

# Raquel Ros

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/6365290/publications.pdf>

Version: 2024-02-01

25  
papers

631  
citations

1040056

9  
h-index

1372567

10  
g-index

26  
all docs

26  
docs citations

26  
times ranked

628  
citing authors

#	ARTICLE	IF	CITATIONS
1	An Educational, Semi-autonomous Telepresence Robot Called Sally. Lecture Notes in Computer Science, 2022, , 142-157.	1.3	0
2	The Maze of Realizing Empathy with Social Robots. , 2020, , .		3
3	Editorial: Towards Real World Impacts: Design, Development, and Deployment of Social Robots in the Wild. Frontiers in Robotics and AI, 2020, 7, 600830.	3.2	6
4	Exploration of a Robot-based Adaptive Cognitive Stimulation System for the Elderly. , 2020, , .		4
5	A Motivational Approach to Support Healthy Habits in Long-term Child-Robot Interaction. International Journal of Social Robotics, 2016, 8, 599-617.	4.6	12
6	Behavioral accommodation towards a dance robot tutor. , 2014, , .		10
7	Adaptive human-robot interaction in sensorimotor task instruction: From human to robot dance tutors. Robotics and Autonomous Systems, 2014, 62, 707-720.	5.1	58
8	Grounding the Interaction: Anchoring Situated Discourse in Everyday Human-Robot Interaction. International Journal of Social Robotics, 2012, 4, 181-199.	4.6	63
9	Towards an open-source social middleware for humanoid robots. , 2011, , .		10
10	What are you talking about? Grounding dialogue in a perspective-aware robotic architecture. , 2011, , .		8
11	Child-robot interaction in the wild. , 2011, , .		69
12	Situation assessment for human-robot interactive object manipulation. , 2011, , .		25
13	Adapting robot behavior to user's capabilities. , 2011, , .		5
14	Analysing the Behaviour of Robot Teams through Relational Sequential Pattern Mining. Lecture Notes in Computer Science, 2011, , 163-169.	1.3	0
15	Solving ambiguities with perspective taking. , 2010, , .		2
16	ORO, a knowledge management platform for cognitive architectures in robotics. , 2010, , .		91
17	Which one? Grounding the referent based on efficient human-robot interaction. , 2010, , .		54
18	Solving ambiguities with perspective taking. , 2010, , .		2

#	ARTICLE	IF	CITATIONS
19	A case-based approach for coordinated action selection in robot soccer. Artificial Intelligence, 2009, 173, 1014-1039.	5.8	61
20	Improving Reinforcement Learning by Using Case Based Heuristics. Lecture Notes in Computer Science, 2009, , 75-89.	1.3	23
21	Executing multi-robot cases through a single coordinator. , 2007, , .		8
22	Team Playing Behavior in Robot Soccer: A Case-Based Reasoning Approach. Lecture Notes in Computer Science, 2007, , 46-60.	1.3	15
23	A Negotiation Meta Strategy Combining Trade-off and Concession Moves. Autonomous Agents and Multi-Agent Systems, 2006, 12, 163-181.	2.1	67
24	Retrieving and Reusing Game Plays for Robot Soccer. Lecture Notes in Computer Science, 2006, , 47-61.	1.3	18
25	Experimental analysis of negotiation meta strategies. , 2005, , .		0