

Olivier Sigaud

List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/6483984/publications.pdf>

Version: 2024-02-01

10
papers

322
citations

1684188

5
h-index

1588992

8
g-index

11
all docs

11
docs citations

11
times ranked

426
citing authors

#	ARTICLE	IF	CITATIONS
1	Many regression algorithms, one unified model: A review. <i>Neural Networks</i> , 2015, 69, 60-79.	5.9	139
2	Robot Skill Learning: From Reinforcement Learning to Evolution Strategies. <i>Paladyn</i> , 2013, 4, .	2.7	76
3	Policy search in continuous action domains: An overview. <i>Neural Networks</i> , 2019, 113, 28-40.	5.9	42
4	The CoDyCo Project Achievements and Beyond: Toward Human Aware Whole-Body Controllers for Physical Human Robot Interaction. <i>IEEE Robotics and Automation Letters</i> , 2018, 3, 516-523.	5.1	21
5	Training a robot with evaluative feedback and unlabeled guidance signals. , 2016, , .		18
6	CLIC: Curriculum Learning and Imitation for Object Control in Nonrewarding Environments. <i>IEEE Transactions on Cognitive and Developmental Systems</i> , 2021, 13, 239-248.	3.8	9
7	Mice adaptively generate choice variability in a deterministic task. <i>Communications Biology</i> , 2020, 3, 34.	4.4	7
8	PBCS: Efficient Exploration and Exploitation Using a Synergy Between Reinforcement Learning and Motion Planning. <i>Lecture Notes in Computer Science</i> , 2020, , 295-307.	1.3	5
9	Understanding Failures of Deterministic Actor-Critic with Continuous Action Spaces and Sparse Rewards. <i>Lecture Notes in Computer Science</i> , 2020, , 308-320.	1.3	5
10	Selection-Expansion: A Unifying Framework for Motion-Planning and Diversity Search Algorithms. <i>Lecture Notes in Computer Science</i> , 2021, , 568-579.	1.3	0