

# Dailiang

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/5940275/publications.pdf>

Version: 2024-02-01

5  
papers

293  
citations

1684129

5  
h-index

2053674

5  
g-index

5  
all docs

5  
docs citations

5  
times ranked

336  
citing authors

#	ARTICLE	IF	CITATIONS
1	Lyapunov vector-based formation tracking control for unmanned aerial vehicles with obstacle/collision avoidance. Transactions of the Institute of Measurement and Control, 2020, 42, 942-950.	1.7	13
2	Adaptive prescribed performance terminal sliding mode attitude control for quadrotor under input saturation. IET Control Theory and Applications, 2020, 14, 2473-2480.	2.1	22
3	Disturbance Rejection MPC for Tracking of Wheeled Mobile Robot. IEEE/ASME Transactions on Mechatronics, 2017, 22, 2576-2587.	5.8	96
4	Active disturbance rejection and predictive control strategy for a quadrotor helicopter. IET Control Theory and Applications, 2016, 10, 2213-2222.	2.1	101
5	Obstacle avoidance and active disturbance rejection control for a quadrotor. Neurocomputing, 2016, 190, 60-69.	5.9	61