

Hitoshi Maekawa

List of Publications by Year in descending order

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2682572

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docs citations

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33
citing authors

#	ARTICLE	IF	CITATIONS
1	Dynamic Grasping Force Control Using Tactile Feedback for Grasp of Multifingered Hand. Transactions of the Society of Instrument and Control Engineers, 1996, 32, 1526-1534.	0.2	3
2	Development of a three-fingered robot hand with stiffness control capability. Mechatronics, 1992, 2, 483-494.	3.3	39
3	Grasp control for a multifingered hand with kinematic redundancy. Experiments on stable grasp by the direct compliance control method.. , 1990, 33, 546-552.		2