List of Publications by Year in descending order

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#	Article	IF	CITATIONS
1	Nonlinear disturbance observer design for robotic manipulators. Control Engineering Practice, 2013, 21, 253-267.	5.5	361
2	Colonial competitive algorithm. International Journal of Intelligent Computing and Cybernetics, 2008, 1, 337-355.	2.7	211
3	Prescribed performance distance-based formation control of Multi-Agent Systems. Automatica, 2020, 119, 109086.	5.0	98
4	Teleoperation in the presence of varying time delays and sandwich linearity in actuators. Automatica, 2013, 49, 2813-2821.	5.0	59
5	Position and force tracking in nonlinear teleoperation systems under varying delays. Robotica, 2015, 33, 1003-1016.	1.9	48
6	Finite-Time Rigidity-Based Formation Maneuvering of Multiagent Systems Using Distributed Finite-Time Velocity Estimators. IEEE Transactions on Cybernetics, 2019, 49, 4473-4484.	9.5	38
7	Position and force tracking in nonlinear teleoperation systems with sandwich linearity in actuators and time-varying delay. Mechanical Systems and Signal Processing, 2017, 86, 308-324.	8.0	35
8	Nonlinear trilateral teleoperation stability analysis subjected to time-varying delays. Control Engineering Practice, 2016, 56, 123-135.	5.5	34
9	A new robust observer-based adaptive type-2 fuzzy control for a class of nonlinear systems. Applied Soft Computing Journal, 2015, 37, 204-216.	7.2	30
10	Designing MIMO PIID controller using colonial competitive algorithm: Applied to distillation column process. , 2008, , .		28
11	Adaptive Control for State Synchronization of Nonlinear Haptic Telerobotic Systems with Asymmetric Varying Time Delays. Journal of Intelligent and Robotic Systems: Theory and Applications, 2012, 68, 245-259.	3.4	24
12	Dual-user nonlinear teleoperation subjected to varying time delay and bounded inputs. ISA Transactions, 2017, 68, 33-47.	5.7	20
13	Surrounding control of nonlinear multi-agent systems with non-identical agents. ISA Transactions, 2017, 70, 219-227.	5.7	16
14	Stability analysis of the linear discrete teleoperation systems with stochastic sampling and data dropout. European Journal of Control, 2018, 41, 63-71.	2.6	12
15	A cooperative paradigm for task-space control of multilateral nonlinear teleoperation with bounded inputs and time-varying delays. Mechatronics, 2019, 62, 102255.	3.3	12
16	An adaptive robust control scheme for robot manipulators with unknown backlash nonlinearity in gears. Transactions of the Institute of Measurement and Control, 2019, 41, 2789-2802.	1.7	12
17	Task-space synchronisation of nonlinear teleoperation with time-varying delays and actuator saturation. International Journal of Control, 2020, 93, 1328-1344.	1.9	12
18	Finite-time-estimation-based surrounding control for a class of unknown nonlinear multi-agent systems. Nonlinear Dynamics, 2019, 96, 1795-1804.	5.2	11

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19	Decentralized switched model-based predictive control for distributed large-scale systems with topology switching. Nonlinear Analysis: Hybrid Systems, 2020, 38, 100912.	3.5	11
20	Controlled Synchronization of Nonlinear Teleoperation in Task-space with Time-varying Delays. International Journal of Control, Automation and Systems, 2019, 17, 1875-1883.	2.7	10
21	Leader-Follower Fixed-Time Consensus for Multi-agent Systems with Heterogeneous Non-linear Inherent Dynamics. , 2016, , .		9
22	Optimal L1 control for linear time-delayed systems using GSA algorithm. , 2016, , .		8
23	Exponential stability of bilateral sampled-data teleoperation systems using multirate approach. ISA Transactions, 2020, 105, 190-197.	5.7	8
24	Scaled Consensus Tracking Under Constant Time Delay. IFAC-PapersOnLine, 2016, 49, 240-243.	0.9	7
25	Performance tuning for robot manipulators using intelligent robust controller. Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering, 2011, 225, 385-392.	1.0	6
26	A New Method for Bilateral Teleoperation Passivity under Varying Time Delays. Mathematical Problems in Engineering, 2012, 2012, 1-19.	1.1	6
27	A new adaptive neural network based observer for robotic manipulators. , 2015, , .		6
28	Event-triggered surrounding adaptive control of nonlinear multi-agent systems. ISA Transactions, 2022, 128, 44-57.	5.7	6
29	On distance-based formation control: A nonlinear mapping approach and its applications. , 2017, , .		5
30	A New Fractional-order Control Method for Robust Synchronization Between Fractional-order Uncertain Permanent Magnet Synchronous Motors. , 2019, , .		5
31	Control for Leader–Follower Consensus of Multi-agent Systems with Actuator Faults Using Decentralized Robust Fault-tolerant Control. Iranian Journal of Science and Technology - Transactions of Electrical Engineering, 2021, 45, 529-541.	2.3	5
32	Delay-Robust Nonlinear Control of Bounded-Input Telerobotic Systems With Synchronization Enhancement. IEEE Robotics and Automation Letters, 2021, 6, 2493-2500.	5.1	5
33	Semi-Clobal Enlargement of Domain of Attraction for a Class of Affine Nonlinear Systems. , 2006, , .		5
34	Adaptive control of nonlinear teleoperation systems with varying asymmetric time delays. , 2012, , .		4
35	Consensus Control of Hierarchical Multi-agent Systems with Constant and Time-Varying Delays. Iranian Journal of Science and Technology - Transactions of Electrical Engineering, 2018, 42, 479-484.	2.3	4
36	Robust stabilization of discrete-time switched systems with state delay and parametric uncertainty via		4

model predictive control approach. , 2019, , .

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37	Optimal active suspension control based on a quarter-car model: an analytical solution. International Journal of Vehicle Safety, 2010, 5, 1.	0.2	3
38	Sensitivity analysis of the bullwhip effect in supply chains with time delay. International Journal of Systems Science: Operations and Logistics, 2023, 10, .	3.0	3
39	Distributed fault tolerant control and estimation for leader-follower consensus of multi-agent systems with actuator faults. , 2017, , .		2
40	Adaptive surrounding control for linear multi-agent systems with unknown disturbance. IOP Conference Series: Materials Science and Engineering, 2018, 361, 012024.	0.6	2
41	Robust Finite-Time Contractive Fault Tolerant Control of Uncertain Nonlinear Network-Based Systems with Adaptive Event-Triggered Communication Scheme. Iranian Journal of Science and Technology - Transactions of Electrical Engineering, 2022, 46, 141-155.	2.3	2
42	Robust event-triggered finite-time control of faulty networked flexible manipulator under external disturbance. JVC/Journal of Vibration and Control, 0, , 107754632110470.	2.6	2
43	Semi-global enlargement of domain of attraction for a class of affine nonlinear systems. , 2006, , .		1
44	Mixture weighted gating and its application to target tracking. , 2006, , .		1
45	A New Fractional Order Hold and Its Capability in Frequency Response and Zero Placement. Journal of Applied Mathematics, 2013, 2013, 1-7.	0.9	1
46	State feedback time-optimal controller for linear systems with input delay. , 2015, , .		1
47	Time Optimal Control and Switching Curve Analysis for Caputo Fractional Systems. , 2016, , .		1
48	An analytical eigenvalue assignment of linear time-delay systems using Lambert W function. , 2017, , .		1
49	Position and velocity synchronization in bilateral teleoperation in presence of stochastic disturbances in control inputs. , 2017, , .		1
50	Scaled Consensus of Multi-agent Systems under Time Delay. , 2018, , .		1
51	Novel sliding mode controller for power control of a doubly fed induction generator in variable speed wind turbine. , 2019, , .		1
52	Task-Space Position and Containment Control of Redundant Manipulators with Bounded Inputs. , 2019, , .		1
53	Extended hybrid control scheme for asynchronous switching. Journal of the Franklin Institute, 2021, 358, 1693-1714.	3.4	1
54	Further enhancement on <i>H</i> _{<i>â^ž</i>} sliding mode control design for singular Markovian jump systems with partly known transition probabilities. JVC/Journal of Vibration and Control, 2022, 28, 1187-1199.	2.6	1

#	Article	IF	CITATIONS
55	Observer-based controller design for a class of networked control systems with transmission delays and packet losses. , 2021, , .		1
56	Asymmetrical Gating with Application on Maneuvering Target Tracking. Applied Computational Intelligence and Soft Computing, 2012, 2012, 1-8.	2.3	0
57	Controller design to enlarge the domain of attraction for a class of nonlinear systems. , 2017, , .		0
58	Delay-independent Li controller for linear systems with time-varying delay. , 2017, , .		0
59	Controller design to enlarge the domain of attraction for a class of nonlinear systems. , 2017, , .		0
60	Hybrid driven based robust stabilization for networked control systems. , 2017, , .		0
61	An Optimized Controller for Region of Attraction Enlargment of Underactuated Systems Using Impulse Manifold Method. , 2018, , .		Ο
62	A new observer based Robust output feedback Controller on Coaxial Tri-copter. , 2019, , .		0
63	Economic Model Predictive Controller Design with a New Cost Function for Linear Systems. , 2021, , .		0
64	Robust stabilization of a class of switched nonlinear systems with time-varying delay and parametric uncertainty under asynchronous switching. , 2020, , .		0
65	Evaluation of efficiency of membrane submerged reactor (MSR) in water treatment using ferric chloride (FeCl3) coagulant with flocculation agents of polyelectrolyte and lime (CaO). , 0, 231, 315-328.		Ο
66	The Effect of Observer Position on Networked Control Systems with Random Transmission Delays and Packet Dropouts. , 2022, , .		0
67	Consensus Tracking of Multi-Agent Systems in The Presence of Byzantine Agents Using Model Predictive Control. , 2022, , .		0