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List of Publications by Year in descending order

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| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 1 | Saturation-Tolerant Prescribed Control for a Class of MIMO Nonlinear Systems. IEEE Transactions on Cybernetics, 2022, 52, 13012-13026. | 9.5 | 22 |
| 2 | Better Than Reference in Low-Light Image Enhancement: Conditional Re-Enhancement Network. IEEE Transactions on Image Processing, 2022, 31, 759-772. | 9.8 | 18 |
| 3 | Finite-Time Adaptive Output Feedback Control for MIMO Nonlinear Systems With Actuator Faults and Saturations. IEEE Transactions on Fuzzy Systems, 2021, 29, 2256-2270. | 9.8 | 35 |
| 4 | Adaptive Neural Control for a Tilting Quadcopter with Finite-Time Convergence. , 2021, , . | | 0 |
| 5 | Adaptive neural control for a tilting quadcopter with finite-time convergence. Neural Computing and Applications, 2021, 33, 15987-16004. | 5.6 | 5 |
| 6 | Adaptive bias RBF neural network control for a robotic manipulator. Neurocomputing, 2021, 447, 213-223. | 5.9 | 54 |
| 7 | Person image generation with attention-based injection network. Neurocomputing, 2021, 460, 345-359. | 5.9 | 7 |
| 8 | Modeling and Control of a Tilting Quadcopter. IEEE Transactions on Aerospace and Electronic Systems, 2020, 56, 2823-2834. | 4.7 | 24 |
| 9 | Design of MRAC and Modified MRAC for the Turntable. , 2020, , . | | 2 |
| 10 | Adaptive Second-Order Sliding Mode Control for a Tilting Quadcopter with Input Saturations. IFAC-PapersOnLine, 2020, 53, 3910-3915. | 0.9 | 7 |
| 11 | Adaptive Neural Network Control of an Airborne Robotic Manipulator System. , 2020, , . | | 2 |
| 12 | Integrated Dynamic Modeling for a Stewart Platform. , 2018, , . | | 2 |
| 13 | Mathematical Modeling and Analysis of a Quadrotor with Tilting Propellers. , 2018, , . | | 7 |
| 14 | Fuzzy PID for Quadrotor Space Fixed-Point Position Control. , 2016, , . | | 11 |