

Iven M Y Mareels

List of Publications by Year in descending order

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342
papers

8,898
citations

76326

40
h-index

54911

84
g-index

351
all docs

351
docs citations

351
times ranked

5482
citing authors

| # | ARTICLE | IF | CITATIONS |
|----|--|------|-----------|
| 1 | Putting energy back in control. IEEE Control Systems, 2001, 21, 18-33. | 0.8 | 663 |
| 2 | An observer looks at synchronization. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 1997, 44, 882-890. | 0.1 | 603 |
| 3 | A Lyapunov formulation of the nonlinear small-gain theorem for interconnected ISS systems. Automatica, 1996, 32, 1211-1215. | 5.0 | 534 |
| 4 | On non-local stability properties of extremum seeking control. Automatica, 2006, 42, 889-903. | 5.0 | 501 |
| 5 | Topological Feedback Entropy and Nonlinear Stabilization. IEEE Transactions on Automatic Control, 2004, 49, 1585-1597. | 5.7 | 320 |
| 6 | A small-gain control method for nonlinear cascaded systems with dynamic uncertainties. IEEE Transactions on Automatic Control, 1997, 42, 292-308. | 5.7 | 285 |
| 7 | Stability theory for differential/algebraic systems with application to power systems. IEEE Transactions on Circuits and Systems, 1990, 37, 1416-1423. | 0.9 | 244 |
| 8 | Control of Large-Scale Irrigation Networks. Proceedings of the IEEE, 2007, 95, 75-91. | 21.3 | 220 |
| 9 | A Unifying Framework for Global Regulation Via Nonlinear Output Feedback: From ISS to iISS. IEEE Transactions on Automatic Control, 2004, 49, 549-562. | 5.7 | 198 |
| 10 | Optimal Charging of Electric Vehicles Taking Distribution Network Constraints Into Account. IEEE Transactions on Power Systems, 2015, 30, 365-375. | 6.5 | 181 |
| 11 | An efficient brute-force solution to the network reconfiguration problem. IEEE Transactions on Power Delivery, 2000, 15, 996-1000. | 4.3 | 168 |
| 12 | On global extremum seeking in the presence of local extrema. Automatica, 2009, 45, 245-251. | 5.0 | 161 |
| 13 | On the choice of dither in extremum seeking systems: A case study. Automatica, 2008, 44, 1446-1450. | 5.0 | 148 |
| 14 | Adaptive repetitive learning control of robotic manipulators without the requirement for initial repositioning. , 2006, 22, 563-568. | | 146 |
| 15 | The power of spectral density analysis for mapping endogenous BOLD signal fluctuations. Human Brain Mapping, 2008, 29, 778-790. | 3.6 | 139 |
| 16 | A new approach to adaptive robust control. International Journal of Adaptive Control and Signal Processing, 1993, 7, 183-211. | 4.1 | 134 |
| 17 | Stability and motor adaptation in human arm movements. Biological Cybernetics, 2006, 94, 20-32. | 1.3 | 118 |
| 18 | Systems engineering for irrigation systems: Successes and challenges. Annual Reviews in Control, 2005, 29, 191-204. | 7.9 | 112 |

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| 19 | On some key issues in the windsurfer approach to adaptive robust control. Automatica, 1995, 31, 1619-1636. | 5.0 | 107 |
| 20 | Controlling nonlinear time-varying systems via euler approximations. Automatica, 1992, 28, 681-696. | 5.0 | 103 |
| 21 | A simple selftuning controller for stably invertible systems. Systems and Control Letters, 1984, 4, 5-16. | 2.3 | 98 |
| 22 | Non-linear dynamics in adaptive control: Chaotic and periodic stabilization. Automatica, 1986, 22, 641-655. | 5.0 | 96 |
| 23 | Adaptive Systems. , 1996, , . | | 95 |
| 24 | Indirect field-oriented control of induction motors is robustly globally stable. Automatica, 1996, 32, 1393-1402. | 5.0 | 90 |
| 25 | A Comparative Testing Study of Commercial 18650-Format Lithium-Ion Battery Cells. Journal of the Electrochemical Society, 2015, 162, A1592-A1600. | 2.9 | 84 |
| 26 | Robust nonlinear integral control. IEEE Transactions on Automatic Control, 2001, 46, 1336-1342. | 5.7 | 80 |
| 27 | LMS estimation via structural detection. IEEE Transactions on Signal Processing, 1998, 46, 2651-2663. | 5.3 | 78 |
| 28 | A software tool to generate simulated white matter structures for the assessment of fibre-tracking algorithms. NeuroImage, 2009, 47, 1288-1300. | 4.2 | 75 |
| 29 | Robust control of uncertain nonlinear systems via measurement feedback. IEEE Transactions on Automatic Control, 1999, 44, 807-812. | 5.7 | 71 |
| 30 | Excitation conditions for signed regressor least mean squares adaptation. IEEE Transactions on Circuits and Systems, 1988, 35, 613-624. | 0.9 | 67 |
| 31 | A Market Mechanism for Electric Vehicle Charging Under Network Constraints. IEEE Transactions on Smart Grid, 2016, 7, 827-836. | 9.0 | 66 |
| 32 | Patient-specific bivariate-synchrony-based seizure prediction for short prediction horizons. Epilepsy Research, 2010, 91, 214-231. | 1.6 | 64 |
| 33 | Event Triggered Adaptive Differential Modulation: A New Method for Traffic Reduction in Networked Control Systems. IEEE Transactions on Automatic Control, 2013, 58, 1696-1706. | 5.7 | 60 |
| 34 | Stability theory for adaptive systems: Method of averaging and persistency of excitation. IEEE Transactions on Automatic Control, 1987, 32, 26-34. | 5.7 | 50 |
| 35 | The Dynamics of the Epileptic Brain Reveal Long-Memory Processes. Frontiers in Neurology, 2014, 5, 217. | 2.4 | 48 |
| 36 | SYSTEMS ENGINEERING FOR IRRIGATION SYSTEMS: SUCCESSES AND CHALLENGES. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2005, 38, 1-16. | 0.4 | 47 |

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| 37 | Industry engagement with control research: Perspective and messages. Annual Reviews in Control, 2020, 49, 1-14. | 7.9 | 47 |
| 38 | Seizure Detection Using Seizure Probability Estimation: Comparison of Features Used to Detect Seizures. Annals of Biomedical Engineering, 2009, 37, 2129-2145. | 2.5 | 46 |
| 39 | Power Sharing in Angle Droop Controlled Microgrids. IEEE Transactions on Power Systems, 2017, 32, 4743-4751. | 6.5 | 45 |
| 40 | Nonlinear estimation of the BOLD signal. NeuroImage, 2008, 40, 504-514. | 4.2 | 43 |
| 41 | Robustness analysis of leader-follower consensus. Journal of Systems Science and Complexity, 2009, 22, 186-206. | 2.8 | 43 |
| 42 | Extremum Seeking for Constrained Inputs. IEEE Transactions on Automatic Control, 2013, 58, 2405-2410. | 5.7 | 41 |
| 43 | How exciting can a signal really be?. Systems and Control Letters, 1987, 8, 197-204. | 2.3 | 40 |
| 44 | Persistency of excitation criteria for linear, multivariable, time-varying systems. Mathematics of Control, Signals, and Systems, 1988, 1, 203-226. | 2.3 | 39 |
| 45 | Dead beat controllability of polynomial systems: symbolic computation approaches. IEEE Transactions on Automatic Control, 1998, 43, 162-175. | 5.7 | 39 |
| 46 | Non-linear stable inversion-based output tracking control for a spherical inverted pendulum. International Journal of Control, 2008, 81, 116-133. | 1.9 | 39 |
| 47 | Decentralized PID Control Design for Magnetic Levitation Systems Using Extremum Seeking. IEEE Access, 2018, 6, 3059-3067. | 4.2 | 39 |
| 48 | Finite sample properties of linear model identification. IEEE Transactions on Automatic Control, 1999, 44, 1370-1383. | 5.7 | 37 |
| 49 | Bifurcation effects in robust adaptive control. IEEE Transactions on Circuits and Systems, 1988, 35, 835-841. | 0.9 | 35 |
| 50 | On Adaptive Robust Control and Control-Relevant System Identification. , 1992, , . | | 35 |
| 51 | System identification and controller design for dual actuated hard disk drive. Control Engineering Practice, 2004, 12, 665-676. | 5.5 | 35 |
| 52 | Feedback and Control for Everyone. , 2010, , . | | 35 |
| 53 | On extremum seeking in bioprocesses with multivalued cost functions. Biotechnology Progress, 2009, 25, 683-689. | 2.6 | 34 |
| 54 | Reinforcement learning for adaptive optimal control of continuous-time linear periodic systems. Automatica, 2020, 118, 109035. | 5.0 | 34 |

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| 55 | Electric vehicle charging and grid constraints: Comparing distributed and centralized approaches. , 2013, , . | | 33 |
| 56 | Dead-beat control of simple Hammerstein models. IEEE Transactions on Automatic Control, 1998, 43, 1184-1188. | 5.7 | 32 |
| 57 | PV generation and demand mismatch: Evaluating the potential of residential storage. , 2015, , . | | 32 |
| 58 | The importance of spatial distribution when analysing the impact of electric vehicles on voltage stability in distribution networks. Energy Systems, 2015, 6, 63-84. | 3.0 | 32 |
| 59 | Learning control in robot-assisted rehabilitation of motor skills “ a review. Journal of Control and Decision, 2016, 3, 19-43. | 1.6 | 32 |
| 60 | Quantifying the effects of dimension on the convergence rate of the LMS adaptive FIR estimator. IEEE Transactions on Signal Processing, 1998, 46, 2611-2615. | 5.3 | 30 |
| 61 | Nonlinear Energy-Based Control Method for Aircraft Automatic Landing Systems. IEEE Transactions on Control Systems Technology, 2010, 18, 871-884. | 5.2 | 29 |
| 62 | Sufficiency of excitation. Systems and Control Letters, 1984, 5, 159-163. | 2.3 | 28 |
| 63 | Nonlinear averaging theorems, and the determination of parameter convergence rates in adaptive control. Systems and Control Letters, 1986, 7, 145-157. | 2.3 | 28 |
| 64 | Non-linear dynamics in adaptive control. Automatica, 1988, 24, 485-497. | 5.0 | 28 |
| 65 | Minimum phase properties for input nonaffine nonlinear systems. IEEE Transactions on Automatic Control, 1999, 44, 868-872. | 5.7 | 27 |
| 66 | A rigorous solution of the infinite time interval LQ problem with constant state tracking. Systems and Control Letters, 2004, 52, 289-296. | 2.3 | 27 |
| 67 | Modelling extracellular electrical stimulation: III. Derivation and interpretation of neural tissue equations. Journal of Neural Engineering, 2014, 11, 065004. | 3.5 | 27 |
| 68 | Linear system security“Detection and correction of adversarial sensor attacks in the noise-free case. Automatica, 2019, 101, 53-59. | 5.0 | 27 |
| 69 | On global extremum seeking in the presence of local extrema. , 2006, , . | | 26 |
| 70 | Analyzing the Stability of Switched Systems Using Common Zeroing-Output Systems. IEEE Transactions on Automatic Control, 2017, 62, 5138-5153. | 5.7 | 25 |
| 71 | Non-local stabilization of a spherical inverted pendulum. International Journal of Control, 2008, 81, 1035-1053. | 1.9 | 24 |
| 72 | CHRONIC AIRWAY DISEASE: DETERIORATING PULMONARY FUNCTION IN SHEEP ASSOCIATED WITH REPEATED CHALLENGES OF HOUSE DUST MITE. Experimental Lung Research, 2006, 32, 321-330. | 1.2 | 23 |

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| 73 | On the Choice of Dither in Extremum Seeking Systems: a Case Study. , 2006, , . | | 23 |
| 74 | Modelling extracellular electrical stimulation: IV. Effect of the cellular composition of neural tissue on its spatio-temporal filtering properties. Journal of Neural Engineering, 2014, 11, 065005. | 3.5 | 23 |
| 75 | Stability theory for adaptive systems: Methods of averaging and persistency of excitation. , 1985, , . | | 22 |
| 76 | Dual stage actuator control in hard disk drive - a review. , 0, , . | | 22 |
| 77 | A dual purpose principal and minor component flow. Systems and Control Letters, 2005, 54, 759-769. | 2.3 | 22 |
| 78 | A Systems Engineering Approach to Viticulture On-Farm Irrigation. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2008, 41, 9569-9574. | 0.4 | 22 |
| 79 | EMU: A transparent 3D robotic manipulandum for upper-limb rehabilitation. , 2017, 2017, 771-776. | | 21 |
| 80 | Dual-loop iterative optimal control for the finite horizon LQR problem with unknown dynamics. Systems and Control Letters, 2018, 111, 49-57. | 2.3 | 21 |
| 81 | Number/theoretic solutions to intercept time problems. IEEE Transactions on Information Theory, 1996, 42, 959-971. | 2.4 | 20 |
| 82 | Feedback-Based Iterative Learning Design and Synthesis With Output Constraints for Robotic Manipulators. , 2018, 2, 513-518. | | 20 |
| 83 | Stabilising influence of a synchronous condenser in low inertia networks. IET Generation, Transmission and Distribution, 2020, 14, 3582-3593. | 2.5 | 20 |
| 84 | The principle of critical simplification in chemical kinetics. Chemical Engineering Science, 2003, 58, 4833-4842. | 3.8 | 19 |
| 85 | Enhanced detection-guided NLMS estimation of sparse FIR-modeled signal channels. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2006, 53, 1783-1791. | 0.1 | 19 |
| 86 | On robustness analysis of linear vibrational control systems. Automatica, 2018, 87, 202-209. | 5.0 | 19 |
| 87 | Energy-balancing passivity-based control. , 2000, , . | | 18 |
| 88 | Decentralized control design of interconnected chains of integrators: A case study. Automatica, 2008, 44, 2171-2178. | 5.0 | 18 |
| 89 | Modeling Individual Human Motor Behavior Through Model Reference Iterative Learning Control. IEEE Transactions on Biomedical Engineering, 2012, 59, 1892-1901. | 4.2 | 18 |
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| 92 | A 40 GHz Power Efficient Static CML Frequency Divider in 0.13- μ m CMOS Technology for High Speed Millimeter-Wave Wireless Systems. , 2008, , . | | 17 |
| 93 | A prototype 64-electrode stimulator in 65 nm CMOS process towards a high density epi-retinal prosthesis. , 2011, 2011, 6729-32. | | 17 |
| 94 | Integral sliding mode control design for systems with fast sensor dynamics. Automatica, 2020, 119, 109093. | 5.0 | 17 |
| 95 | Experimental and theoretical comparison of some algorithms for beamforming in single receiver adaptive arrays. IEEE Transactions on Antennas and Propagation, 1991, 39, 21-28. | 5.1 | 16 |
| 96 | Decision region approximation by polynomials or neural networks. IEEE Transactions on Information Theory, 1997, 43, 903-907. | 2.4 | 16 |
| 97 | Controlling nonlinear systems with input unmodelled dynamics. , 0, , . | | 15 |
| 98 | Towards a smart automated surface irrigation management in rice-growing areas in Italy. Journal of Agricultural Engineering, 2017, 48, 42-48. | 1.5 | 15 |
| 99 | A novel passivity-based controller for an active magnetic bearing benchmark experiment. , 2000, , . | | 14 |
| 100 | A 60-GHz transceiver on CMOS. , 2008, , . | | 14 |
| 101 | Invariance Principles and Observability in Switched Systems With an Application in Consensus. IEEE Transactions on Automatic Control, 2021, 66, 5128-5143. | 5.7 | 14 |
| 102 | LS detection guided NLMS estimation of sparse systems. , 0, , . | | 13 |
| 103 | Indirect field oriented control of induction motors is robustly globally stable. , 0, , . | | 13 |
| 104 | Predicting stand basal area in thinned stands using a dynamical model. Forest Ecology and Management, 1999, 116, 175-187. | 3.2 | 13 |
| 105 | Energy shaping revisited. , 0, , . | | 13 |
| 106 | Issues in the Implementation of a 60GHz Transceiver on CMOS. , 2007, , . | | 13 |
| 107 | Compatible Formation Set for UAVs with Visual Sensing Constraint. , 2018, , . | | 13 |
| 108 | Adaptively controlling non-linear systems, using trajectory approximations. International Journal of Adaptive Control and Signal Processing, 1992, 6, 395-411. | 4.1 | 12 |

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| 109 | Modeling and validation of an unbalanced LV network using Smart Meter and SCADA inputs. , 2013, , . | | 12 |
| 110 | Evaluating Rehabilitation Progress Using Motion Features Identified by Machine Learning. IEEE Transactions on Biomedical Engineering, 2021, 68, 1417-1428. | 4.2 | 12 |
| 111 | Asymptotic Dynamics in Adaptive Gain Control. , 1999, , 29-63. | | 12 |
| 112 | MaxNet: Faster Flow Control Convergence. Lecture Notes in Computer Science, 2004, , 588-599. | 1.3 | 12 |
| 113 | Dynamics of an adaptive hybrid. IEEE Transactions on Circuits and Systems, 1991, 38, 1-12. | 0.9 | 11 |
| 114 | A fully flexible stimulator using 65 nm cmos process for 1024-electrode epi-retinal prosthesis. , 2009, 2009, 1643-6. | | 11 |
| 115 | A paradigm for epileptic seizure prediction using a coupled oscillator model of the brain. , 2009, 2009, 6428-31. | | 11 |
| 116 | Information infrastructures for on-line measurement of non-productive greenhouse gas emissions in manufacturing: case of the brewing industry. International Journal of Production Research, 2012, 50, 6553-6573. | 7.5 | 11 |
| 117 | Rabi resonance in spin systems: Theory and experiment. Journal of Magnetic Resonance, 2014, 242, 136-142. | 2.1 | 11 |
| 118 | Limitations of robust adaptive pole placement control. IEEE Transactions on Automatic Control, 1994, 39, 1665-1671. | 5.7 | 10 |
| 119 | Sample Complexity of Least Squares Identification of FIR Models. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 1996, 29, 4664-4669. | 0.4 | 10 |
| 120 | Output deadbeat control of nonlinear discrete-time systems with one-dimensional zero dynamics: global stability conditions. IEEE Transactions on Automatic Control, 1999, 44, 1262-1266. | 5.7 | 10 |
| 121 | Controllability of structured polynomial systems. IEEE Transactions on Automatic Control, 1999, 44, 761-764. | 5.7 | 10 |
| 122 | Iterative identification and two step control design for partially unknown unstable plants. International Journal of Control, 2001, 74, 43-57. | 1.9 | 10 |
| 123 | Patient Un-Specific Detection of Epileptic Seizures Through Changes in Variance. , 2006, 2006, 3747-50. | | 10 |
| 124 | Analysis and Design of a 50-GHz 2:1 CMOS CML Static Frequency Divider Based on LC-tank. , 2008, , . | | 10 |
| 125 | On making energy demand and network constraints compatible in the last mile of the power grid. Annual Reviews in Control, 2014, 38, 243-258. | 7.9 | 10 |
| 126 | Local measurements and virtual pricing signals for residential demand side management. Sustainable Energy, Grids and Networks, 2015, 4, 62-71. | 3.9 | 10 |

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| 127 | Probing to Observe Neural Dynamics Investigated with Networked Kuramoto Oscillators. International Journal of Neural Systems, 2017, 27, 1650038. | 5.2 | 10 |
| 128 | Traffic Reduction in Packet Switched Networked Control Systems Using Deadband Error Modulation. IEEE Transactions on Automatic Control, 2017, 62, 4038-4043. | 5.7 | 10 |
| 129 | Model-Guided Data-Driven Decentralized Control for Magnetic Levitation Systems. IEEE Access, 2018, 6, 43546-43562. | 4.2 | 10 |
| 130 | Output Feedback Global Stabilization for a Class of Nonlinear Systems with Unmodelled Dynamics. European Journal of Control, 1996, 2, 201-210. | 2.6 | 9 |
| 131 | MODELLING AND STABILISATION OF A SPHERICAL INVERTED PENDULUM. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2005, 38, 1130-1135. | 0.4 | 9 |
| 132 | Way Point Tracking of a Spherical Inverted Pendulum. , 2007, , . | | 9 |
| 133 | Personalised Public Transportation: A new mobility model for urban and suburban transportation. , 2014, , . | | 9 |
| 134 | Upper Limb Deseighting Using Underactuated End-Effector-Based Backdrivable Manipulanda. IEEE Robotics and Automation Letters, 2018, 3, 2116-2122. | 5.1 | 9 |
| 135 | Feedback data rates for nonlinear systems. , 2003, , . | | 9 |
| 136 | On the dynamics of an equation arising in adaptive control. , 1986, , . | | 8 |
| 137 | Online learning via congregational gradient descent. Mathematics of Control, Signals, and Systems, 1997, 10, 331-363. | 2.3 | 8 |
| 138 | Passivity-based control for flight control systems. , 1999, , . | | 8 |
| 139 | Robust nonlinear integral control by partial-state and output feedback. , 0, , . | | 8 |
| 140 | Sufficient conditions for the existence of an unbounded solution. Automatica, 2001, 37, 1609-1617. | 5.0 | 8 |
| 141 | Irrigation networks: a systems engineering approach. , 2003, , . | | 8 |
| 142 | Correlation analysis of seizure detection features. , 2008, , . | | 8 |
| 143 | A subthreshold down converter optimized for super-low-power applications in MICS Band. , 2011, , . | | 8 |
| 144 | Observability limits for networked oscillators. Automatica, 2014, 50, 1087-1099. | 5.0 | 8 |

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| 145 | Model predictive motion control of autonomous forklift vehicles with dynamics balance constraint. , 2016, , . | | 8 |
| 146 | Detectability and Uniform Global Asymptotic Stability in Switched Nonlinear Time-Varying Systems. IEEE Transactions on Automatic Control, 2020, 65, 2123-2138. | 5.7 | 8 |
| 147 | A Lyapunov Formulation of Nonlinear Small Gain Theorem for Interconnected Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 1995, 28, 625-630. | 0.4 | 7 |
| 148 | Output stabilization of square nonlinear systems. Automatica, 1997, 33, 1571-1577. | 5.0 | 7 |
| 149 | On the modelling complexity and utility of an EMS system. , 2010, , . | | 7 |
| 150 | Real-time Optimal Control of River Basin Networks. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 11459-11464. | 0.4 | 7 |
| 151 | A distributed electric vehicle charging management algorithm using only local measurements. , 2014, , . | | 7 |
| 152 | Power sharing correction in angle droop controlled inverter interfaced microgrids. , 2015, , . | | 7 |
| 153 | Stability and active power sharing in droop controlled inverter interfaced microgrids: Effect of clock mismatches. Automatica, 2018, 93, 469-475. | 5.0 | 7 |
| 154 | Controlling DC microgrids in communities, buildings and data centers. IET Smart Grid, 2020, 3, 376-384. | 2.2 | 7 |
| 155 | Nonlinear averaging analysis of the incremental pole placement adaptive controller. Automatica, 1991, 27, 769-782. | 5.0 | 6 |
| 156 | Flight control systems using passivity-based control - Disturbance rejection and robustness analysis. , 1999, , . | | 6 |
| 157 | Solutions to disturbance decoupling problem with constant measurement feedback for linear systems. Automatica, 2000, 36, 1717-1724. | 5.0 | 6 |
| 158 | Nonlinear energy-based control method for aircraft dynamics. , 0, , . | | 6 |
| 159 | Universal output feedback controllers for nonlinear systems with unknown control direction. , 0, , . | | 6 |
| 160 | Revisiting the Bloch equation through averaging. , 2008, , . | | 6 |
| 161 | A super low power MICS band receiver in 65 nm CMOS for high resolution epi-retinal prosthesis. , 2009, , . | | 6 |
| 162 | On the finite time performance of model predictive control. Systems and Control Letters, 2014, 70, 60-68. | 2.3 | 6 |

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| 163 | Personalized Public Transportation: A Mobility Model and its Application to Melbourne. IEEE Intelligent Transportation Systems Magazine, 2015, 7, 37-48. | 3.8 | 6 |
| 164 | Fourier Tract Sampling (FouTS): A framework for improved inference of white matter tracts from diffusion MRI by explicitly modelling tract volume. NeuroImage, 2015, 120, 412-427. | 4.2 | 6 |
| 165 | Modeling of Endpoint Feedback Learning Implemented Through Point-to-Point Learning Control. IEEE Transactions on Control Systems Technology, 2017, 25, 1576-1585. | 5.2 | 6 |
| 166 | Markovian framework for diabetes control. , 0, , . | | 6 |
| 167 | Comments on "Adaptive control of linearizable systems" by S.S. Sastry and A. Isidori. IEEE Transactions on Automatic Control, 1992, 37, 698-701. | 5.7 | 5 |
| 168 | Estimation of noisy quantized Gaussian AR time-series with randomly varying observation coefficient. IEEE Transactions on Signal Processing, 1995, 43, 1285-1290. | 5.3 | 5 |
| 169 | A unifying framework for global regulation via nonlinear output feedback. , 0, , . | | 5 |
| 170 | Optimal power analysis for network lifetime balance in wireless sensor networks. , 2007, , . | | 5 |
| 171 | Magnetic resonance described in the excitation dependent rotating frame of reference. , 2008, 2008, 5769-73. | | 5 |
| 172 | Modeling reversible self-discharge in series-connected Li-ion battery cells. , 2013, , . | | 5 |
| 173 | Electric Vehicle Charging: A Noncooperative Game Using Local Measurements. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 5426-5431. | 0.4 | 5 |
| 174 | Effects of robotic exoskeleton dynamics on joint recruitment in a neurorehabilitation context. , 2015, , . | | 5 |
| 175 | Effect of sensory experience on motor learning strategy. Journal of Neurophysiology, 2015, 113, 1077-1084. | 1.8 | 5 |
| 176 | On V-shaped flight formation of bird flocks with visual communication constraints. , 2017, , . | | 5 |
| 177 | Input and Output Constraints in Iterative Learning Control Design for Robotic Manipulators. Unmanned Systems, 2018, 06, 197-208. | 3.6 | 5 |
| 178 | REVISITING THE MIT RULE FOR ADAPTIVE CONTROL. , 1987, , 161-166. | | 5 |
| 179 | Improved LMS estimation via structural detection. , 0, , . | | 4 |
| 180 | A virtual laboratory experience based on a double tank apparatus. , 0, , . | | 4 |

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| 181 | RECOVERING STATE TRAJECTORIES FROM OUTPUT MEASUREMENTS AND DYNAMIC MODELS: A COMPUTATIONAL COMPLEXITY POINT OF VIEW. <i>International Journal of Bifurcation and Chaos in Applied Sciences and Engineering</i> , 2002, 12, 1079-1095. | 1.7 | 4 |
| 182 | Reduced-Complexity Estimation for Large-Scale Hidden Markov Models. <i>IEEE Transactions on Signal Processing</i> , 2004, 52, 1242-1249. | 5.3 | 4 |
| 183 | STABILITY RESULTS FOR NETWORKED CONTROL SYSTEMS SUBJECT TO PACKET DROPOUTS. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2005, 38, 73-78. | 0.4 | 4 |
| 184 | Revisiting excitation pattern design for magnetic resonance imaging through optimisation of the signal contrast efficiency. <i>Biomedical Signal Processing and Control</i> , 2009, 4, 317-328. | 5.7 | 4 |
| 185 | Automation of On-Farm Irrigation: Horticultural Case Study. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2010, 43, 256-261. | 0.4 | 4 |
| 186 | A Flexible Electrode Driver Using 65 nm CMOS Process for 1024-Electrode Epi-Retinal Prosthesis. , 2010, , . | | 4 |
| 187 | Human Motor Learning Through Iterative Model Reference Adaptive Control. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2011, 44, 2883-2888. | 0.4 | 4 |
| 188 | Autonomous Performance Monitoring of an On-Line Real-Time Decision Support System. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2011, 44, 13080-13085. | 0.4 | 4 |
| 189 | Maximum Parsimony, Substitution Model, and Probability Phylogenetic Trees. <i>Journal of Computational Biology</i> , 2011, 18, 67-80. | 1.6 | 4 |
| 190 | On sign-definite pairs of functions. , 2014, , . | | 4 |
| 191 | Battery Management using Secondary Loads: A Novel Integrated Approach. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2014, 47, 3924-3929. | 0.4 | 4 |
| 192 | Comment on "A Comparative Testing Study of Commercial 18650-Format Lithium-Ion Battery Cells" [<i>i></i>]. <i>Electrochem. Soc.</i> , 162, A1592 (2015)]. <i>Journal of the Electrochemical Society</i> , 2015, 162, Y11-Y12. | 2.9 | 4 |
| 193 | Sensor attack correction for linear systems with known inputs. <i>IFAC-PapersOnLine</i> , 2018, 51, 206-211. | 0.9 | 4 |
| 194 | On Model-guided Neural Networks for System Identification. , 2019, , . | | 4 |
| 195 | Extremum Seeking Control With Sporadic Packet Transmission for Networked Control Systems. <i>IEEE Transactions on Control of Network Systems</i> , 2020, 7, 758-769. | 3.7 | 4 |
| 196 | On Stability Radii of Slowly Time-Varying Systems. <i>Systems and Control: Foundations and Applications</i> , 2001, , 55-75. | 0.3 | 4 |
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| 198 | Necessary and sufficient conditions for output dead beat controllability for a class of polynomial systems. , 0, , . | | 3 |

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