

# Bao-Ling Han

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/6603761/publications.pdf>

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#	ARTICLE	IF	CITATIONS
1	Closed-form camera pose and plane parameters estimation for moments-based visual servoing of planar objects. <i>International Journal of Advanced Robotic Systems</i> , 2022, 19, 172988062210997.	2.1	1
2	A Planning Method for Multi-Axis Point-to-Point Synchronization Based on Time Constraints. <i>IEEE Access</i> , 2020, 8, 85575-85604.	4.2	10
3	Model Predictive Control With Integral Compensation for Motion Control of Robot Manipulator in Joint and Task Spaces. <i>IEEE Access</i> , 2020, 8, 107063-107075.	4.2	17
4	Collision-Free Path Planning Method for Robots Based on an Improved Rapidly-Exploring Random Tree Algorithm. <i>Applied Sciences (Switzerland)</i> , 2020, 10, 1381.	2.5	45
5	A General Approach Based on Newton's Method and Cyclic Coordinate Descent Method for Solving the Inverse Kinematics. <i>Applied Sciences (Switzerland)</i> , 2019, 9, 5461.	2.5	5
6	Stability Criterion for Dynamic Gaits of Quadruped Robot. <i>Applied Sciences (Switzerland)</i> , 2018, 8, 2381.	2.5	12
7	Monocular-Vision-Based Autonomous Hovering for a Miniature Flying Ball. <i>Sensors</i> , 2015, 15, 13270-13287.	3.8	1