

Changchun Hua

List of Publications by Year in descending order

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370
papers

10,751
citations

30070

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372
all docs

372
docs citations

372
times ranked

5094
citing authors

#	ARTICLE	IF	CITATIONS
1	Robust backstepping control for a class of time delayed systems. IEEE Transactions on Automatic Control, 2005, 50, 894-899.	5.7	234
2	Adaptive Fuzzy Finite-Time Coordination Control for Networked Nonlinear Bilateral Teleoperation System. IEEE Transactions on Fuzzy Systems, 2014, 22, 631-641.	9.8	211
3	Adaptive Fuzzy Output-Feedback Controller Design for Nonlinear Time-Delay Systems With Unknown Control Direction. IEEE Transactions on Systems, Man, and Cybernetics, 2009, 39, 363-374.	5.0	205
4	Backstepping Control for Nonlinear Systems With Time Delays and Applications to Chemical Reactor Systems. IEEE Transactions on Industrial Electronics, 2009, 56, 3723-3732.	7.9	194
5	Delay-Dependent Stability Criteria of Teleoperation Systems With Asymmetric Time-Varying Delays. IEEE Transactions on Robotics, 2010, 26, 925-932.	10.3	193
6	New results on stability analysis of neural networks with time-varying delays. Physics Letters, Section A: General, Atomic and Solid State Physics, 2006, 352, 335-340.	2.1	187
7	Finite/Fixed-Time Stabilization for Nonlinear Interconnected Systems With Dead-Zone Input. IEEE Transactions on Automatic Control, 2017, 62, 2554-2560.	5.7	181
8	Optimum design of fractional order $PI^{\alpha}D^{\beta}$ controller for AVR system using chaotic ant swarm. Expert Systems With Applications, 2012, 39, 6887-6896.	7.6	168
9	Robust Output Feedback Tracking Control for Time-Delay Nonlinear Systems Using Neural Network. IEEE Transactions on Neural Networks, 2007, 18, 495-505.	4.2	164
10	Robust controller design of a class of nonlinear time delay systems via backstepping method. Automatica, 2008, 44, 567-573.	5.0	162
11	Distributed Adaptive Neural Network Output Tracking of Leader-Following High-Order Stochastic Nonlinear Multiagent Systems With Unknown Dead-Zone Input. IEEE Transactions on Cybernetics, 2017, 47, 177-185.	9.5	150
12	Adaptive Tracking Controller Design of Nonlinear Systems With Time Delays and Unknown Dead-Zone Input. IEEE Transactions on Automatic Control, 2008, 53, 1753-1759.	5.7	142
13	New Delay-Dependent Stability Criteria for Neural Networks With Time-Varying Delay Using Delay-Decomposition Approach. IEEE Transactions on Neural Networks and Learning Systems, 2014, 25, 1378-1383.	11.3	133
14	Event-Triggered Leader-Following Consensus for Nonlinear Multiagent Systems Subject to Actuator Saturation Using Dynamic Output Feedback Method. IEEE Transactions on Automatic Control, 2018, 63, 4391-4396.	5.7	130
15	Output Feedback Stabilization for Time-Delay Nonlinear Interconnected Systems Using Neural Networks. IEEE Transactions on Neural Networks, 2008, 19, 673-688.	4.2	129
16	Finite Time Control Design for Bilateral Teleoperation System With Position Synchronization Error Constrained. IEEE Transactions on Cybernetics, 2016, 46, 609-619.	9.5	128
17	A new particle swarm optimization algorithm with adaptive inertia weight based on Bayesian techniques. Applied Soft Computing Journal, 2015, 28, 138-149.	7.2	125
18	Leader-following consensus for a class of high-order nonlinear multi-agent systems. Automatica, 2016, 73, 138-144.	5.0	121

#	ARTICLE	IF	CITATIONS
19	Decentralized Output Feedback Adaptive NN Tracking Control for Time-Delay Stochastic Nonlinear Systems With Prescribed Performance. IEEE Transactions on Neural Networks and Learning Systems, 2015, 26, 2749-2759.	11.3	114
20	Adaptive control for chaotic systems. Chaos, Solitons and Fractals, 2004, 22, 55-60.	5.1	107
21	Adaptive Fuzzy Prescribed Performance Control for Nonlinear Switched Time-Delay Systems With Unmodeled Dynamics. IEEE Transactions on Fuzzy Systems, 2018, 26, 1934-1945.	9.8	105
22	Stabilization of T-S Fuzzy System With Time Delay Under Sampled-Data Control Using a New Looped-Functional. IEEE Transactions on Fuzzy Systems, 2020, 28, 400-407.	9.8	102
23	Synchronization of Chaotic Lurâ€™e Systems With Time Delays Using Sampled-Data Control. IEEE Transactions on Neural Networks and Learning Systems, 2015, 26, 1214-1221.	11.3	101
24	Fixed-time backstepping control design for high-order strict-feedback nonlinear systems via terminal sliding mode. IET Control Theory and Applications, 2017, 11, 1184-1193.	2.1	96
25	Output-Feedback Adaptive Control of Networked Teleoperation System With Time-Varying Delay and Bounded Inputs. IEEE/ASME Transactions on Mechatronics, 2015, 20, 2009-2020.	5.8	93
26	Adaptive neural network based prescribed performance control for teleoperation system under input saturation. Journal of the Franklin Institute, 2015, 352, 1850-1866.	3.4	89
27	Finite-time consensus tracking of second-order multi-agent systems via nonsingular TSM. Nonlinear Dynamics, 2014, 75, 311-318.	5.2	86
28	Adaptive Leader-Following Consensus for Second-Order Time-Varying Nonlinear Multiagent Systems. IEEE Transactions on Cybernetics, 2017, 47, 1532-1539.	9.5	86
29	Tracking differentiator and extended state observer-based nonsingular fast terminal sliding mode attitude control for a quadrotor. Nonlinear Dynamics, 2018, 94, 343-354.	5.2	86
30	Decentralized Networked Control System Design Using Tâ€™S Fuzzy Approach. IEEE Transactions on Fuzzy Systems, 2012, 20, 9-21.	9.8	81
31	Output feedback-based consensus control for nonlinear time delay multiagent systems. Automatica, 2020, 111, 108669.	5.0	81
32	Event-Based Dynamic Output Feedback Adaptive Fuzzy Control for Stochastic Nonlinear Systems. IEEE Transactions on Fuzzy Systems, 2018, 26, 3004-3015.	9.8	80
33	Dynamic multi-swarm particle swarm optimizer with cooperative learning strategy. Applied Soft Computing Journal, 2015, 29, 169-183.	7.2	72
34	A Hybrid Dynamic Event-Triggered Approach to Consensus of Multiagent Systems With External Disturbances. IEEE Transactions on Automatic Control, 2021, 66, 3213-3220.	5.7	72
35	Convergence Analysis of Teleoperation Systems With Unsymmetric Time-Varying Delays. IEEE Transactions on Circuits and Systems II: Express Briefs, 2009, 56, 240-244.	3.0	69
36	Self-Triggered Leader-Following Consensus for High-Order Nonlinear Multiagent Systems via Dynamic Output Feedback Control. IEEE Transactions on Cybernetics, 2019, 49, 2002-2010.	9.5	69

#	ARTICLE	IF	CITATIONS
37	Model Following Controller Design for Large-Scale Systems With Time-Delay Interconnections and Multiple Dead-Zone Inputs. IEEE Transactions on Automatic Control, 2011, 56, 962-968.	5.7	68
38	Teleoperation Over the Internet With/Without Velocity Signal. IEEE Transactions on Instrumentation and Measurement, 2011, 60, 4-13.	4.7	67
39	Fixed-Time Leader-Following Consensus for High-Order Time-Varying Nonlinear Multiagent Systems. IEEE Transactions on Automatic Control, 2020, 65, 5510-5516.	5.7	67
40	Smooth dynamic output feedback control for multiple time-delay systems with nonlinear uncertainties. Automatica, 2016, 68, 1-8.	5.0	66
41	Disturbance Observer-Based Finite-Time Control Design for a Quadrotor UAV With External Disturbance. IEEE Transactions on Aerospace and Electronic Systems, 2021, 57, 834-847.	4.7	66
42	Nonlinear Control for Tracking and Obstacle Avoidance of a Wheeled Mobile Robot With Nonholonomic Constraint. IEEE Transactions on Control Systems Technology, 2015, , 1-1.	5.2	65
43	Adaptive prescribed performance control of half-car active suspension system with unknown dead-zone input. Mechanical Systems and Signal Processing, 2018, 111, 135-148.	8.0	65
44	Distributed Adaptive Fuzzy Containment Control of Stochastic Pure-Feedback Nonlinear Multiagent Systems With Local Quantized Controller and Tracking Constraint. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2019, 49, 787-796.	9.3	65
45	Trajectory Tracking Control of Autonomous Underwater Vehicle With Unknown Parameters and External Disturbances. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2021, 51, 1054-1063.	9.3	65
46	Leader-Following Output Consensus for High-Order Nonlinear Multiagent Systems. IEEE Transactions on Automatic Control, 2019, 64, 1156-1161.	5.7	63
47	Parameter identification of commensurate fractional-order chaotic system via differential evolution. Physics Letters, Section A: General, Atomic and Solid State Physics, 2012, 376, 457-464.	2.1	62
48	Adaptive feedback control for a class of chaotic systems. Chaos, Solitons and Fractals, 2005, 23, 757-765.	5.1	61
49	Distributed output feedback consensus tracking prescribed performance control for a class of nonlinear multiagent systems with unknown disturbances. IET Control Theory and Applications, 2016, 10, 877-883.	2.1	61
50	Robust stabilization of a class of nonlinear time-delay systems. Applied Mathematics and Computation, 2004, 155, 737-752.	2.2	60
51	Output Feedback Distributed Containment Control for High-Order Nonlinear Multiagent Systems. IEEE Transactions on Cybernetics, 2017, 47, 2032-2043.	9.5	60
52	Neural network-based adaptive position tracking control for bilateral teleoperation under constant time delay. Neurocomputing, 2013, 113, 204-212.	5.9	59
53	Exponential stabilization controller design for interconnected time delay systems. Automatica, 2008, 44, 2600-2606.	5.0	58
54	Finite-time output-feedback synchronization control for bilateral teleoperation system via neural networks. Information Sciences, 2017, 406-407, 216-233.	6.9	57

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55	Fractional-order sliding mode control of uncertain QUAVs with time-varying state constraints. <i>Nonlinear Dynamics</i> , 2019, 95, 1347-1360.	5.2	57
56	Adaptive Prescribed-Time Control for a Class of Uncertain Nonlinear Systems. <i>IEEE Transactions on Automatic Control</i> , 2022, 67, 6159-6166.	5.7	56
57	A New Coordinated Slave Torque Feedback Control Algorithm for Network-Based Teleoperation Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2013, 18, 764-774.	5.8	55
58	Bayesian Block Structure Sparse Based T-S Fuzzy Modeling for Dynamic Prediction of Hot Metal Silicon Content in the Blast Furnace. <i>IEEE Transactions on Industrial Electronics</i> , 2018, 65, 4933-4942.	7.9	55
59	Variable structure adaptive fuzzy control for a class of nonlinear time-delay systems. <i>Fuzzy Sets and Systems</i> , 2004, 148, 453-468.	2.7	54
60	Leader-following consensus for high-order stochastic multi-agent systems via dynamic output feedback control. <i>Automatica</i> , 2019, 107, 418-424.	5.0	54
61	Output Feedback Predefined-Time Bipartite Consensus Control for High-Order Nonlinear Multiagent Systems. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , 2021, 68, 3069-3078.	5.4	54
62	Semi-global/global output consensus for nonlinear multiagent systems with time delays. <i>Automatica</i> , 2019, 103, 480-489.	5.0	53
63	Robust H_∞ stabilization for T-S fuzzy systems with time-varying delays and memory sampled-data control. <i>Applied Mathematics and Computation</i> , 2019, 346, 500-512.	2.2	52
64	Adaptive Formation Control of Cooperative Teleoperators With Intermittent Communications. <i>IEEE Transactions on Cybernetics</i> , 2019, 49, 2514-2523.	9.5	52
65	Output feedback control for interconnected time-delay systems with prescribed performance. <i>Neurocomputing</i> , 2014, 129, 208-215.	5.9	49
66	Fixed-Time Prescribed Tracking Control for Stochastic Nonlinear Systems With Unknown Measurement Sensitivity. <i>IEEE Transactions on Cybernetics</i> , 2022, 52, 3722-3732.	9.5	49
67	Adaptive fuzzy control for uncertain interconnected time-delay systems. <i>Fuzzy Sets and Systems</i> , 2005, 153, 447-458.	2.7	47
68	Neural network observer-based networked control for a class of nonlinear systems. <i>Neurocomputing</i> , 2014, 133, 103-110.	5.9	47
69	Leader-follower finite-time formation control of multiple quadrotors with prescribed performance. <i>International Journal of Systems Science</i> , 2017, 48, 2499-2508.	5.5	47
70	A Hybrid Event-Triggered Approach to Consensus of Multiagent Systems With Disturbances. <i>IEEE Transactions on Control of Network Systems</i> , 2020, 7, 1259-1271.	3.7	47
71	Dissipativity Analysis for T-S Fuzzy System Under Memory Sampled-Data Control. <i>IEEE Transactions on Cybernetics</i> , 2021, 51, 961-969.	9.5	47
72	Master-slave synchronization criteria of Lur'e systems with time-delay feedback control. <i>Applied Mathematics and Computation</i> , 2014, 244, 895-902.	2.2	46

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73	Adaptive prescribed performance control of QUAVs with unknown time-varying payload and wind gust disturbance. <i>Journal of the Franklin Institute</i> , 2018, 355, 6323-6338.	3.4	46
74	Nonfragile Consensus of Multiagent Systems Based on Memory Sampled-Data Control. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021, 51, 391-399.	9.3	46
75	A New Master-Slave Torque Design for Teleoperation System by T-S Fuzzy Approach. <i>IEEE Transactions on Control Systems Technology</i> , 2015, 23, 1611-1619.	5.2	45
76	Stability analysis of neural networks with time-varying delay using a new augmented Lyapunov-Krasovskii functional. <i>Neurocomputing</i> , 2019, 332, 1-9.	5.9	45
77	Leader-Following Consensus for High-Order Nonlinear Stochastic Multiagent Systems. <i>IEEE Transactions on Cybernetics</i> , 2017, 47, 1882-1891.	9.5	44
78	Adaptive observer-based control for a class of chaotic systems. <i>Chaos, Solitons and Fractals</i> , 2004, 22, 103-110.	5.1	43
79	Overcoming overshoot performance limitations of linear systems with reset control. <i>Automatica</i> , 2019, 101, 27-35.	5.0	43
80	New stability criteria for networked teleoperation system. <i>Information Sciences</i> , 2013, 233, 244-254.	6.9	42
81	Attitude tracking control for spacecraft formation with time-varying delays and switching topology. <i>Acta Astronautica</i> , 2016, 126, 98-108.	3.2	42
82	Output feedback NN tracking control for fractional-order nonlinear systems with time-delay and input quantization. <i>Neurocomputing</i> , 2018, 290, 229-237.	5.9	42
83	Robust Adaptive Controller Design for Nonlinear Time-Delay Systems via T-S Fuzzy Approach. <i>IEEE Transactions on Fuzzy Systems</i> , 2009, 17, 901-910.	9.8	41
84	Leader-following consensus for multi-agent systems subject to actuator saturation with switching topologies and time-varying delays. <i>IET Control Theory and Applications</i> , 2016, 10, 144-150.	2.1	41
85	Output feedback tracking control for nonlinear time-delay systems with tracking errors and input constraints. <i>Neurocomputing</i> , 2016, 173, 751-758.	5.9	41
86	Decentralized robust model reference adaptive control for interconnected time-delay systems. <i>Journal of Computational and Applied Mathematics</i> , 2006, 193, 383-396.	2.0	40
87	Memoryless State Feedback Controller Design for Time Delay Systems With Matched Uncertain Nonlinearities. <i>IEEE Transactions on Automatic Control</i> , 2008, 53, 801-807.	5.7	39
88	An improved krill herd algorithm: Krill herd with linear decreasing step. <i>Applied Mathematics and Computation</i> , 2014, 234, 356-367.	2.2	39
89	Synchronization of chaotic systems based on PI observer design. <i>Physics Letters, Section A: General, Atomic and Solid State Physics</i> , 2005, 334, 382-389.	2.1	38
90	Decentralized MRAC for large-scale interconnected systems with time-varying delays and applications to chemical reactor systems. <i>Journal of Process Control</i> , 2012, 22, 1985-1996.	3.3	37

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91	Attitude control of reusable launch vehicle in reentry phase with input constraint via robust adaptive backstepping control. <i>International Journal of Adaptive Control and Signal Processing</i> , 2015, 29, 1308-1327.	4.1	37
92	An Exact Stability Condition for Bilateral Teleoperation With Delayed Communication Channel. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2016, 46, 434-439.	9.3	37
93	Leader-Following Consensus of Multiagent Systems via Asynchronous Sampled-Data Control: A Hybrid System Approach. <i>IEEE Transactions on Automatic Control</i> , 2022, 67, 2568-2575.	5.7	37
94	Robust tracking control for wheeled mobile robot based on extended state observer. <i>Advanced Robotics</i> , 2016, 30, 68-78.	1.8	35
95	Stability analysis of time-delay systems via free-matrix-based double integral inequality. <i>International Journal of Systems Science</i> , 2017, 48, 257-263.	5.5	35
96	Adaptive Neural Tracking Control for Interconnected Switched Systems With Non-ISS Unmodeled Dynamics. <i>IEEE Transactions on Cybernetics</i> , 2019, 49, 1669-1679.	9.5	35
97	A new chaotic secure communication scheme. <i>Physics Letters, Section A: General, Atomic and Solid State Physics</i> , 2005, 342, 305-308.	2.1	34
98	Robust controller design for uncertain multiple-delay systems with unknown actuator parameters. <i>Automatica</i> , 2012, 48, 211-218.	5.0	34
99	On Exploring the Domain of Attraction for Bilateral Teleoperator Subject to Interval Delay and Saturated P + d Control Scheme. <i>IEEE Transactions on Automatic Control</i> , 2017, 62, 2923-2928.	5.7	34
100	Fuzzy Classifier Design for Development Tendency of Hot Metal Silicon Content in Blast Furnace. <i>IEEE Transactions on Industrial Informatics</i> , 2018, 14, 1115-1123.	11.3	34
101	Cooperative Stabilization for Linear Switched Systems With Asynchronous Switching. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2019, 49, 1081-1087.	9.3	34
102	Necessary and Sufficient Stability Criteria for a Class of Fractional-Order Delayed Systems. <i>IEEE Transactions on Circuits and Systems II: Express Briefs</i> , 2014, 61, 59-63.	3.0	32
103	Analysis and design for delta operator systems with actuator saturation. <i>International Journal of Control</i> , 2014, 87, 987-999.	1.9	32
104	Finite-time synchronization control for bilateral teleoperation under communication delays. <i>Robotics and Computer-Integrated Manufacturing</i> , 2015, 31, 61-69.	9.9	31
105	Distributed formation control for teleoperating cyber-physical system under time delay and actuator saturation constrains. <i>Information Sciences</i> , 2016, 370-371, 680-694.	6.9	31
106	Formation Control of Teleoperating Cyber-Physical System With Time Delay and Actuator Saturation. <i>IEEE Transactions on Control Systems Technology</i> , 2018, 26, 1458-1467.	5.2	31
107	Disturbance observer-based fixed-time prescribed performance tracking control for robotic manipulator. <i>International Journal of Systems Science</i> , 2019, 50, 2437-2448.	5.5	31
108	Distributed Adaptive Event-Triggered Control for Leader-Following Consensus of Multi-Agent Systems. <i>Asian Journal of Control</i> , 2017, 19, 2155-2164.	3.0	30

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109	Multivariable sliding mode backstepping controller design for quadrotor UAV based on disturbance observer. <i>Science China Information Sciences</i> , 2018, 61, 1.	4.3	30
110	Pricing Mechanism With Noncooperative Game and Revenue Sharing Contract in Electricity Market. <i>IEEE Transactions on Cybernetics</i> , 2019, 49, 97-106.	9.5	30
111	Event-Triggered/Self-Triggered Leader-Following Control of Stochastic Nonlinear Multiagent Systems Using High-Gain Method. <i>IEEE Transactions on Cybernetics</i> , 2021, 51, 2969-2978.	9.5	30
112	Decentralized event-triggered control for interconnected time-delay stochastic nonlinear systems using neural networks. <i>Neurocomputing</i> , 2018, 272, 270-278.	5.9	29
113	Dual-loop integral sliding mode control for robust trajectory tracking of a quadrotor. <i>International Journal of Systems Science</i> , 2020, 51, 203-216.	5.5	29
114	Distributed Event-Triggered Consensus of Multiagent Systems With Communication Delays: A Hybrid System Approach. <i>IEEE Transactions on Cybernetics</i> , 2020, 50, 3169-3181.	9.5	28
115	Output feedback prescribed performance control for interconnected time-delay systems with unknown Prandtl–Ishlinskii hysteresis. <i>Journal of the Franklin Institute</i> , 2015, 352, 2750-2764.	3.4	27
116	Disturbance observer based robust backstepping control design of flexible air-breathing hypersonic vehicle. <i>IET Control Theory and Applications</i> , 2019, 13, 572-583.	2.1	27
117	Decentralized Adaptive Output Feedback Fault Detection and Control for Uncertain Nonlinear Interconnected Systems. <i>IEEE Transactions on Cybernetics</i> , 2020, 50, 935-945.	9.5	27
118	Application of grey wolf optimisation algorithm in parameter calculation of overhead transmission line system. <i>IET Science, Measurement and Technology</i> , 2021, 15, 218-231.	1.6	27
119	Distributed adaptive output feedback containment control for time-delay nonlinear multiagent systems. <i>Automatica</i> , 2021, 127, 109545.	5.0	27
120	Synchronization control for bilateral teleoperation system with prescribed performance under asymmetric time delay. <i>Nonlinear Dynamics</i> , 2015, 81, 481-493.	5.2	26
121	Finite-Time Observer-Based Leader-Following Consensus for Nonlinear Multiagent Systems With Input Delays. <i>IEEE Transactions on Cybernetics</i> , 2021, 51, 5850-5858.	9.5	26
122	Full state constraints-based adaptive tracking control for uncertain nonlinear stochastic systems with input saturation. <i>Journal of the Franklin Institute</i> , 2020, 357, 5125-5142.	3.4	26
123	Robust passivity analysis for uncertain neural networks with discrete and distributed time-varying delays. <i>Neurocomputing</i> , 2019, 364, 330-337.	5.9	25
124	Improved Modulation Strategy for Single-Phase Cascaded H-Bridge Multilevel Inverter. <i>IEEE Transactions on Power Electronics</i> , 2022, 37, 2470-2474.	7.9	25
125	Adaptive Full-State-Constrained Control of Nonlinear Systems With Deferred Constraints Based on Nonbarrier Lyapunov Function Method. <i>IEEE Transactions on Cybernetics</i> , 2022, 52, 7634-7642.	9.5	25
126	Decentralized output feedback controller design for nonlinear interconnected systems with unknown control direction and time-varying delays. <i>International Journal of Adaptive Control and Signal Processing</i> , 2014, 28, 1160-1173.	4.1	24

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127	Decentralised fault-tolerant finite-time control for a class of interconnected non-linear systems. IET Control Theory and Applications, 2015, 9, 2331-2339.	2.1	24
128	Finite-time consensus control for second-order multi-agent systems without velocity measurements. International Journal of Systems Science, 2017, 48, 337-346.	5.5	24
129	Distributed Adaptive Output Feedback Leader-Following Consensus Control for Nonlinear Multiagent Systems. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2020, 50, 4309-4317.	9.3	24
130	Event-Triggered Iterative Learning Containment Control of Model-Free Multiagent Systems. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2021, 51, 7719-7726.	9.3	24
131	Comments on "State Feedback Stabilization for a Class of Stochastic Time-Delay Nonlinear Systems". IEEE Transactions on Automatic Control, 2004, 49, 1216-1216.	5.7	23
132	Adaptive fuzzy synchronization control for networked teleoperation system with input and multi-state constraints. Journal of the Franklin Institute, 2016, 353, 2814-2834.	3.4	23
133	Data-Driven Bayesian-Based Takagi-Sugeno Fuzzy Modeling for Dynamic Prediction of Hot Metal Silicon Content in Blast Furnace. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2022, 52, 1087-1099.	9.3	23
134	Delay-Dependent Stability for Load Frequency Control System via Linear Operator Inequality. IEEE Transactions on Cybernetics, 2022, 52, 6984-6992.	9.5	23
135	Decentralized output feedback adaptive NN tracking control of interconnected nonlinear time-delay systems with prescribed performance. Neurocomputing, 2016, 174, 885-896.	5.9	22
136	Decentralized adaptive tracking quantized control for interconnected pure feedback time delay nonlinear systems. Journal of the Franklin Institute, 2018, 355, 2313-2328.	3.4	22
137	Adaptive synchronization control design for flexible telerobotics with actuator fault and input saturation. International Journal of Robust and Nonlinear Control, 2018, 28, 1016-1034.	3.7	22
138	Real-time detection of flame and smoke using an improved YOLOv4 network. Signal, Image and Video Processing, 2022, 16, 1109-1116.	2.7	22
139	Bilateral Teleoperation Design With/Without Gravity Measurement. IEEE Transactions on Instrumentation and Measurement, 2012, 61, 3136-3146.	4.7	21
140	Finite-time coordination control for networked bilateral teleoperation. Robotica, 2015, 33, 451-462.	1.9	21
141	Improved approach to delay-dependent stability and stabilisation of two-dimensional discrete-time systems with interval time-varying delays. IET Control Theory and Applications, 2015, 9, 1839-1845.	2.1	21
142	Multi-manipulators coordination for bilateral teleoperation system using fixed-time control approach. International Journal of Robust and Nonlinear Control, 2018, 28, 5667-5687.	3.7	21
143	A Mobile Anchor Node Assisted RSSI Localization Scheme in Underwater Wireless Sensor Networks. Sensors, 2019, 19, 4369.	3.8	21
144	Disturbance observer-based output feedback control for uncertain QUAVs with input saturation. Neurocomputing, 2020, 413, 96-106.	5.9	21

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145	A Novel MIMO Tâ€‘S Fuzzy Modeling for Prediction of Blast Furnace Molten Iron Quality With Missing Outputs. IEEE Transactions on Fuzzy Systems, 2021, 29, 1654-1666.	9.8	21
146	Observer-based adaptive control for uncertain time-delay systems. Information Sciences, 2006, 176, 201-214.	6.9	20
147	New Exponential Stability Criteria for Neural Networks With Time-Varying Delay. IEEE Transactions on Circuits and Systems II: Express Briefs, 2011, 58, 931-935.	3.0	20
148	Robust adaptive uniform exact tracking control for uncertain Eulerâ€‘Lagrange system. International Journal of Control, 2017, 90, 2711-2720.	1.9	20
149	Integrated Localization and Tracking for AUV With Model Uncertainties via Scalable Sampling-Based Reinforcement Learning Approach. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2022, 52, 6952-6967.	9.3	20
150	Event-Based Finite-Time Control for High-Order Interconnected Nonlinear Systems With Asymmetric Output Constraints. IEEE Transactions on Automatic Control, 2022, 67, 6135-6142.	5.7	20
151	Robust control of time-delay chaotic systems. Physics Letters, Section A: General, Atomic and Solid State Physics, 2003, 314, 72-80.	2.1	19
152	Robust output feedback control for fractional order nonlinear systems with time-varying delays. IEEE/CAA Journal of Automatica Sinica, 2016, 3, 477-482.	13.1	19
153	Modeling of the hot metal silicon content in blast furnace using support vector machine optimized by an improved particle swarm optimizer. Neural Computing and Applications, 2016, 27, 1451-1461.	5.6	19
154	Discrete-Time MIMO Reset Controller and Its Application to Networked Control Systems. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2018, 48, 2485-2494.	9.3	19
155	Distributed Output-Feedback Adaptive Fuzzy Leader-Following Consensus of Stochastic Nonlinear Interconnected Multiagent Systems. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2022, 52, 311-323.	9.3	19
156	Stabilization and Data-Rate Condition for Stability of Networked Control Systems With Denial-of-Service Attacks. IEEE Transactions on Cybernetics, 2022, 52, 700-711.	9.5	19
157	Distributed Containment Control for Nonlinear Stochastic Multiagent Systems. IEEE Transactions on Cybernetics, 2021, 51, 3361-3370.	9.5	19
158	Distributed Output-Feedback Consensus Control of Multiagent Systems with Unknown Output Measurement Sensitivity. IEEE Transactions on Automatic Control, 2021, 66, 3303-3310.	5.7	19
159	Exponential synchronization of the switched uncertain neural networks with mixed delays based on sampled-data control. Journal of the Franklin Institute, 2022, 359, 2259-2282.	3.4	19
160	Ill-posed Echo State Network based on L-curve Method for Prediction of Blast Furnace Gas Flow. Neural Processing Letters, 2016, 43, 97-113.	3.2	18
161	Disturbance observerâ€‘based dynamic surface control design for a hypersonic vehicle with input constraints and uncertainty. Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering, 2016, 230, 522-536.	1.0	18
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