

Mauricio Mauledoux

List of Publications by Year in descending order

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| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 1 | Leading presence-based strategies to manipulate user experience in virtual reality environments. <i>Virtual Reality</i> , 2022, 26, 1507-1518. | 4.1 | 5 |
| 2 | Simulation of a microgrid for a non-interconnected zone that integrates renewable energies. <i>International Journal of Electrical and Computer Engineering</i> , 2021, 11, 201. | 0.5 | 1 |
| 3 | Design of Dynamic Controllers for Continuous Paths on Parallel Platforms (Slide Modes and PD+). <i>MATEC Web of Conferences</i> , 2020, 306, 03005. | 0.1 | 1 |
| 4 | Modeling and Simulation of a DC Micro-Grid with a Model Predictive Controller. <i>International Journal on Advanced Science, Engineering and Information Technology</i> , 2020, 10, 1091-1098. | 0.2 | 1 |
| 5 | Inverse, Direct Kinetics and Differential Kinematic Control of Parallel Robot with Six Degrees of Hexa Freedom "Hunt.", 2019, . | | 3 |
| 6 | Algorithm for Object Grasp Detection. <i>Research Journal of Applied Sciences</i> , 2019, 13, 162-175. | 0.1 | 0 |
| 7 | Comparative Study of Control Strategies for a Micro Grid DC System of Renewable Energy Sources. <i>Journal of Engineering and Applied Sciences</i> , 2019, 14, 2822-2829. | 0.2 | 0 |
| 8 | Modeling a Microgrid that Integrates Renewable Energies in IEC 61850 - 7 - 420 and IEC 61400 - 25 - 3. <i>Journal of Engineering Science and Technology Review</i> , 2018, 11, 174-179. | 0.2 | 4 |
| 9 | Sliding Modes for a Manipulator Arm of 4 Degrees of Freedom. <i>International Journal of Online Engineering</i> , 2017, 13, 114. | 0.5 | 0 |
| 10 | Genetic Algorithm Optimization for DC Micro Grid Design, a Case of Study. <i>International Review of Electrical Engineering</i> , 2017, 12, 318. | 0.1 | 2 |
| 11 | Analysis of Autoregressive Predictive Models and Artificial Neural Networks for Irradiance Estimation. <i>Indian Journal of Science and Technology</i> , 2016, 9, . | 0.5 | 3 |
| 12 | Design of Sliding Mode Based Differential Flatness Control of Leg-Wheel Hybrid Robot. <i>Applied Mechanics and Materials</i> , 2016, 835, 681-686. | 0.2 | 1 |
| 13 | Process Design for Autonomous Car Mining 1st Prototype "ACM1PT" to Help on Exploration Task on Outdoor Environments. <i>Applied Mechanics and Materials</i> , 2016, 823, 447-452. | 0.2 | 0 |
| 14 | Approach for Negotiation Problems in Multi-Agent Systems for DC Micro Grid Using Multi-Objective Evolutionary Algorithms. <i>Applied Mechanics and Materials</i> , 2015, 713-715, 2106-2109. | 0.2 | 0 |
| 15 | Autonomous Car for Mining 1st ProtoType "ACM1PT". <i>Applied Mechanics and Materials</i> , 2015, 713-715, 901-904. | 0.2 | 0 |
| 16 | Tool to Perform Software-in-the-Loop through Robot Operating System. <i>Applied Mechanics and Materials</i> , 2015, 713-715, 2391-2394. | 0.2 | 0 |
| 17 | Comparative Study of Various Models to Estimate Hourly Solar Irradiance: Application for Performance Analysis of a Renewable Energy DC-Micro Grid. <i>Applied Mechanics and Materials</i> , 2014, 700, 7-11. | 0.2 | 0 |
| 18 | Development of Software for Analyzing of Solar Irradiance and Sizing of Stand-Alone PV Power Systems. <i>Applied Mechanics and Materials</i> , 2014, 700, 16-19. | 0.2 | 0 |

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|----|--|-----|-----------|
| 19 | Design of a three-finger end effector for optimal grip. DYNA (Colombia), 2014, 81, 93. | 0.2 | 1 |
| 20 | Diseño y construcción de un generador ultrasónico para la evaluación de la erosión y corrosión por cavitación en recubrimientos duros. Ingenium: Revista De La Facultad De Ingeniería, 2013, 14, 41. | 0.0 | 0 |
| 21 | Multiobjective evolutionary algorithm MOEA to solve task allocation problems in multi agents systems. , 2010, , . | | 2 |
| 22 | Multiobjective evolutionary algorithm MOEA an approach for solving MAS multiattribute allocation task. , 2010, , . | | 1 |
| 23 | Multiobjective Evolutionary Algorithms MOEA to Solve Task Allocation Problems in Multiagent Systems for DC MicroGrid. Applied Mechanics and Materials, 0, 700, 24-27. | 0.2 | 1 |
| 24 | Design and Implementation of Mechatronic Prosthesis for Amputees with Trans-Humeral Amputation. Applied Mechanics and Materials, 0, 713-715, 781-784. | 0.2 | 0 |
| 25 | Grasping Optimization in a Three Fingers Final Effector. Applied Mechanics and Materials, 0, 713-715, 919-922. | 0.2 | 0 |
| 26 | Mechanical Design of a Self-Balancing Platform for Transporting Purposes. Applied Mechanics and Materials, 0, 713-715, 785-788. | 0.2 | 0 |
| 27 | Linear Control for Full Bridge Phase PWM Rectifier. Applied Mechanics and Materials, 0, 823, 453-458. | 0.2 | 1 |
| 28 | Adaptive Control for Solar Photovoltaic Tracking System. Applied Mechanics and Materials, 0, 823, 377-382. | 0.2 | 0 |