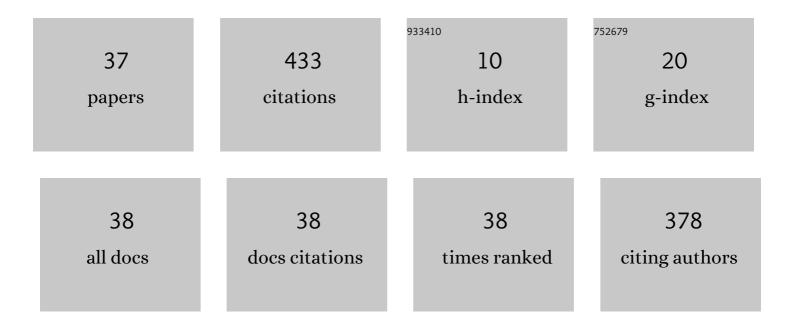
Yongjing Wang

List of Publications by Year in descending order

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YONGUNG WANG

#	Article	lF	CITATIONS
1	Robotic Disassembly Sequence Planning With Backup Actions. IEEE Transactions on Automation Science and Engineering, 2022, 19, 2095-2107.	5.2	8
2	Robotic Disassembly for Remanufacturing. Springer Series in Advanced Manufacturing, 2022, , 7-25.	0.5	0
3	Component and Subassembly Detection. Springer Series in Advanced Manufacturing, 2022, , 47-58.	0.5	Ο
4	Modelling of Robotic Disassembly Sequence Planning. Springer Series in Advanced Manufacturing, 2022, , 59-69.	0.5	0
5	Robotic Disassembly Sequence Re-planning. Springer Series in Advanced Manufacturing, 2022, , 131-142.	0.5	1
6	Product Representation for Disassembly Sequence Planning. Springer Series in Advanced Manufacturing, 2022, , 27-45.	0.5	2
7	Modelling of Robotic Disassembly Line Balancing. Springer Series in Advanced Manufacturing, 2022, , 71-83.	0.5	0
8	Evolutionary Optimisation for Robotic Disassembly Sequence Planning and Line Balancing. Springer Series in Advanced Manufacturing, 2022, , 85-110.	0.5	1
9	Introduction to Remanufacturing. Springer Series in Advanced Manufacturing, 2022, , 1-6.	0.5	1
10	Solutions for Robotic Disassembly Sequence Planning with Backup Actions. Springer Series in Advanced Manufacturing, 2022, , 111-130.	0.5	2
11	Solutions for Mixed-Model Disassembly Line Balancing with Multi-robot Workstations. Springer Series in Advanced Manufacturing, 2022, , 153-180.	0.5	0
12	Optimisation of Robotic Disassembly for Remanufacturing. Springer Series in Advanced Manufacturing, 2022, , .	0.5	5
13	A method to improve position accuracy for the dual-drive feed machines by state-dependent friction compensation. Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture, 2022, 236, 1247-1267.	2.4	1
14	Towards a Uniform Welding Quality: A Novel Weaving Welding Control Algorithm Based on Constant Heat Input. Materials, 2022, 15, 3796.	2.9	1
15	A self-evolving system for robotic disassembly sequence planning under uncertain interference conditions. Robotics and Computer-Integrated Manufacturing, 2022, 78, 102392.	9.9	9
16	Interlocking problems in disassembly sequence planning. International Journal of Production Research, 2021, 59, 4723-4735.	7.5	11
17	Smart Composites and Their Applications. , 2021, , 380-389.		Ο
18	An experimental human-robot collaborative disassembly cell. Computers and Industrial Engineering, 2021, 155, 107189.	6.3	38

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#	Article	IF	CITATIONS
19	Interference probability matrix for disassembly sequence planning under uncertain interference. Journal of Manufacturing Systems, 2021, 60, 214-225.	13.9	10
20	A case study in human–robot collaboration in the disassembly of press-fitted components. Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture, 2020, 234, 654-664.	2.4	43
21	Self-healing of structural carbon fibres in polymer composites. Cogent Engineering, 2020, 7, 1799909.	2.2	7
22	A Non-Delay Error Compensation Method for Dual-Driving Gantry-Type Machine Tool. Processes, 2020, 8, 748.	2.8	6
23	Unfastening of Hexagonal Headed Screws by a Collaborative Robot. IEEE Transactions on Automation Science and Engineering, 2020, , 1-14.	5.2	25
24	Interlocking Problem in Automatic Disassembly Planning and Two Solutions. Lecture Notes in Electrical Engineering, 2020, , 193-213.	0.4	1
25	Variable Span Multistep Straightening Process for Long/Extra-Long Linear Guideways. IEEE Access, 2019, 7, 107491-107505.	4.2	3
26	Peg–hole disassembly using active compliance. Royal Society Open Science, 2019, 6, 190476.	2.4	23
27	Robotic disassembly re-planning using a two-pointer detection strategy and a super-fast bees algorithm. Robotics and Computer-Integrated Manufacturing, 2019, 59, 130-142.	9.9	49
28	A strategy for human-robot collaboration in taking products apart for remanufacture. FME Transactions, 2019, 47, 731-738.	1.4	21
29	Automatic Detection of Subassemblies for Disassembly Sequence Planning. , 2018, , .		0
30	Design of a Novel Six-Axis Force/Torque Sensor based on Optical Fibre Sensing for Robotic Applications. , 2018, , .		0
31	Design of a Novel Six-Axis Force/Torque Sensor based on Optical Fibre Sensing for Robotic Applications. , 2018, , .		2
32	Automatic Detection of Subassemblies for Disassembly Sequence Planning. , 2018, , .		1
33	Nanocomposites for Extrinsic Self-healing Polymer Materials. Springer Series on Polymer and Composite Materials, 2017, , 243-279.	0.7	2
34	Sustainable self-healing at ultra-low temperatures in structural composites incorporating hollow vessels and heating elements. Royal Society Open Science, 2016, 3, 160488.	2.4	31
35	Designing robust feedback linearisation controllers using imperfect dynamic models and sensor feedback. Cogent Engineering, 2016, 3, 1173529.	2.2	2
36	Laser directed writing of flat lenses on buckypaper. Nanoscale, 2015, 7, 12405-12410.	5.6	11

#	Article	IF	CITATIONS
37	Self-healing composites: A review. Cogent Engineering, 2015, 2, 1075686.	2.2	116