

Negin Lashkari

List of Publications by Year in descending order

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papers

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2258059

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docs citations

5
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84
citing authors

#	ARTICLE	IF	CITATIONS
1	Development of a Novel Robust Control Method for Formation of Heterogeneous Multiple Mobile Robots With Autonomous Docking Capability. IEEE Transactions on Automation Science and Engineering, 2020, 17, 1759-1776.	5.2	14
2	Development of Novel Motion Planning and Controls for a Series of Physically Connected Robots in Dynamic Environments. Journal of Intelligent and Robotic Systems: Theory and Applications, 2019, 95, 291-310.	3.4	6
3	Backstepping Tracking Control Design for a Tractor Robot Pulling Multiple Trailers. , 2018, , .		12
4	Development of a New Robust Controller With Velocity Estimator for Docked Mobile Robots: Theory and Experiments. IEEE/ASME Transactions on Mechatronics, 2017, 22, 1287-1298.	5.8	18
5	Optimal design of formation tracking control for a tractor-trailer robotic system with omni-directional wheels. , 2016, , .		6