

Petr Zaytsev

List of Publications by Year in descending order

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4
papers

76
citations

2682572

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2917675

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g-index

4
all docs

4
docs citations

4
times ranked

93
citing authors

#	ARTICLE	IF	CITATIONS
1	The Boundaries of Walking Stability: Viability and Controllability of Simple Models. IEEE Transactions on Robotics, 2018, 34, 336-352.	10.3	38
2	All common bipedal gaits emerge from a single passive model. Journal of the Royal Society Interface, 2018, 15, 20180455.	3.4	29
3	RAMone: A planar biped for studying the energetics of gait. , 2017, , .		6
4	Effects of Foot Stiffness and Damping on Walking Robot Performance. , 2019, , .		3