

Laura Marchal-Crespo

List of Publications by Year in descending order

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Version: 2024-02-01

61
papers

2,593
citations

394390

19
h-index

289230

40
g-index

68
all docs

68
docs citations

68
times ranked

2480
citing authors

#	ARTICLE	IF	CITATIONS
1	Effect of immersive visualization technologies on cognitive load, motivation, usability, and embodiment. <i>Virtual Reality</i> , 2023, 27, 307-331.	6.1	32
2	Hiding Assistive Robots During Training in Immersive VR Does Not Affect Users'™ Motivation, Presence, Embodiment, Performance, Nor Visual Attention. <i>IEEE Transactions on Neural Systems and Rehabilitation Engineering</i> , 2022, 30, 390-399.	4.9	7
3	Towards functional robotic training: motor learning of dynamic tasks is enhanced by haptic rendering but hampered by arm weight support. <i>Journal of NeuroEngineering and Rehabilitation</i> , 2022, 19, 19.	4.6	14
4	Haptic Training: Which Types Facilitate (re)Learning of Which Motor Task and for Whom? Answers by a Review. <i>IEEE Transactions on Haptics</i> , 2021, 14, 722-739.	2.7	32
5	Development of an Active Cable-Driven, Force-Controlled Robotic System for Walking Rehabilitation. <i>Frontiers in Neurobotics</i> , 2021, 15, 651177.	2.8	4
6	Towards Functional Robotic Rehabilitation: Clinical-Driven Development of a Novel Device for Sensorimotor Hand Training. , 2021, , .		0
7	Congruency of Information Rather Than Body Ownership Enhances Motor Performance in Highly Embodied Virtual Reality. <i>Frontiers in Neuroscience</i> , 2021, 15, 678909.	2.8	10
8	Assessing Touch Sensibility with a Robotic System for Sensory Rehabilitation. , 2021, , .		1
9	Tricking the Brain—Using Immersive Virtual Reality: Modifying the Self-Perception Over Embodied Avatar Influences Motor Cortical Excitability and Action Initiation. <i>Frontiers in Human Neuroscience</i> , 2021, 15, 787487.	2.0	9
10	A Novel Clinical-Driven Design for Robotic Hand Rehabilitation: Combining Sensory Training, Effortless Setup, and Large Range of Motion in a Palmar Device. <i>Frontiers in Neurobotics</i> , 2021, 15, 748196.	2.8	11
11	Providing Task Instructions During Motor Training Enhances Performance and Modulates Attentional Brain Networks. <i>Frontiers in Neuroscience</i> , 2021, 15, 755721.	2.8	3
12	Haptic Rendering Modulates Task Performance, Physical Effort and Movement Strategy during Robot-Assisted Training. , 2020, , .		6
13	Promoting Motor Variability During Robotic Assistance Enhances Motor Learning of Dynamic Tasks. <i>Frontiers in Neuroscience</i> , 2020, 14, 600059.	2.8	12
14	Do we need complex rehabilitation robots for training complex tasks?. , 2019, 2019, 1085-1090.		3
15	Virtual Reality Environments and Haptic Strategies to Enhance Implicit Learning and Motivation in Robot-Assisted Training. , 2019, 2019, 760-765.		18
16	Validity of pervasive computing based continuous physical activity assessment in community-dwelling old and oldest-old. <i>Scientific Reports</i> , 2019, 9, 9662.	3.3	25
17	Multi-purpose Robotic Training Strategies for Neurorehabilitation with Model Predictive Controllers. , 2019, 2019, 754-759.		5
18	Reaching in Several Realities: Motor and Cognitive Benefits of Different Visualization Technologies. , 2019, 2019, 1037-1042.		12

#	ARTICLE	IF	CITATIONS
19	Haptic Error Modulation Outperforms Visual Error Amplification When Learning a Modified Gait Pattern. <i>Frontiers in Neuroscience</i> , 2019, 13, 61.	2.8	28
20	Rowing Simulator Modulates Water Density to Foster Motor Learning. <i>Frontiers in Robotics and AI</i> , 2019, 6, 74.	3.2	9
21	Therapist-Guided Tablet-Based Telerehabilitation for Patients With Aphasia: Proof-of-Concept and Usability Study. <i>JMIR Rehabilitation and Assistive Technologies</i> , 2019, 6, e13163.	2.2	26
22	Comparing the Relaxing Effects of Different Virtual Reality Environments in the Intensive Care Unit: Observational Study. <i>JMIR Perioperative Medicine</i> , 2019, 2, e15579.	1.0	22
23	Visual and Haptic Error Modulating Controllers for Robotic Gait Training. , 2018, , .		9
24	Robot-assisted gait training. , 2018, , 227-240.		12
25	Neural circuits activated by error amplification and haptic guidance training techniques during performance of a timing-based motor task by healthy individuals. <i>Experimental Brain Research</i> , 2018, 236, 3085-3099.	1.5	14
26	Experimental Evaluation of a Mixed Controller That Amplifies Spatial Errors and Reduces Timing Errors. <i>Frontiers in Robotics and AI</i> , 2017, 4, .	3.2	13
27	Effect of Error Augmentation on Brain Activation and Motor Learning of a Complex Locomotor Task. <i>Frontiers in Neuroscience</i> , 2017, 11, 526.	2.8	50
28	The effectiveness of robotic training depends on motor task characteristics. <i>Experimental Brain Research</i> , 2017, 235, 3799-3816.	1.5	26
29	Evaluation of a mixed controller that amplifies spatial errors while reducing timing errors. , 2016, 2016, 5136-5139.		3
30	Towards more efficient robotic gait training: A novel controller to modulate movement errors. , 2016, , .		15
31	On the Modulation of Brain Activation During Simulated Weight Bearing in Supine Gait-Like Stepping. <i>Brain Topography</i> , 2016, 29, 193-205.	1.8	13
32	Test-retest reliability of fMRI experiments during robot-assisted active and passive stepping. <i>Journal of NeuroEngineering and Rehabilitation</i> , 2015, 12, 102.	4.6	17
33	Detecting motion intention in stroke survivors using autonomic nervous system responses. , 2015, , .		1
34	The role of skill level and motor task characteristics on the effectiveness of robotic training: first results. , 2015, , .		25
35	The Effect of Haptic Guidance on Learning a Hybrid Rhythmic-Discrete Motor Task. <i>IEEE Transactions on Haptics</i> , 2015, 8, 222-234.	2.7	29
36	Sonification and haptic feedback in addition to visual feedback enhances complex motor task learning. <i>Experimental Brain Research</i> , 2015, 233, 909-925.	1.5	129

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37	Brain activation associated with active and passive lower limb stepping. <i>Frontiers in Human Neuroscience</i> , 2014, 8, 828.	2.0	56
38	Physiological noise cancellation in fNIRS using an adaptive filter based on mutual information. , 2014, , .		3
39	Optimizing learning of a locomotor task: Amplifying errors as needed. , 2014, 2014, 5304-7.		30
40	The Learning Benefits of Haptic Guidance Are Age-Dependent. <i>Biosystems and Biorobotics</i> , 2014, , 65-73.	0.3	2
41	Learning a locomotor task: with or without errors?. <i>Journal of NeuroEngineering and Rehabilitation</i> , 2014, 11, 25.	4.6	48
42	Detection of motor execution using a hybrid fNIRS-biosignal BCI: a feasibility study. <i>Journal of NeuroEngineering and Rehabilitation</i> , 2013, 10, 4.	4.6	65
43	Non-linear adaptive controllers for an over-actuated pneumatic MR-compatible stepper. <i>Medical and Biological Engineering and Computing</i> , 2013, 51, 799-809.	2.8	12
44	Whatâ€™s Your Next Move? Detecting Movement Intention for Stroke Rehabilitation. <i>Springer Briefs in Electrical and Computer Engineering</i> , 2013, , 23-37.	0.5	1
45	The effect of haptic guidance and visual feedback on learning a complex tennis task. <i>Experimental Brain Research</i> , 2013, 231, 277-291.	1.5	76
46	Motor execution detection based on autonomic nervous system responses. <i>Physiological Measurement</i> , 2013, 34, 35-51.	2.1	16
47	A reconfigurable, tendon-based haptic interface for research into human-environment interactions. <i>Robotica</i> , 2013, 31, 441-453.	1.9	9
48	Balancing objects on the feet — An fMRI experiment using the MR-compatible stepper MARCOS. , 2012, , .		0
49	Synthesis and control of an assistive robotic tennis trainer. , 2012, , .		14
50	An fMRI pilot study to evaluate brain activation associated with locomotion adaptation. , 2011, 2011, 5975371.		14
51	Assistance or challenge? Filling a gap in user-cooperative control. , 2011, , .		1
52	Towards a BCI for sensorimotor training: Initial results from simultaneous fNIRS and biosignal recordings. , 2011, 2011, 6339-43.		10
53	Assistance or challenge? Filling a gap in user-cooperative control. , 2011, , .		22
54	Comparison of error-amplification and haptic-guidance training techniques for learning of a timing-based motor task by healthy individuals. <i>Experimental Brain Research</i> , 2010, 201, 119-131.	1.5	122

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55	The effect of haptic guidance, aging, and initial skill level on motor learning of a steering task. <i>Experimental Brain Research</i> , 2010, 201, 209-220.	1.5	118
56	A robotic wheelchair trainer: design overview and a feasibility study. <i>Journal of NeuroEngineering and Rehabilitation</i> , 2010, 7, 40.	4.6	60
57	BDNF Val66Met Polymorphism Influences Motor System Function in the Human Brain. <i>Cerebral Cortex</i> , 2010, 20, 1254-1262.	2.9	191
58	Review of control strategies for robotic movement training after neurologic injury. <i>Journal of NeuroEngineering and Rehabilitation</i> , 2009, 6, 20.	4.6	887
59	Effect of robotic guidance on motor learning of a timing task. , 2008, , .		26
60	Haptic Guidance Can Enhance Motor Learning of a Steering Task. <i>Journal of Motor Behavior</i> , 2008, 40, 545-557.	0.9	133
61	Some Key Problems for Robot-Assisted Movement Therapy Research: A Perspective from the University of California at Irvine. , 2007, , .		22