

Kangwagye Samuel

List of Publications by Year in descending order

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Version: 2024-02-01

6
papers

26
citations

2258059

3
h-index

2272923

4
g-index

6
all docs

6
docs citations

6
times ranked

23
citing authors

#	ARTICLE	IF	CITATIONS
1	Robust UKF-IMM Filter for Tracking an Off-road Ground Target. International Journal of Control, Automation and Systems, 2019, 17, 1149-1157.	2.7	11
2	Improved IMM Filter for Tracking a Highly Maneuvering Target with Mixed System Noises. International Journal of Control, Automation and Systems, 2018, 16, 2763-2771.	2.7	8
3	An Autonomous Human Following Caddie Robot with High-Level Driving Functions. Electronics (Switzerland), 2020, 9, 1516.	3.1	4
4	Novel Force Observer for Precise Force Estimation Using Force Sensor. , 2020, , .		2
5	Twofold Observer-Based Precise Force Control. IEEE Transactions on Control Systems Technology, 2022, 30, 2251-2260.	5.2	1
6	A Reduced-Order Multisensor-Based Force Observer. IEEE Transactions on Industrial Electronics, 2022, 69, 4946-4956.	7.9	0