

Jaewoon Kwon

List of Publications by Year in descending order

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Version: 2024-02-01

5
papers

51
citations

2682572

2
h-index

2917675

2
g-index

5
all docs

5
docs citations

5
times ranked

41
citing authors

#	ARTICLE	IF	CITATIONS
1	A Natural Adaptive Control Law for Robot Manipulators. , 2018, , .		18
2	A hybrid dynamic model for the AMBIDEX tendon-driven manipulator. Mechatronics, 2020, 69, 102398.	3.3	17
3	Kinodynamic Model Identification: A Unified Geometric Approach. IEEE Transactions on Robotics, 2021, 37, 1100-1114.	10.3	15
4	On the encoding capacity of human motor adaptation. Journal of Neurophysiology, 2021, 126, 123-139.	1.8	1
5	Physically Consistent Lie Group Mesh Models for Robot Design and Motion Co-Optimization. IEEE Robotics and Automation Letters, 2022, 7, 9501-9508.	5.1	0