

Timur DÃ¼zenli

List of Publications by Year in descending order

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Version: 2024-02-01

12
papers

88
citations

1684188

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1474206

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12
all docs

12
docs citations

12
times ranked

29
citing authors

#	ARTICLE	IF	CITATIONS
1	A New Method of Spectrum Sensing in Cognitive Radio for Dynamic and Randomly Modelled Primary Users. IETE Journal of Research, 2022, 68, 957-965.	2.6	5
2	Circuit Applications of Schwarz-Pick Lemma. IEEE Transactions on Circuits and Systems II: Express Briefs, 2022, 69, 20-24.	3.0	1
3	Some remarks on activation function design in complex extreme learning using Schwarz lemma. Neurocomputing, 2022, 492, 23-33.	5.9	4
4	A novel version of slime mould algorithm for global optimization and real world engineering problems. Mathematics and Computers in Simulation, 2022, 198, 253-288.	4.4	33
5	Rogosinski Lemmas ile ilgili $\frac{1}{2}$ ren Nokta Empedans Fonksiyonlar \pm i $\frac{1}{2}$ sin Carath \odot odory E \ddot{y} itsizli \ddot{y} i. D \ddot{a} ceMF $\frac{1}{2}$ hendislik Dergisi, 2021, 12, 61-68.	0.2	1
6	Uniqueness part of Schwarz lemma for driving point impedance functions. Filomat, 2020, 34, 2953-2959.	0.5	0
7	Schwarz lemma for driving point impedance functions and its circuit applications. International Journal of Circuit Theory and Applications, 2019, 47, 813-824.	2.0	1
8	On boundary analysis for derivative of driving point impedance functions and its circuit applications. IET Circuits, Devices and Systems, 2019, 13, 145-152.	1.4	8
9	Boundary Analysis for the Derivative of Driving Point Impedance Functions. IEEE Transactions on Circuits and Systems II: Express Briefs, 2018, 65, 1149-1153.	3.0	13
10	Bound estimates for the derivative of driving point impedance functions. Filomat, 2018, 32, 6211-6218.	0.5	6
11	A New Spectrum Sensing Strategy for Dynamic Primary Users in Cognitive Radio. IEEE Communications Letters, 2016, 20, 752-755.	4.1	16
12	Applications of the Carath \odot odory \hat{e} ms Inequality for Driving Point Impedance Functions. European Journal of Science and Technology, 0, , .	0.5	0