 837-857	2.9	19
8	Determining Characteristic Vegetation Areas by Terrestrial Laser Scanning for Floodplain Flow Modeling. <i>Water (Switzerland)</i> , <b>2015</b> , 7, 420-437	3	30
7	Luminance-Corrected 3D Point Clouds for Road and Street Environments. <i>Remote Sensing</i> , <b>2015</b> , 7, 11389-11402		23
6	Customized Visualizations of Urban Infill Development Scenarios for Local Stakeholders. <i>Journal of Building Construction and Planning Research</i> , <b>2015</b> , 03, 68-81	0.4	6
5	Rapid Prototyping A Tool for Presenting 3-Dimensional Digital Models Produced by Terrestrial Laser Scanning. <i>ISPRS International Journal of Geo-Information</i> , <b>2014</b> , 3, 871-890	2.9	7
4	Customer Journey Mapping of an Experience-Centric Service by Mobile Self-reporting: Testing the Qualiwall Tool. <i>Lecture Notes in Computer Science</i> , <b>2014</b> , 261-272	0.9	3
3	DEVELOPING NATURAL AND INTUITIVE VIDEO-MEDIATED COLLABORATION [NIVMC SYSTEM]. <i>International Journal on Artificial Intelligence Tools</i> , <b>2012</b> , 21, 1240009	0.9	

2 Natural and Intuitive Video Mediated Collaboration. *Smart Innovation, Systems and Technologies*,  
**2011**, 21-28 0.5

1 Applying photogrammetry to reconstruct 3D luminance point clouds of indoor environments.  
*Architectural Engineering and Design Management*,1-17 1.2 1