

# Jaehwan Park

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/6738047/publications.pdf>

Version: 2024-02-01

5  
papers

43  
citations

2682572

2  
h-index

2917675

2  
g-index

5  
all docs

5  
docs citations

5  
times ranked

47  
citing authors

#	ARTICLE	IF	CITATIONS
1	Anti-sway trajectory generation of incompletely restrained wire-suspended system. Journal of Mechanical Science and Technology, 2013, 27, 3171-3176.	1.5	16
2	Impedance control of quadruped robot and its impedance characteristic modulation for trotting on irregular terrain. , 2012, , .		15
3	A wearable robotic orthosis with a spring-assist actuator. , 2016, 2016, 5051-5054.		5
4	Design and Control of a Powered Lower Limb Orthosis Using a Cable-Differential Mechanism, COWALK-Mobile 2. IEEE Access, 2021, 9, 43775-43784.	4.2	4
5	A robotic orthosis with a cable-differential mechanism. , 2017, , .		3