## **Woolim Hong**

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/6728918/publications.pdf

Version: 2024-02-01

| 12<br>papers   | 124<br>citations     | 1937685<br>4<br>h-index | 1872680<br>6<br>g-index |
|----------------|----------------------|-------------------------|-------------------------|
|                |                      | 10                      |                         |
| 12<br>all docs | 12<br>docs citations | 12<br>times ranked      | 26<br>citing authors    |

| #  | Article   | IF  | CITATIONS |
|----|---|-----|-----------|
| 1  | Biomechanical Impacts of Toe Joint With Transfemoral Amputee Using a Powered Knee-Ankle Prosthesis. Frontiers in Neurorobotics, 2022, 16, 809380.   | 2.8 | 1         |
| 2  | Effect of Torso Kinematics on Gait Phase Estimation at Different Walking Speeds. Frontiers in Neurorobotics, 2022, 16, 807826.  | 2.8 | 2         |
| 3  | 3D-Printable Toe-joint Design of Prosthetic Foot. , 2021, , .   |     | 2         |
| 4  | Structural design for energy absorption during heel strike using the auxetic structure in the heel part of the prosthetic foot. , $2021$ , , .  |     | 2         |
| 5  | A Phase-Shifting Based Human Gait Phase Estimation for Powered Transfemoral Prostheses. IEEE Robotics and Automation Letters, 2021, 6, 5113-5120.   | 5.1 | 28        |
| 6  | Continuous Gait Phase Estimation Using LSTM for Robotic Transfemoral Prosthesis Across Walking Speeds. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2021, 29, 1470-1477. | 4.9 | 30        |
| 7  | Control of a Transfemoral Prosthesis on Sloped Terrain using Continuous and Nonlinear Impedance Parameters., 2021,,.  |     | 1         |
| 8  | Design of 3D printable prosthetic foot to implement nonlinear stiffness behavior of human toe joint based on finite element analysis. Scientific Reports, 2021, 11, 19780.                      | 3.3 | 9         |
| 9  | Control Framework for Sloped Walking With a Powered Transfemoral Prosthesis. Frontiers in Neurorobotics, 2021, 15, 790060.  | 2.8 | 9         |
| 10 | Impedance Control of a Transfemoral Prosthesis using Continuously Varying Ankle Impedances and Multiple Equilibria. , 2020, , .   |     | 9         |
| 11 | Consolidated control framework to control a powered transfemoral prosthesis over inclined terrain conditions. , 2019, , .   |     | 18        |
| 12 | Upslope walking with transfemoral prosthesis using optimization based spline generation. , 2016, , .  |     | 13        |