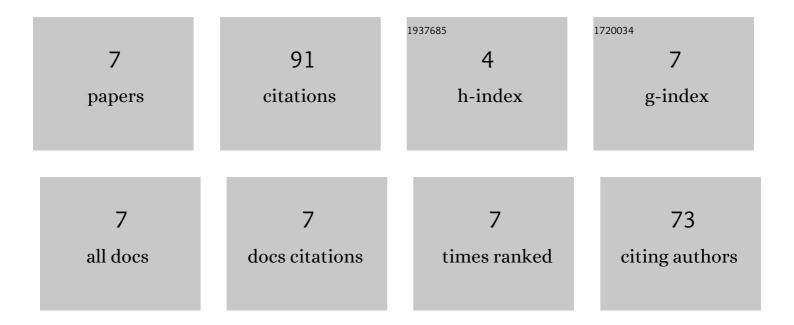
## **Bao-Ling Han**

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/6603761/publications.pdf

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RAO-LINC HAN

#	Article	IF	CITATIONS
1	Closed-form camera pose and plane parameters estimation for moments-based visual servoing of planar objects. International Journal of Advanced Robotic Systems, 2022, 19, 172988062210997.	2.1	1
2	A Planning Method for Multi-Axis Point-to-Point Synchronization Based on Time Constraints. IEEE Access, 2020, 8, 85575-85604.	4.2	10
3	Model Predictive Control With Integral Compensation for Motion Control of Robot Manipulator in Joint and Task Spaces. IEEE Access, 2020, 8, 107063-107075.	4.2	17
4	Collision-Free Path Planning Method for Robots Based on an Improved Rapidly-Exploring Random Tree Algorithm. Applied Sciences (Switzerland), 2020, 10, 1381.	2.5	45
5	A General Approach Based on Newton's Method and Cyclic Coordinate Descent Method for Solving the Inverse Kinematics. Applied Sciences (Switzerland), 2019, 9, 5461.	2.5	5
6	Stability Criterion for Dynamic Gaits of Quadruped Robot. Applied Sciences (Switzerland), 2018, 8, 2381.	2.5	12
7	Monocular-Vision-Based Autonomous Hovering for a Miniature Flying Ball. Sensors, 2015, 15, 13, 13270-13287	3.8	1