Ahmad B Rad

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/6452320/publications.pdf

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| 15 | 363 | 7 | 9 |
|----------|----------------|--------------|----------------|
| papers | citations | h-index | g-index |
| 15 | 15 | 15 | 392 |
| all docs | docs citations | times ranked | citing authors |

| # | Article | IF | CITATIONS |
|----|--|------|-----------|
| 1 | Topologies and Control Schemes of Bidirectional DC–DC Power Converters: An Overview. IEEE Access, 2019, 7, 117997-118019. | 4.2 | 193 |
| 2 | An Intelligent Longitudinal Controller for Application in Semiautonomous Vehicles. IEEE Transactions on Industrial Electronics, 2010, 57, 1487-1497. | 7.9 | 55 |
| 3 | SLAM in Dynamic Environments: A Deep Learning Approach for Moving Object Tracking Using ML-RANSAC Algorithm. Sensors, 2019, 19, 3699. | 3.8 | 32 |
| 4 | $\{\{\text{mathcal L}_1\}\}$ Adaptive Control of Vehicle Lateral Dynamics. IEEE Transactions on Intelligent Vehicles, 2018, 3, 92-101. | 12.7 | 18 |
| 5 | A Robust Regression Model for Simultaneous Localization and Mapping in Autonomous Mobile Robot. Journal of Intelligent and Robotic Systems: Theory and Applications, 2008, 53, 183-202. | 3.4 | 17 |
| 6 | Autonomous humanoid robot navigation using augmented reality technique. , 2011, , . | | 10 |
| 7 | Multiâ€model direct generalised predictive control for automatic train operation system. IET Intelligent Transport Systems, 2015, 9, 86-94. | 3.0 | 8 |
| 8 | A Brain-Inspired Multi-Modal Perceptual System for Social Robots: An Experimental Realization. IEEE Access, 2018, 6, 35402-35424. | 4.2 | 8 |
| 9 | End-Point Contact Force Control with Quantitative Feedback Theory for Mobile Robots. International Journal of Advanced Robotic Systems, 2012, 9, 236. | 2.1 | 7 |
| 10 | Fuzzy Q-learning obstacle avoidance algorithm of humanoid robot in unknown environment. , 2018, , . | | 6 |
| 11 | A novel mapping strategy based on neocortex model: Pre-liminary results by hierarchical temporal memory. , 2012, , . | | 5 |
| 12 | An overriding controller for vehicle lateral control system. , 2011, , . | | 3 |
| 13 | Sensor Fusion for SLAM Based on Information Theory. Journal of Intelligent and Robotic Systems: Theory and Applications, 2010, 59, 241-267. | 3.4 | 1 |
| 14 | An Entropy Optimization Strategy for Simultaneous Localization and Mapping. Journal of Intelligent and Robotic Systems: Theory and Applications, 2010, 60, 435-455. | 3.4 | 0 |
| 15 | Weighted Multimodel Predictive Function Control for Automatic Train Operation System. Journal of Applied Mathematics, 2014, 2014, 1-8. | 0.9 | 0 |