

Masayoshi Tomizuka

List of Publications by Citations

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

308
papers

6,842
citations

40
h-index

72
g-index

358
ext. papers

8,742
ext. citations

3
avg, IF

6.45
L-index

#	Paper	IF	Citations
308	Zero Phase Error Tracking Algorithm for Digital Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1987 , 109, 65-68	1.6	887
307	Analysis and Synthesis of Discrete-Time Repetitive Controllers. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1989 , 111, 353-358	1.6	362
306	Control of Rotary Series Elastic Actuator for Ideal Force-Mode Actuation in HumanRobot Interaction Applications. <i>IEEE/ASME Transactions on Mechatronics</i> , 2009 , 14, 105-118	5.5	265
305	A Compact Rotary Series Elastic Actuator for Human Assistive Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2012 , 17, 288-297	5.5	202
304	Robust Adaptive and Repetitive Digital Tracking Control and Application to a Hydraulic Servo for Noncircular Machining. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1994 , 116, 24-32	1.6	163
303	Smooth Robust Adaptive Sliding Mode Control of Manipulators With Guaranteed Transient Performance. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1996 , 118, 764-775	1.6	146
302	Vehicle Lateral Control for Highway Automation 1990 ,		131
301	Synchronization of Two Motion Control Axes Under Adaptive Feedforward Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1992 , 114, 196-203	1.6	128
300	Adaptive Pulse Width Control for Precise Positioning Under the Influence of Stiction and Coulomb Friction. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1988 , 110, 221-227	1.6	109
299	Mechatronics - "What Is It, Why, and How?" An editorial. <i>IEEE/ASME Transactions on Mechatronics</i> , 1996 , 1, 1-4	5.5	106
298	Adaptive Zero Phase Error Tracking Algorithm for Digital Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1987 , 109, 349-354	1.6	92
297	A Unified Approach to the Design of Adaptive and Repetitive Controllers for Robotic Manipulators. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1990 , 112, 618-629	1.6	84
296	New Repetitive Control With Improved Steady-State Performance and Accelerated Transient. <i>IEEE Transactions on Control Systems Technology</i> , 2014 , 22, 664-675	4.8	77
295	On the Design of Digital Tracking Controllers. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1993 , 115, 412-418	1.6	77
294	Discrete-Time Domain Analysis and Synthesis of Repetitive Controllers 1988 ,		77
293	On the Optimal Digital State Vector Feedback Controller With Integral and Preview Actions. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1979 , 101, 172-178	1.6	77
292	An Adaptive Control Scheme for Mechanical Manipulators Compensation of Nonlinearity and Decoupling Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1986 , 108, 127-135	1.6	76

291	Preview Control for Vehicle Lateral Guidance in Highway Automation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1993 , 115, 679-686	1.6	74
290	A Minimum Parameter Adaptive Approach for Rejecting Multiple Narrow-Band Disturbances With Application to Hard Disk Drives. <i>IEEE Transactions on Control Systems Technology</i> , 2012 , 20, 408-415	4.8	72
289	Optimization-Based Constrained Iterative Learning Control. <i>IEEE Transactions on Control Systems Technology</i> , 2011 , 19, 1613-1621	4.8	72
288	Steady-State and Stochastic Performance of a Modified Discrete-Time Prototype Repetitive Controller. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1990 , 112, 35-41	1.6	71
287	Coordinated Position Control of Multi-Axis Mechanical Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1998 , 120, 389-393	1.6	67
286	Passivity-Based Versus Disturbance Observer Based Robot Control: Equivalence and Stability. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1999 , 121, 41-47	1.6	66
285	Cancellation of Discrete Time Unstable Zeros by Feedforward Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1994 , 116, 33-38	1.6	66
284	Impedance Compensation of SUBAR for Back-Drivable Force-Mode Actuation. <i>IEEE Transactions on Robotics</i> , 2009 , 25, 512-521	6.5	63
283	A Comparison of Four Discrete-Time Repetitive Control Algorithms 1992 ,		63
282	Control of Exoskeletons Inspired by Fictitious Gain in Human Model. <i>IEEE/ASME Transactions on Mechatronics</i> , 2009 , 14, 689-698	5.5	60
281	A novel integrated chassis controller for full drive-by-wire vehicles. <i>Vehicle System Dynamics</i> , 2015 , 53, 215-236	2.8	59
280	Projection-Based Iterative Learning Control for Wafer Scanner Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2009 , 14, 388-393	5.5	59
279	Model-free Deep Reinforcement Learning for Urban Autonomous Driving 2019 ,		55
278	Probabilistic Prediction of Vehicle Semantic Intention and Motion 2018 ,		50
277	Flatness-Based Nonlinear Control for Position Tracking of Electrohydraulic Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015 , 20, 197-206	5.5	47
276	Distributed Conflict Resolution for Connected Autonomous Vehicles. <i>IEEE Transactions on Intelligent Vehicles</i> , 2018 , 3, 18-29	5	45
275	Clinical impact of gait training enhanced with visual kinematic biofeedback: Patients with Parkinson's disease and patients stable post stroke. <i>Neuropsychologia</i> , 2015 , 79, 332-43	3.2	43
274	High-Gain-Observer-Based Integral Sliding Mode Control for Position Tracking of Electrohydraulic Servo Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2017 , 22, 2695-2704	5.5	41

273	Optimal preview control for a linear continuous-time stochastic control system in finite-time horizon. <i>International Journal of Systems Science</i> , 2017 , 48, 129-137	2.3	40
272	Dual-Stage Iterative Learning Control for MIMO Mismatched System With Application to Robots With Joint Elasticity. <i>IEEE Transactions on Control Systems Technology</i> , 2014 , 22, 1350-1361	4.8	40
271	Spatially-partitioned environmental representation and planning architecture for on-road autonomous driving 2017 ,		40
270	An Overview on Study of Identification of Driver Behavior Characteristics for Automotive Control. <i>Mathematical Problems in Engineering</i> , 2014 , 2014, 1-15	1.1	40
269	Conditional Generative Neural System for Probabilistic Trajectory Prediction 2019 ,		40
268	Adaptive Output Regulation for the Rejection of a Periodic Disturbance With an Unknown Frequency. <i>IEEE Transactions on Control Systems Technology</i> , 2011 , 19, 1296-1304	4.8	38
267	Adaptive And Repetitive Digital Control Algorithms for Noncircular Machining 1988 ,		38
266	Disturbance Rejection Through an External Model. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1990 , 112, 559-564	1.6	34
265	A non-conservatively defensive strategy for urban autonomous driving 2016 ,		34
264	Modified Preview Control for a Wireless Tracking Control System With Packet Loss. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015 , 20, 299-307	5.5	33
263	Adaptive Control of Robot Manipulators in Constrained Motion Controller Design. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1995 , 117, 320-328	1.6	32
262	Probabilistic Prediction of Interactive Driving Behavior via Hierarchical Inverse Reinforcement Learning 2018 ,		30
261	A nonlinear feedback controller for aerial self-righting by a tailed robot 2013 ,		28
260	Fuzzy Logic Traction Controllers and their Effect on Longitudinal Vehicle Platoon Systems. <i>Vehicle System Dynamics</i> , 1996 , 25, 277-303	2.8	28
259	Vehicle lateral velocity and yaw rate control with two independent control inputs 1990 ,		28
258	Teach industrial robots peg-hole-insertion by human demonstration 2016 ,		28
257	Kinematic Kalman Filter (KKF) for Robot End-Effector Sensing. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2009 , 131,	1.6	27
256	Coordinated Longitudinal and Lateral Motion Control of Vehicles for IVHS. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 535-543	1.6	27

255	Network-Based Rehabilitation System for Improved Mobility and Tele-Rehabilitation. <i>IEEE Transactions on Control Systems Technology</i> , 2013 , 21, 1980-1987	4.8	26
254	A lizard-inspired active tail enables rapid maneuvers and dynamic stabilization in a terrestrial robot		26
253	Autonomous alignment of peg and hole by force/torque measurement for robotic assembly 2016 ,		26
252	Overview and new results in disturbance observer based adaptive vibration rejection with application to advanced manufacturing. <i>International Journal of Adaptive Control and Signal Processing</i> , 2015 , 29, 1459-1474	2.8	24
251	Preview control for impulse-free continuous-time descriptor systems. <i>International Journal of Control</i> , 2015 , 88, 1142-1149	1.5	24
250	Gait Phase-Based Control for a Rotary Series Elastic Actuator Assisting the Knee Joint. <i>Journal of Medical Devices, Transactions of the ASME</i> , 2011 , 5,	1.3	24
249	A new bias-compensating LS method for continuous system identification in the presence of coloured noise. <i>International Journal of Control</i> , 1992 , 56, 1441-1452	1.5	24
248	Disturbance Rejection Through an External Model for Nonminimum Phase Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1994 , 116, 39-44	1.6	23
247	Design of Digital Feedforward/Preview Controllers for Processes With Predetermined Feedback Controllers. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1980 , 102, 218-225	1.6	23
246	Control of an Exoskeleton for Realization of Aquatic Therapy Effects. <i>IEEE/ASME Transactions on Mechatronics</i> , 2010 , 15, 191-200	5.5	22
245	Smooth and continuous human gait phase detection based on foot pressure patterns 2008 ,		22
244	Deep Imitation Learning for Autonomous Driving in Generic Urban Scenarios with Enhanced Safety 2019 ,		22
243	Courteous Autonomous Cars 2018 ,		22
242	A Framework for Manipulating Deformable Linear Objects by Coherent Point Drift. <i>IEEE Robotics and Automation Letters</i> , 2018 , 3, 3426-3433	4.2	21
241	Torque Mode Control of a Cable-Driven Actuating System by Sensor Fusion. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2013 , 135,	1.6	21
240	Iterative learning control design for synchronization of wafer and reticle stages 2008 ,		21
239	Robust control of discretized continuous systems using the theory of sliding modes. <i>International Journal of Control</i> , 1995 , 62, 209-226	1.5	21
238	Enabling safe freeway driving for automated vehicles 2016 ,		21

237	2017,		20
236	Dual-Stage Adaptive Friction Compensation for Precise Load Side Position Tracking of Indirect Drive Mechanisms. <i>IEEE Transactions on Control Systems Technology</i> , 2015 , 23, 164-175	4.8	20
235	Contact Transition Control of Nonlinear Mechanical Systems Subject to a Unilateral Constraint. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1997 , 119, 749-759	1.6	20
234	Appropriate Sensor Placement for Fault-Tolerant Lane-Keeping Control of Automated Vehicles. <i>IEEE/ASME Transactions on Mechatronics</i> , 2007 , 12, 465-471	5.5	20
233	Preview Control for Vehicle Lateral Guidance in Highway Automation 1991,		20
232	Interaction-aware Multi-agent Tracking and Probabilistic Behavior Prediction via Adversarial Learning 2019,		19
231	Ensuring safety in human-robot coexistence environment 2014,		19
230	A mobile gait monitoring system for gait analysis 2009,		19
229	Compensation of Dominant Frequency Components of Nonrepeatable Disturbance in Hard Disk Drives. <i>IEEE Transactions on Magnetism</i> , 2007 , 43, 3756-3762	2	19
228	Adaptive Robust Motion and Force Tracking Control of Robot Manipulators in Contact With Compliant Surfaces With Unknown Stiffness. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1998 , 120, 232-240	1.6	19
227	A Theoretical and Experimental Study on Vehicle Lateral Control 1992,		19
226	Nonlinear Control With High-Gain Extended State Observer for Position Tracking of Electro-Hydraulic Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 25, 2610-2621	5.5	18
225	The stability of limit cycles in nonlinear systems. <i>Nonlinear Dynamics</i> , 2009 , 56, 269-275	5	18
224	A Fast Integrated Planning and Control Framework for Autonomous Driving via Imitation Learning 2018,		18
223	Towards Efficient Human-Robot Collaboration With Robust Plan Recognition and Trajectory Prediction. <i>IEEE Robotics and Automation Letters</i> , 2020 , 5, 2602-2609	4.2	17
222	Robust Performance Enhancement Using Disturbance Observers for Hysteresis Compensation Based on Generalized Prandtl-Bhlinkii Model. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2013 , 135,	1.6	17
221	Optimal preview control for discrete-time descriptor causal systems in a multirate setting. <i>International Journal of Control</i> , 2013 , 86, 844-854	1.5	17
220	Fuzzy Stabilization of Nonlinear Systems under Sampled-Data Feedback: An Exact Discrete-Time Model Approach. <i>IEEE Transactions on Fuzzy Systems</i> , 2010 ,	8.3	17

219	Robot end-effector sensing with position sensitive detector and inertial sensors 2012,		17
218	Adaptive Control of Robot Manipulators in Constrained Motion 1993,		17
217	Generic Tracking and Probabilistic Prediction Framework and Its Application in Autonomous Driving. <i>IEEE Transactions on Intelligent Transportation Systems</i> , 2020 , 21, 3634-3649	6.1	17
216	Generic Vehicle Tracking Framework Capable of Handling Occlusions Based on Modified Mixture Particle Filter 2018,		17
215	A terminal sliding mode based torque distribution control for an individual-wheel-drive vehicle. <i>Journal of Zhejiang University: Science A</i> , 2014 , 15, 681-693	2.1	16
214	Speed profile planning in dynamic environments via temporal optimization 2017,		16
213	Convex feasible set algorithm for constrained trajectory smoothing 2017,		16
212	Interaction-aware Decision Making with Adaptive Strategies under Merging Scenarios 2019,		16
211	Interpretable End-to-End Urban Autonomous Driving With Latent Deep Reinforcement Learning. <i>IEEE Transactions on Intelligent Transportation Systems</i> , 2021 , 1-11	6.1	16
210	Discrete-time nonlinear damping backstepping control with observers for rejection of low and high frequency disturbances. <i>Mechanical Systems and Signal Processing</i> , 2018 , 104, 436-448	7.8	16
209	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 25, 1961-1970	5.5	15
208	Design of arbitrary-order robust iterative learning control based on robust control theory. <i>Mechatronics</i> , 2017 , 47, 67-76	3	15
207	A New Plug-In Adaptive Controller for Rejection of Periodic Disturbances. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1993 , 115, 543-546	1.6	15
206	Efficient Sampling-Based Maximum Entropy Inverse Reinforcement Learning With Application to Autonomous Driving. <i>IEEE Robotics and Automation Letters</i> , 2020 , 5, 5355-5362	4.2	15
205	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2018 , 23, 2671-2680	5.5	15
204	Wasserstein Generative Learning with Kinematic Constraints for Probabilistic Interactive Driving Behavior Prediction 2019,		14
203	Design and torque-mode control of a cable-driven rotary series elastic actuator for subject-robot interaction 2015,		14
202	Statistical Learning Algorithms to Compensate Slow Visual Feedback for Industrial Robots. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2015 , 137,	1.6	14

201	An improved delay-dependent stability criterion for linear uncertain systems with multiple time-varying delays. <i>International Journal of Control</i> , 2014 , 87, 861-873	1.5	14
200	Improving Control Performance by Minimizing Jitter in RT-WiFi Networks 2014 ,		14
199	Design of a network-based mobile gait rehabilitation system 2012 ,		14
198	Mechanical design and impedance compensation of SUBAR (Sogang University's Biomedical Assist Robot) 2008 ,		14
197	LIDAR Sensing for Vehicle Lateral Guidance: Algorithm and Experimental Study. <i>IEEE/ASME Transactions on Mechatronics</i> , 2006 , 11, 653-660	5.5	14
196	Precise Linear-Motor Synchronization Control via Cross-Coupled Second-Order Discrete-Time Fractional-Order Sliding Mode. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 1-1	5.5	14
195	Towards a Fatality-Aware Benchmark of Probabilistic Reaction Prediction in Highly Interactive Driving Scenarios 2018 ,		14
194	State estimation for deformable objects by point registration and dynamic simulation 2017 ,		13
193	Dynamic Anti-Integrator-Windup Controller Design for Linear Systems With Actuator Saturation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2007 , 129, 1-12	1.6	13
192	An Experimental Study on Lateral Control of a Vehicle 1991 ,		13
191	. <i>IEEE Transactions on Automatic Control</i> , 2021 , 66, 5554-5560	5.9	13
190	Human Motion Prediction using Semi-adaptable Neural Networks 2019 ,		13
189	Generic Probabilistic Interactive Situation Recognition and Prediction: From Virtual to Real 2018 ,		13
188	Continuous Decision Making for On-road Autonomous Driving under Uncertain and Interactive Environments 2018 ,		13
187	Multi-modal Probabilistic Prediction of Interactive Behavior via an Interpretable Model 2019 ,		12
186	A design methodology for disturbance observer with application to precision motion control: An H-infinity based approach 2017 ,		12
185	Direct Joint Space State Estimation in Robots With Multiple Elastic Joints. <i>IEEE/ASME Transactions on Mechatronics</i> , 2014 , 19, 697-706	5.5	12
184	A lizard-inspired active tail enables rapid maneuvers and dynamic stabilization in a terrestrial robot 2011 ,		12

183	Intelligent Modeling of Thrust Force in Drilling Process. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2006 , 128, 846-855	1.6	12
182	Man-Machine Systems (Information, Control, and Decision Models of Human Performance). <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1975 , 97, 105-105	1.6	12
181	Learning Variable Impedance Control via Inverse Reinforcement Learning for Force-Related Tasks. <i>IEEE Robotics and Automation Letters</i> , 2021 , 6, 2225-2232	4.2	12
180	Interpretable Modelling of Driving Behaviors in Interactive Driving Scenarios based on Cumulative Prospect Theory 2019 ,		12
179	A Framework for Probabilistic Generic Traffic Scene Prediction 2018 ,		12
178	Behavior Planning of Autonomous Cars with Social Perception 2019 ,		11
177	Optimal Decoupled Disturbance Observers for Dual-Input Single-Output Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2014 , 136,	1.6	11
176	Cancellation of Unnatural Reaction Torque in Variable-Gear-Ratio. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2012 , 134,	1.6	11
175	A Reusability Study of Vehicle Lateral Control System. <i>Vehicle System Dynamics</i> , 1994 , 23, 259-278	2.8	11
174	Robotic manipulation of deformable objects by tangent space mapping and non-rigid registration 2016 ,		11
173	Deep Hierarchical Reinforcement Learning for Autonomous Driving with Distinct Behaviors 2018 ,		11
172	Non-uniform Multi-rate Estimator based Periodic Event-Triggered Control for resource saving. <i>Information Sciences</i> , 2018 , 459, 86-102	7.7	11
171	Fast planning of well conditioned trajectories for model learning 2014 ,		10
170	Flexible Joint Actuator for Patient's Rehabilitation Device 2007 ,		10
169	Position/Force Control of Multi-Axis Robot Manipulator based on the TDOF Robust Servo Controller for Each Joint 1992 ,		10
168	An Anti-Windup Design for Linear System With Asymptotic Tracking Subjected to Actuator Saturation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2000 , 122, 369-374	1.6	10
167	Neural-Network-Based Iterative Learning Control for Multiple Tasks. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2021 , 32, 4178-4190	10.3	10
166	Autonomous Ground Vehicle Lane-Keeping LPV Model-Based Control: Dual-Rate State Estimation and Comparison of Different Real-Time Control Strategies. <i>Sensors</i> , 2021 , 21,	3.8	10

165	Zero-shot Deep Reinforcement Learning Driving Policy Transfer for Autonomous Vehicles based on Robust Control 2018 ,		10
164	Iterative learning control with saturation constraints 2009 ,		9
163	Signal Optimization at Urban Highway Rail Grade Crossings Using an Online Adaptive Priority Strategy. <i>Journal of Transportation Engineering</i> , 2012 , 138, 479-484		9
162	A Digital Segmented Repetitive Control Algorithm. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1994 , 116, 577-582	1.6	9
161	Design and Implementation of Digital Servo Controller for High Speed Machine Tools 1991 ,		9
160	Constructing a Highly Interactive Vehicle Motion Dataset 2019 ,		9
159	Fusing Bird's Eye View LIDAR Point Cloud and Front View Camera Image for 3D Object Detection 2018 ,		9
158	A Double Disturbance Observer Design for Compensation of Unknown Time Delay in a Wireless Motion Control System. <i>IEEE Transactions on Control Systems Technology</i> , 2018 , 26, 675-683	4.8	8
157	On the time-optimal trajectory planning and control of robotic manipulators along predefined paths 2013 ,		8
156	Introduction and initial exploration of an Active/Passive Exoskeleton framework for portable assistance 2015 ,		8
155	Robotic rehabilitation treatments: Realization of aquatic therapy effects in exoskeleton systems 2009 ,		8
154	A Fuzzy Tuner for Fuzzy Logic Controllers 1992 ,		8
153	Trajectory Planning for High Speed Multiple Axis Contouring Systems 1989 ,		8
152	Robust impedance control with applications to a series-elastic actuated system 2016 ,		8
151	Multi-rate Observer Based Sliding Mode Control with Frequency Shaping for Vibration Suppression Beyond Nyquist Frequency**This work was sponsored by Western Digital Corporation.. <i>IFAC-PapersOnLine</i> , 2016 , 49, 13-18	0.7	8
150	Robust Deformation Model Approximation for Robotic Cable Manipulation 2019 ,		8
149	Discrete-Time Reduced-Complexity Youla Parameterization for Dual-Input Single-Output Systems. <i>IEEE Transactions on Control Systems Technology</i> , 2016 , 24, 302-309	4.8	7
148	Coordination and Trajectory Prediction for Vehicle Interactions via Bayesian Generative Modeling 2019 ,		7

147	Track deformable objects from point clouds with structure preserved registration. <i>International Journal of Robotics Research</i> , 2019 , 027836491984143	5.7	7
146	Efficient Grasp Planning and Execution With Multifingered Hands by Surface Fitting. <i>IEEE Robotics and Automation Letters</i> , 2019 , 4, 3995-4002	4.2	7
145	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2019 , 24, 2040-2051	5.5	7
144	Real-time collision avoidance algorithm on industrial manipulators 2017 ,		7
143	Optimal plant shaping for high bandwidth disturbance rejection in discrete disturbance observers 2010 ,		7
142	Full Sheet Control Using Steerable Nips. <i>IEEE/ASME Transactions on Mechatronics</i> , 2010 , 15, 48-58	5.5	7
141	A New Approach of Coordinated Motion Control Subjected to Actuator Saturation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 496-504	1.6	7
140	Extended state observer with phase compensation to estimate and suppress high-frequency disturbances 2016 ,		7
139	A Remote Control Strategy for an Autonomous Vehicle with Slow Sensor Using Kalman Filtering and Dual-Rate Control. <i>Sensors</i> , 2019 , 19,	3.8	6
138	Safe and feasible motion generation for autonomous driving via constrained policy net 2017 ,		6
137	Robust principal component analysis for iterative learning control of precision motion systems with non-repetitive disturbances 2015 ,		6
136	Control methodologies for precision positioning systems 2013 ,		6
135	Design of the Tracking Controller for Holographic Digital Data Storage. <i>IEEE/ASME Transactions on Mechatronics</i> , 2010 , 15, 242-252	5.5	6
134	Output Saturation in Electric Motor Systems: Identification and Controller Design. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2010 , 132,	1.6	6
133	Time-varying complementary filtering for attitude estimation 2011 ,		6
132	Design of iterative learning controller based on frequency domain linear matrix inequality 2009 ,		6
131	Robust fixed-structure controller design of electric power steering systems 2009 ,		6
130	Compensation of packet loss for a network-based rehabilitation system 2012 ,		6

129	Design of a Rehabilitation Device Based on a Mechanical Link System. <i>Journal of Mechanisms and Robotics</i> , 2012 , 4,	2.2	6
128	A disturbance observer approach to detecting and rejecting narrow-band disturbances in hard disk drives 2008 ,		6
127	Robust digital tracking with perturbation estimation via the Euler operator. <i>International Journal of Control</i> , 1996 , 63, 239-256	1.5	6
126	An Adaptive Sliding Mode Vehicle Traction Controller Design 1990 ,		6
125	Multirate sampling adaptive control and its application to thermal mixing systems. <i>International Journal of Control</i> , 1988 , 47, 735-744	1.5	6
124	A Discrete-Time Robust Vehicle Traction Controller Design 1989 ,		6
123	Digital Control Of Repetitive Errors In Disk Drive Systems 1989 ,		6
122	Human guidance programming on a 6-DoF robot with collision avoidance 2016 ,		6
121	Prediction of Human Arm Target for Robot Reaching Movements 2019 ,		6
120	Energy-Efficient Control for an Unmanned Ground Vehicle in a Wireless Sensor Network. <i>Journal of Sensors</i> , 2019 , 2019, 1-16	2	6
119	Generic Prediction Architecture Considering both Rational and Irrational Driving Behaviors 2019 ,		6
118	Real-Time Finger Gaits Planning for Dexterous Manipulation. <i>IFAC-PapersOnLine</i> , 2017 , 50, 12765-12772.0.7		5
117	Improving Efficiency of Autonomous Vehicles by V2V Communication 2018 ,		5
116	Adaptive Probabilistic Vehicle Trajectory Prediction Through Physically Feasible Bayesian Recurrent Neural Network 2019 ,		5
115	Nonlinear Controller With the Dead-Zone and Saturation for Optical Disk Drive Systems in the Presence of External Shocks. <i>IEEE/ASME Transactions on Mechatronics</i> , 2014 , 19, 1458-1463	5.5	5
114	Robust time delay compensation in a wireless motion control system with double disturbance observers 2015 ,		5
113	Fall-prediction algorithm using a neural network for safety enhancement of elderly 2013 ,		5
112	Robust disturbance observer design for a power-assist electric bicycle 2010 ,		5

111	Load side state estimation in robot with joint elasticity 2012 ,		5
110	DYNAMIC ANALYSES AND ROBUST STEERING CONTROLLER DESIGN FOR AUTOMATED LANE GUIDANCE OF HEAVY-DUTY VEHICLES. <i>Asian Journal of Control</i> , 2008 , 2, 140-154	1.7	5
109	Multivariable Direct Adaptive Control of Thermal Mixing Processes. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1985 , 107, 278-283	1.6	5
108	Multi-Rate Feedforward Tracking Control for Plants With Nonminimum Phase Discrete Time Models. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 556-560	1.6	5
107	Optimization-based constrained iterative learning control with application to building temperature control systems 2016 ,		5
106	The Experimental Realization of an Artificial Low-Reynolds-Number Swimmer with Three-Dimensional Maneuverability 2019 ,		5
105	Interactive Prediction for Multiple, Heterogeneous Traffic Participants with Multi-Agent Hybrid Dynamic Bayesian Network 2019 ,		5
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