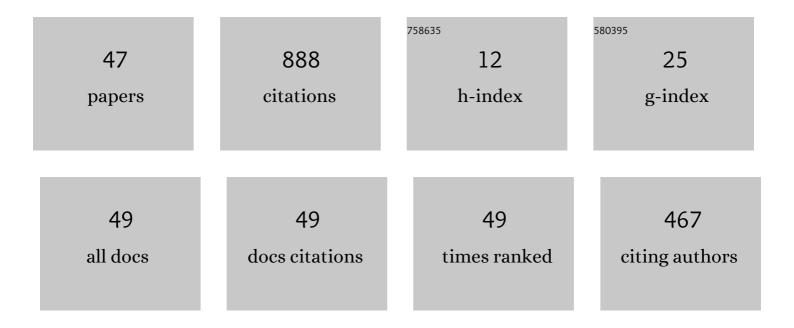
## **Ruediger Ehlers**

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/6374566/publications.pdf Version: 2024-02-01



| #  | Article  | IF  | CITATIONS |
|----|--|-----|-----------|
| 1  | Formal Verification of Piece-Wise Linear Feed-Forward Neural Networks. Lecture Notes in Computer Science, 2017, , 269-286.   | 1.0 | 266       |
| 2  | Slugs: Extensible GR(1) Synthesis. Lecture Notes in Computer Science, 2016, , 333-339.   | 1.0 | 62        |
| 3  | Supervisory control and reactive synthesis: a comparative introduction. Discrete Event Dynamic Systems: Theory and Applications, 2017, 27, 209-260.  | 0.6 | 48        |
| 4  | Unbeast: Symbolic Bounded Synthesis. Lecture Notes in Computer Science, 2011, , 272-275.   | 1.0 | 47        |
| 5  | Symbolic Bounded Synthesis. Lecture Notes in Computer Science, 2010, , 365-379.  | 1.0 | 33        |
| 6  | How to Handle Assumptions in Synthesis. Electronic Proceedings in Theoretical Computer Science, EPTCS, 0, 157, 34-50.  | 0.8 | 33        |
| 7  | Resilience to intermittent assumption violations in reactive synthesis. , 2014, , .  |     | 31        |
| 8  | Correct-by-synthesis reinforcement learning with temporal logic constraints. , 2015, , .   |     | 30        |
| 9  | Symbolic bounded synthesis. Formal Methods in System Design, 2012, 40, 232-262.  | 0.9 | 25        |
| 10 | The first reactive synthesis competition (SYNTCOMP 2014). International Journal on Software Tools for Technology Transfer, 2017, 19, 367-390.  | 1.7 | 23        |
| 11 | Formalizing and guaranteeing human-robot interaction. Communications of the ACM, 2021, 64, 78-84.  | 3.3 | 22        |
| 12 | Generalized Rabin(1) Synthesis with Applications to Robust System Synthesis. Lecture Notes in Computer Science, 2011, , 101-115.   | 1.0 | 21        |
| 13 | Correct High-level Robot Behavior in Environments with Unexpected Events. , 0, , .   |     | 20        |
| 14 | Synthesizing cooperative reactive mission plans. , 2015, , .   |     | 16        |
| 15 | Cooperative Reactive Synthesis. Lecture Notes in Computer Science, 2015, , 394-410.  | 1.0 | 16        |
| 16 | Minimising Deterministic Büchi Automata Precisely Using SAT Solving. Lecture Notes in Computer<br>Science, 2010, , 326-332.  | 1.0 | 15        |
| 17 | Fully Symbolic Timed Model Checking Using Constraint Matrix Diagrams. , 2010, , .  |     | 14        |
| 18 | Bridging the Gap between Supervisory Control and Reactive Synthesis: Case of Full Observation and<br>Centralized Control. IFAC Postprint Volumes IPPV / International Federation of Automatic Control,<br>2014, 47, 222-227. | 0.4 | 14        |

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| #  | Article  | IF  | CITATIONS |
|----|--|-----|-----------|
| 19 | Synthia: Verification and Synthesis for Timed Automata. Lecture Notes in Computer Science, 2011, ,<br>649-655.   | 1.0 | 14        |
| 20 | Special Session: Embedded Software for Robotics: Challenges and Future Directions. , 2018, , .   |     | 9         |
| 21 | Low-Effort Specification Debugging and Analysis. Electronic Proceedings in Theoretical Computer Science, EPTCS, 0, 157, 117-133.                                   | 0.8 | 9         |
| 22 | Short Witnesses and Accepting Lassos in ω-Automata. Lecture Notes in Computer Science, 2010, , 261-272.  | 1.0 | 9         |
| 23 | Shortcut through an evil door: Optimality of correct-by-construction controllers in adversarial environments. , 2013, , .  |     | 8         |
| 24 | Estimator-based reactive synthesis under incomplete information. , 2015, , .   |     | 8         |
| 25 | Resilient, Provably-Correct, and High-Level Robot Behaviors. IEEE Transactions on Robotics, 2018, 34, 936-952.   | 7.3 | 8         |
| 26 | On the Virtue of Patience: Minimizing Büchi Automata. Lecture Notes in Computer Science, 2010, ,<br>129-145.   | 1.0 | 8         |
| 27 | Synthesis with Identifiers. Lecture Notes in Computer Science, 2014, , 415-433.  | 1.0 | 8         |
| 28 | Engineering Human–Machine Teams for Trusted Collaboration. Big Data and Cognitive Computing,<br>2020, 4, 35.   | 2.9 | 7         |
| 29 | Model Checking the FlexRay Physical Layer Protocol. Lecture Notes in Computer Science, 2010, , 132-147.  | 1.0 | 7         |
| 30 | ALLQBF Solving by Computational Learning. Lecture Notes in Computer Science, 2012, , 370-384.  | 1.0 | 7         |
| 31 | Monitoring Realizability. Lecture Notes in Computer Science, 2012, , 427-441.  | 1.0 | 6         |
| 32 | Experimental Aspects of Synthesis. Electronic Proceedings in Theoretical Computer Science, EPTCS, 0, 50, 1-16.   | 0.8 | 6         |
| 33 | CEGAR-based EF synthesis of Boolean functions with an application to circuit rectification. , 2017, , .  |     | 5         |
| 34 | Automated generation of dynamics-based runtime certificates for high-level control. Discrete Event<br>Dynamic Systems: Theory and Applications, 2017, 27, 371-405. | 0.6 | 5         |
| 35 | ACTL â^© LTL Synthesis. Lecture Notes in Computer Science, 2012, , 39-54.  | 1.0 | 5         |
| 36 | Reactive Safety. Electronic Proceedings in Theoretical Computer Science, EPTCS, 0, 54, 178-191.  | 0.8 | 5         |

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| #  | Article  | IF  | CITATIONS |
|----|--|-----|-----------|
| 37 | Sparse Positional Strategies for Safety Games. Electronic Proceedings in Theoretical Computer Science, EPTCS, 0, 84, 1-16.                           | 0.8 | 4         |
| 38 | A Fragment of Linear Temporal Logic for Universal Very Weak Automata. Lecture Notes in Computer<br>Science, 2018, , 335-351.                         | 1.0 | 3         |
| 39 | Reactive Synthesis of Graphical User Interface Glue Code. Lecture Notes in Computer Science, 2019, , 387-403.  | 1.0 | 1         |
| 40 | Making the Right Cut in Model Checking Data-Intensive Timed Systems. Lecture Notes in Computer Science, 2010, , 565-580.                             | 1.0 | 1         |
| 41 | FlexRay for Avionics: Automatic Verification with Parametric Physical Layers. , 2012, , .  |     | 0         |
| 42 | Risk-averse control of Markov decision processes with ω-regular objectives. , 2016, , .  |     | 0         |
| 43 | Adapting to the Behavior of Environments with Bounded Memory. Electronic Proceedings in Theoretical Computer Science, EPTCS, 0, 346, 52-66.          | 0.8 | 0         |
| 44 | A Tool That Incrementally Approximates Finite Satisfiability in Full Interval Temporal Logic. Lecture<br>Notes in Computer Science, 2014, , 360-366. | 1.0 | 0         |
| 45 | Path-Based Program Repair. Electronic Proceedings in Theoretical Computer Science, EPTCS, 0, 178, 22-32.   | 0.8 | 0         |
| 46 | How Hard Is Finding Shortest Counter-Example Lassos in Model Checking?. Lecture Notes in Computer Science, 2019, , 245-261.                          | 1.0 | 0         |
| 47 | SAT Solving with Fragmented Hamiltonian Path Constraints for Wire Arc Additive Manufacturing.<br>Lecture Notes in Computer Science, 2020, , 492-500. | 1.0 | 0         |