Valter J S Leite

List of Publications by Year in descending order

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9	90	1,092	17		30
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	92	92	92		697
all	docs	docs citations	times ranked		citing authors

#	Article	IF	CITATIONS
1	An improved lmi condition for robust D-stability of uncertain polytopic systems. IEEE Transactions on Automatic Control, 2003, 48, 500-504.	3.6	171
2	Hâ^ž guaranteed cost computation by means of parameter-dependent Lyapunov functions. Automatica, 2004, 40, 1053-1061.	3.0	79
3	LMI approach for â,, â^ž linear parameter-varying state feedback control. IET Control Theory and Applications, 2005, 152, 195-201.	1.7	73
4	State feedback control of switched linear systems: An LMI approach. Journal of Computational and Applied Mathematics, 2006, 194, 192-206.	1.1	70
5	Fuzzy dynamic output feedback control through nonlinear Takagi–Sugeno models. Fuzzy Sets and Systems, 2015, 263, 92-111.	1.6	66
6	Fault tolerant control for linear parameter varying systems: An improved robust virtual actuator and sensor approach. ISA Transactions, 2020, 104, 356-369.	3.1	34
7	ISS Robust Stabilization of State-Delayed Discrete-Time Systems With Bounded Delay Variation and Saturating Actuators. IEEE Transactions on Automatic Control, 2019, 64, 3913-3919.	3.6	31
8	Anti-windup TS Fuzzy PI-like Control for Discrete-Time Nonlinear Systems with Saturated Actuators. International Journal of Fuzzy Systems, 2020, 22, 46-61.	2.3	31
9	Robust control through piecewise Lyapunov functions for discrete time-varying uncertain systems. International Journal of Control, 2004, 77, 230-238.	1.2	27
10	Global non-quadratic <mml:math altimg="si2.gif" overflow="scroll" xmlns:mml="http://www.w3.org/1998/Math/MathML"><mml:mi mathvariant="bold-script">D</mml:mi></mml:math> -stabilization of Takagiâ€"Sugeno systems with piecewise continuous membership functions. Applied Mathematics and Computation, 2019, 351, 23-36.	1.4	26
11	2guaranteed cost computation by means of parameter dependent Lyapunov functions. International Journal of Systems Science, 2004, 35, 305-315.	3.7	23
12	Robust Stabilization of Discrete-Time Systems with Time-Varying Delay: An LMI Approach. Mathematical Problems in Engineering, 2008, 2008, 1-15.	0.6	23
13	Gain scheduled state feedback control of discrete-time systems with time-varying uncertainties: an LMI approach. , 0, , .		22
14	Local stabilization of nonlinear discrete-time systems with time-varying delay in the states and saturating actuators. Information Sciences, 2020, 518, 272-285.	4.0	22
15	Improved robustâ,, «â^žcontrol for neutral systems via discretised Lyapunov-Krasovskii functional. International Journal of Control, 2008, 81, 1462-1474.	1.2	20
16	Robust stabilization of polytopic discrete-time systems with time-varying state delay: A convex approach. Journal of the Franklin Institute, 2011, 348, 568-588.	1.9	19
17	Robust HFormula state feedback control of discrete-time systems with state delay: an LMI approach. IMA Journal of Mathematical Control and Information, 2009, 26, 357-373.	1.1	18
18	Delayâ€dependent robust â,, â^ž filter design for stateâ€delayed discreteâ€time linear systems via homogeneous polynomial matrices. IET Control Theory and Applications, 2013, 7, 125-135.	1.2	18

#	Article	IF	Citations
19	Delay Dependent Local Stabilization Conditions for Time-delay Nonlinear Discrete-time Systems Using Takagi-Sugeno Models. International Journal of Control, Automation and Systems, 2018, 16, 1435-1447.	1.6	18
20	Pole location control design of an active suspension system with uncertain parameters. Vehicle System Dynamics, 2005, 43, 561-579.	2.2	16
21	Local Stabilization of Time-Delay Nonlinear Discrete-Time Systems Using Takagi-Sugeno Models and Convex Optimization. Mathematical Problems in Engineering, 2014, 2014, 1-10.	0.6	16
22	Local Sampled-Data Controller Design for T-S Fuzzy Systems With Saturated Actuators. , 2021, 5, 1169-1174.		16
23	Nonlinear Model Predictive Control on SE(3) for Quadrotor Aggressive Maneuvers. Journal of Intelligent and Robotic Systems: Theory and Applications, 2021, 101, 1.	2.0	16
24	An LMI characterization of polynomial parameter-dependent Lyapunov functions for robust stability. , 0, , .		11
25	Evolving granular feedback linearization: Design, analysis, and applications. Applied Soft Computing Journal, 2020, 86, 105927.	4.1	11
26	Co-design of an event-triggered dynamic output feedback controller for discrete-time LPV systems with constraints. Journal of the Franklin Institute, 2022, 359, 697-718.	1.9	10
27	Event-triggered policy for dynamic output stabilization of discrete-time LPV systems under input constraints. Systems and Control Letters, 2021, 153, 104950.	1.3	10
28	Robust stabilization of polytopic discrete-time systems with time-varying delay in the states. , 2010, , .		9
29	ISS Stabilization of Discrete-time LPV Systems with Interval Time-varying State Delay and Saturating Actuators. IFAC-PapersOnLine, 2018, 51, 143-148.	0.5	9
30	Robust performance for uncertain systems via Lyapunov functions with higher order terms. Journal of the Franklin Institute, 2019, 356, 3072-3089.	1.9	9
31	Robust Local Stabilization of Discrete-Time Systems with Time-Varying State Delay and Saturating Actuators. Mathematical Problems in Engineering, 2018, 2018, 1-9.	0.6	8
32	Nonlinear Model Predictive Control on SE(3) for Quadrotor Trajectory Tracking and Obstacle Avoidance. , $2019, \ldots$		8
33	Affordable Control Platform with MPC Application. Studies in Informatics and Control, 2018, 27, 265-274.	0.6	8
34	Estabilidade robusta de sistemas lineares através de desigualdades matriciais lineares. Controle and Automacao, 2004, 15, 24-40.	0.2	7
35	Synthesis of output feedback controllers for a class of nonlinear parameter-varying discrete-time systems subject to actuators limitations. , 2010, , .		7
36	A Dynamic Compensator for Parameter Varying Systems Subject to Actuator Limitations applied to a T-S Fuzzy System. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 14495-14500.	0.4	7

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37	Design of a switched control with pole location constraints for a UPS system. , 2004, , .		6
38	Stabilization of time-delay nonlinear discrete-time systems with saturating actuators through T-S models. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 11000-11005.	0.4	6
39	Robust Hybrid PI Controller with a Simple Adaptation in the Integrator Reset State. IFAC-PapersOnLine, 2017, 50, 1457-1462.	0.5	6
40	Robust Stabilization of Uncertain 2-D Discrete Delayed Systems. Journal of Control, Automation and Electrical Systems, 2018, 29, 280-291.	1.2	6
41	Finsler-based Sampled-data Controller Design for Takagi-Sugeno Systems. IFAC-PapersOnLine, 2020, 53, 7965-7970.	0.5	6
42	Stabilization of discrete time-varying delay systems: A convex parameter dependent approach. , 2008, , .		5
43	Design of saturating state feedback control laws for discreteâ€time linear parameter varying systems through homogeneous polynomial parameterâ€dependent functions. International Journal of Robust and Nonlinear Control, 2021, 31, 6585-6601.	2.1	5
44	Exponential Stabilization of LPV Systems Under Magnitude and Rate Saturating Actuators. , 2022, 6, 1418-1423.		5
45	Robust fault hiding approach for T–S fuzzy systems with unmeasured premise variables. Information Sciences, 2022, 589, 690-715.	4.0	5
46	SÃntese convexa para sistemas incertos discretos no tempo com atrasos variantes. Controle and Automacao, 2008, 19, 242-255.	0.2	4
47	Robust & amp; #x210B; & lt; inf & gt; & amp; #x211E; & lt; / inf & gt; filter design for polytopic linear discrete-time delay systems via LMIs and polynomial matrices. , 2011, , .		4
48	Input-To-State Stabilization of Discrete-Time LPV Systems with Bounded Time-Varying State Delay and Saturating Actuators through a Dynamic Controller. , 2019, , .		4
49	Robust local stabilization of discrete time-varying delayed state systems under saturating actuators. Automatica, 2020, 122, 109266.	3.0	4
50	Energy-Peak Evaluation of Nonlinear Control Systems Under Neglected Dynamics. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 646-651.	0.4	3
51	Delay-dependent local stabilization of nonlinear discrete-time system using T-S models through convex optimization. , 2014, , .		3
52	Granular evolving fuzzy robust feedback linearization., 2017,,.		3
53	On the integral action of discrete-time fuzzy TS control under saturated actuator. , 2018, , .		3
54	Regional stability and stabilization of a class of linear hyperbolic systems with nonlinear quadratic dynamic boundary conditions. European Journal of Control, 2018, 43, 46-56.	1.6	3

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55	A plug-in procedure for hybridization of PI controllers. IFAC-PapersOnLine, 2019, 52, 892-897.	0.5	3
56	Evolving granular control with high-gain observers for feedback linearizable nonlinear systems. Evolving Systems, 2021, 12, 935-948.	2.4	3
57	Emulation-Based Dynamic Output-Feedback Control of Saturating Discrete-Time LPV Systems. , 2021, 5, 1549-1554.		3
58	Robust stability of time-delay continuous-time systems in polytopic domains. , 2003, , .		3
59	Regional consensus in discrete-time multi-agent systems subject to time-varying delays and saturating actuators. International Journal of Control, 2023, 96, 1457-1469.	1.2	3
60	Dynamic output compensator design for time-varying discrete time systems with delayed states. , 2010, , .		2
61	Dynamic output stabilizing design for discrete-time fuzzy systems with time-varying delay. , 2010, , .		2
62	Robust D-stabilization with minimization of the $$\alpha = 1.00$ key; and the $$\alpha = 0.00$ key; and the systems with multiple delays in the state. , 2010, , .		2
63	Multiobjective robust discrete dynamic output-feeback control synthesis based on closed-loop reference model. , $2011, \ldots$		2
64	Local â, "2-stabilization of nonlinear discrete-time systems with delayed states through T-S fuzzy models. , 2016, , .		2
65	Local stabilization of T-S fuzzy discrete-time systems with time-varying delay in the states and saturating actuators. , 2018 , , .		2
66	Dynamic controllers for local inputâ€toâ€state stabilization of discreteâ€time linear parameterâ€varying systems with delay and saturating actuators. International Journal of Robust and Nonlinear Control, 2021, 31, 131-147.	2.1	2
67	Control of constrained discrete-time systems with time-varying state delay., 2021,, 347-381.		2
68	Event-triggered Dynamic Output Feedback Controller for Discrete-time LPV Systems with Constraints. IFAC-PapersOnLine, 2021, 54, 213-218.	0.5	2
69	Regional input-to-state stabilization of fuzzy state-delayed discrete-time systems with saturating actuators. Information Sciences, 2021, 557, 250-267.	4.0	2
70	State-feedback control for continuous-time LPV systems with polynomial vector fields. IFAC-PapersOnLine, 2020, 53, 6299-6304.	0.5	2
71	Design of LPV-PI-like controller with guaranteed performance for discrete-time systems under saturating actuators. IFAC-PapersOnLine, 2020, 53, 3898-3903.	0.5	2
72	Convex robust Hâ^ž control design to discrete-time systems with time-varying delay*. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 10150-10155.	0.4	1

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73	Modeling and control of flow with dynamical boundary actions. , 2015, , .		1
74	Analysis and synthesis conditions for T-S fuzzy continuous-time systems with partially matched premises. IFAC-PapersOnLine, 2020, 53, 7989-7994.	0.5	1
75	Robust pole location for an interacting tank system with uncertain parameters. , 0, , .		O
76	Scaled Small Gain Conditions for Robust Stability of Time-Delay Systems: An LMI Approach., 2006,,.		0
77	Convex analysis and synthesis for uncertain discrete-time systems with time-varying state delay. , 2008, , .		O
78	Stability Analysis and Controller Design for Discrete-Time Fuzzy Systems With Time-Varying Delay. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 325-330.	0.4	0
79	Fuzzy control of delayed systems: Less conservative convex conditions. , 2010, , .		O
80	Uncertain Discrete-Time Systems with Delayed State: Robust Stabilization with Performance Specification via LMI Formulations. , 0, , .		0
81	Minimização do custo Hâ^ž de sistemas incertos discretos no tempo com atraso nos estados. Controle and Automacao, 2011, 22, 256-272.	0.2	O
82	Robust non-fragile $\#x210B$; $\#x221E$; $\#x221$		0
83	Numerically tractable stability tests for 2-D singular discrete-time systems. , 2013, , .		0
84	Heuristic to tune the compensation gain of modeling uncertainties through the robust multi inversion. , 2014, , .		0
85	Compensated hybrid PI controllers for sampled-data controlled systems. IFAC-PapersOnLine, 2018, 51, 240-245.	0.5	O
86	Stability and controller design for T-S fuzzy discrete-time systems with time-varying delay in the state. , 2018 , , .		0
87	Sampled-data Controller Design for Mechatronic Systems Described by Takagi-Sugeno Descriptors. , 2021, , .		O
88	Comparisons of robust methods on feedback linearization through experimental tests. IFAC-PapersOnLine, 2020, 53, 7983-7988.	0.5	0
89	Command Governor Strategy Based on Region of Attraction. Journal of Control, Automation and Electrical Systems, 0 , , 1 .	1.2	0
90	ISS control for continuousâ€time systems with filtered timeâ€varying parameter and saturating actuators. Asian Journal of Control, 0, , .	1.9	0