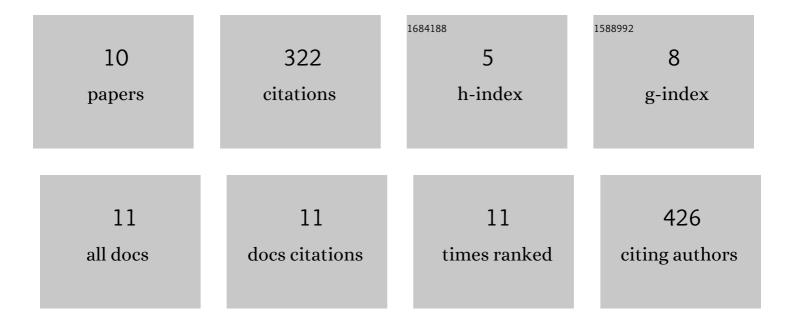
Olivier Sigaud

List of Publications by Year in descending order

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OLIVIER SIGNUD

| # | Article | IF | CITATIONS |
|----|---|-----|-----------|
| 1 | CLIC: Curriculum Learning and Imitation for Object Control in Nonrewarding Environments. IEEE Transactions on Cognitive and Developmental Systems, 2021, 13, 239-248. | 3.8 | 9 |
| 2 | Selection-Expansion: A Unifying Framework for Motion-Planning andÂDiversity Search Algorithms. Lecture Notes in Computer Science, 2021, , 568-579. | 1.3 | 0 |
| 3 | Mice adaptively generate choice variability in a deterministic task. Communications Biology, 2020, 3, 34. | 4.4 | 7 |
| 4 | PBCS: Efficient Exploration and Exploitation Using a Synergy Between Reinforcement Learning and Motion Planning. Lecture Notes in Computer Science, 2020, , 295-307. | 1.3 | 5 |
| 5 | Understanding Failures of Deterministic Actor-Critic with Continuous Action Spaces and Sparse Rewards. Lecture Notes in Computer Science, 2020, , 308-320. | 1.3 | 5 |
| 6 | Policy search in continuous action domains: An overview. Neural Networks, 2019, 113, 28-40. | 5.9 | 42 |
| 7 | The CoDyCo Project Achievements and Beyond: Toward Human Aware Whole-Body Controllers for Physical Human Robot Interaction. IEEE Robotics and Automation Letters, 2018, 3, 516-523. | 5.1 | 21 |
| 8 | Training a robot with evaluative feedback and unlabeled guidance signals. , 2016, , . | | 18 |
| 9 | Many regression algorithms, one unified model: A review. Neural Networks, 2015, 69, 60-79. | 5.9 | 139 |
| 10 | Robot Skill Learning: From Reinforcement Learning to Evolution Strategies. Paladyn, 2013, 4, . | 2.7 | 76 |