

Hai Zhu

List of Publications by Year in descending order

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papers

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1478505

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1872680

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178
citing authors

#	ARTICLE	IF	CITATIONS
1	Decentralized probabilistic multi-robot collision avoidance using buffered uncertainty-aware Voronoi cells. <i>Autonomous Robots</i> , 2022, 46, 401-420.	4.8	15
2	An escape strategy in orbital pursuit-evasion games with incomplete information. <i>Science China Technological Sciences</i> , 2021, 64, 559-570.	4.0	15
3	Learning Interaction-Aware Trajectory Predictions for Decentralized Multi-Robot Motion Planning in Dynamic Environments. <i>IEEE Robotics and Automation Letters</i> , 2021, 6, 2256-2263.	5.1	29
4	Multi-robot Task Assignment for Aerial Tracking with Viewpoint Constraints. , 2021, , .		2
5	Saddle Point of Orbital Pursuit-Evasion Game Under J2-Perturbed Dynamics. <i>Journal of Guidance, Control, and Dynamics</i> , 2020, 43, 1733-1739.	2.8	23
6	Robust Vision-based Obstacle Avoidance for Micro Aerial Vehicles in Dynamic Environments. , 2020, , .		39
7	With Whom to Communicate: Learning Efficient Communication for Multi-Robot Collision Avoidance. , 2020, , .		9
8	Distributed Multi-Robot Formation Splitting and Merging in Dynamic Environments. , 2019, , .		22
9	A dimension-reduction solution of free-time differential games for spacecraft pursuit-evasion. <i>Acta Astronautica</i> , 2019, 163, 201-210.	3.2	30
10	Chance-Constrained Collision Avoidance for MAVs in Dynamic Environments. <i>IEEE Robotics and Automation Letters</i> , 2019, 4, 776-783.	5.1	130
11	B-UAVC: Buffered Uncertainty-Aware Voronoi Cells for Probabilistic Multi-Robot Collision Avoidance. , 2019, , .		33