

Byeongho Yu

List of Publications by Year in descending order

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citing authors

#	ARTICLE	IF	CITATIONS
1	STEP: State Estimator for Legged Robots Using a Preintegrated Foot Velocity Factor. IEEE Robotics and Automation Letters, 2022, 7, 4456-4463.	5.1	13
2	CAROS-Q: Climbing Aerial Robot System Adopting Rotor Offset With a Quasi-Decoupling Controller. IEEE Robotics and Automation Letters, 2021, 6, 8490-8497.	5.1	12
3	Retro-RL: Reinforcing Nominal Controller With Deep Reinforcement Learning for Tilting-Rotor Drones. IEEE Robotics and Automation Letters, 2022, 7, 9004-9011.	5.1	1