

# Guru Subramani

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/6719071/publications.pdf>

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4  
papers

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citations

3311381

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3475538

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51  
citing authors

#	ARTICLE	IF	CITATIONS
1	Tackling friction - an analytical modeling approach to understanding friction in single tendon driven continuum manipulators. , 2015, , .		22
2	Characterizing Input Methods for Human-to-Robot Demonstrations. , 2019, , .		7
3	Recognizing Geometric Constraints in Human Demonstrations Using Force and Position Signals. IEEE Robotics and Automation Letters, 2018, 3, 1252-1259.	5.1	6
4	Supplementary Material for Characterizing Input Methods for Human-to-Robot Demonstrations. , 2019, , .		1