

# Huang Huang

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/6121509/publications.pdf>

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3311381

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#	ARTICLE	IF	CITATIONS
1	Complex Stiffness Model of Physical Human-Robot Interaction: Implications for Control of Performance Augmentation Exoskeletons. , 2019, , .		8
2	A Complex Stiffness Human Impedance Model With Customizable Exoskeleton Control. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2020, 28, 2468-2477.	4.9	6
3	Adaptive Compliance Shaping with Human Impedance Estimation. , 2020, , .		5